# ERROR ANALYSIS OF THE GENERALIZED LOW-RANK MATRIX APPROXIMATION* 

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#### Abstract

In this paper, we propose an error analysis of the generalized low-rank approximation, which is a generalization of the classical approximation of a matrix $A \in \mathbb{R}^{m \times n}$ by a matrix of a rank at most $r$, where $r \leq \min \{m, n\}$.


Key words. Generalized low-rank approximation, Frobenius norm, SVD, Pseudoinverse, Error analysis.

AMS subject classifications. 15A18, 15A29.

1. Introduction. Throughout this paper, we adopt the following notation: $\mathbb{R}_{r}^{m \times n}$ denotes the set of all real $m \times n$ matrices of rank at most $r$, where $r \leq \min \{m, n\}$, i.e., $A \in \mathbb{R}_{r}^{m \times n}$ if and only if $\operatorname{rank}(A) \leq r$. $I_{m} \in \mathbb{R}^{m \times m}$ and $\boldsymbol{O}_{m \times n} \in \mathbb{R}^{m \times n}$ are the identity matrix of order $m$ and the null $m \times n$ matrix, respectively. $M^{\dagger}, \operatorname{tr}\{M\},\|M\|$ and $\mathcal{N}(M)$ denote the pseudoinvserse, the trace, the Frobenius norm and the null space of $M$, respectively. Furthermore, $N^{1 / 2}$ is the square root of $N \in \mathbb{R}^{m \times m}$, i.e., $N=N^{1 / 2} N^{1 / 2}$.

Let $D=U_{D} \Sigma_{D} V_{D}^{T}$ be the singular value decomposition (SVD) of $D \in \mathbb{R}^{m \times n}$, where $U_{D} \in \mathbb{R}^{m \times m}$ and $V_{D} \in \mathbb{R}^{n \times n}$ are two orthogonal matrices, and $\Sigma_{D}=\operatorname{diag}\left(\sigma_{1}(D), \ldots, \sigma_{\min (m, n)}(D)\right) \in \mathbb{R}^{m \times n}$ is a generalized diagonal matrix with singular values $\sigma_{1}(D) \geq \sigma_{2}(D) \geq \ldots \geq \sigma_{\min (m, n)}(D) \geq 0$ on the main diagonal. The $r$-truncated SVD is defined by

$$
\lfloor D\rfloor_{r}=\sum_{i=1}^{r} \sigma_{i}(D) u_{i} v_{i}^{T}=U_{D, r} \Sigma_{D, r} V_{D, r}^{T} \in \mathbb{R}^{m \times n},
$$

where $U_{D, r} \in \mathbb{R}^{m \times r}$ and $V_{D, r} \in \mathbb{R}^{n \times r}$ are formed with the first $r$ columns of $U_{D}$ and $V_{D}$, respectively, and $\Sigma_{D, r}=\operatorname{diag}\left(\sigma_{1}(D), \ldots, \sigma_{r}(D)\right) \in \mathbb{R}^{r \times r}$. If $k=\operatorname{rank}(D)$, then $P_{D, L} \in \mathbb{R}^{m \times m}$ and $P_{D, R} \in \mathbb{R}^{n \times n}$ are the orthogonal projections of $D$ on the range of $D$ and $D^{T}$, respectively, where $P_{D, L}=D D^{\dagger}=U_{D, k} U_{D, k}^{T}$ and $P_{D, R}=D^{\dagger} D=V_{D, k} V_{D, k}^{T}$.

A generalization of the low-rank approximation was proposed in $[2,3,4]$. Given matrices $A \in \mathbb{R}^{p \times q}$, $B \in \mathbb{R}^{p \times m}$ and $C \in \mathbb{R}^{n \times q}$, and rank $r \leq \min \{m, n\}$, the generalized low-rank approximation finds a matrix $\widehat{X}_{r} \in \mathbb{R}_{r}^{m \times n}$ such that

$$
\begin{equation*}
\left\|A-B \widehat{X}_{r} C\right\|^{2}=\min _{X \in \mathbb{R}_{r}^{m \times n}}\|A-B X C\|^{2} . \tag{1.1}
\end{equation*}
$$

Note that if $B$ and $C$ are identity matrices, the problem (1.1) is the well-known low-rank approximation problem proposed by Eckart and Young [1]. The problem in (1.1) was studied in [2, 3, 4] by Sonderman, Friedland and Torokthi, respectively. The following theorem presents the solution of the generalized low-rank approximation given in [3].

[^0]Theorem 1.1. Let $A \in \mathbb{R}^{p \times q}, B \in \mathbb{R}^{p \times m}$ and $C \in \mathbb{R}^{n \times q}$, and let $M=U_{M} \Sigma_{M} V_{M}^{T}$ be the $S V D$ of $M=P_{B, L} A P_{C, R}=B B^{\dagger} A C^{\dagger} C$. Then matrix

$$
\begin{equation*}
\widehat{X}_{r}=B^{\dagger}\lfloor M\rfloor_{r} C^{\dagger}=B^{\dagger} U_{M, r} \Sigma_{M, r} V_{M, r}^{T} C^{\dagger} \tag{1.2}
\end{equation*}
$$

minimizes the problem (1.1). This solution is unique if and only if either

$$
r \geq \operatorname{rank}(M)
$$

or

$$
1 \leq r<\operatorname{rank}(M) \quad \text { and } \quad \sigma_{r}(M) \geq \sigma_{r+1}(M)
$$

In this paper, we present an error analysis for the solution of the problem (1.1). The main result of this paper is presented below, in Theorem 3.1. In the related work, for the same problem, in [5, Theorem 3.2] Wang presented an error analysis for the specific case of $\operatorname{rank}\left(\widehat{X}_{r}\right)=r$. In this paper, we extend the analysis to the case $\operatorname{rank}\left(\widehat{X}_{r}\right) \leq r$. The formula for the error in [5, Theorem 3.2] is different from that in Theorem 3.1.
2. Preliminaries. In this section, we present some preliminary results that will be used in the next section to study the error associated with the solution of the problem (1.1).

Lemma 2.1 (Theorem 2.8 in [6]). If $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{n \times m}$, then $A B$ and $B A$ have the same nonzero eigenvalues, counting multiplicity.

Lemma 2.2 (Propositions 3.1 and 3.2 in [7]). $A^{\dagger}=A^{T}\left(A^{\dagger}\right)^{T} A^{\dagger}=A^{\dagger}\left(A^{\dagger}\right)^{T} A^{T}=\left(A^{T} A\right)^{\dagger} A^{T}$, for all $A \in \mathbb{R}^{m \times n}$.

Lemma 2.3 (Lemma 2.4.1 in [8]). Let $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{p \times m}$. Then $\mathcal{N}(A) \subseteq \mathcal{N}(B A)$.
Lemma 2.4 (Lemma 23 in [9] - Fact 2 in [10]). For any $M \in \mathbb{R}^{m \times n}, N \in \mathbb{R}^{p \times n}$ and $S \in \mathbb{R}^{m \times s}$, the following statements hold.
(a) If $\mathcal{N}(M) \subseteq \mathcal{N}(N)$, then $N M^{\dagger} M=N$.
(b) If $\mathcal{N}\left(M^{T}\right) \subseteq \mathcal{N}\left(S^{T}\right)$, then $M M^{\dagger} S=S$.

Lemma 2.5. Let $M \in \mathbb{R}^{m \times n}$ and $r \leq \min \{m, n\}$. Then $\mathcal{N}(M) \subseteq \mathcal{N}\left(\lfloor M\rfloor_{r}\right)$.
Proof. Without loss of generality, we assume $m \leq n$. Let $M=U_{M} \Sigma_{M} V_{M}^{T}$ be the SVD of $M$. If $x \in \mathcal{N}(M)$, then $M x=\boldsymbol{O}_{n \times 1}$, and therefore, $\Sigma_{M} V_{M}^{T} x=\boldsymbol{O}_{n \times 1}$, because $U_{M}$ is an orthogonal matrix. If $\bar{\Sigma}_{M, r}=\operatorname{diag}\left(\sigma_{1}(M), \ldots, \sigma_{r}(M), 0, \ldots, 0\right) \in \mathbb{R}^{m \times n}$, then

$$
\begin{aligned}
\Sigma_{M} V_{M}^{T} x=\boldsymbol{O}_{n \times 1} & \Rightarrow\left[\begin{array}{cc}
I_{r} & \boldsymbol{o}_{k \times m-r} \\
\boldsymbol{o}_{m-r \times r} & \boldsymbol{O}_{m-r \times m-r}
\end{array}\right] \Sigma_{M} V_{M}^{T} x=\boldsymbol{O}_{n \times 1} \\
& \Rightarrow \Sigma_{M, r} V_{M}^{T} x=\boldsymbol{O}_{n \times 1} \\
& \Rightarrow U_{M} \bar{\Sigma}_{M, r} V_{M}^{T} x=\boldsymbol{O}_{n \times 1} .
\end{aligned}
$$

Note that

$$
U_{M} \bar{\Sigma}_{M, r} V_{M}^{T}=\sum_{i=1}^{\min \{m, n\}} \sigma_{i}(M) u_{i} v_{i}^{T}=\sum_{i=1}^{r} \sigma_{i}(M) u_{i} v_{i}^{T}=\lfloor M\rfloor_{r}
$$

Finally, $\lfloor M\rfloor_{r} x=\boldsymbol{0}_{n \times 1}$. Thus, $x \in \mathcal{N}\left(\lfloor M\rfloor_{r}\right)$.
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LEMMA 2.6. If $M \in \mathbb{R}^{m \times n}, S \in \mathbb{R}^{n \times s}$ and $R \in \mathbb{R}^{s \times m}$, then the following statements hold.
(a) $\lfloor R M\rfloor_{r} M^{\dagger} M=\lfloor R M\rfloor_{r}$.
(b) $S S^{\dagger}\lfloor S R\rfloor_{r}=\lfloor S R\rfloor_{r}$.

Proof. We consider (a). It follows from Lemma 2.3 that $\mathcal{N}(M) \subseteq \mathcal{N}(R M)$. By Lemma 2.5, we obtain $\mathcal{N}(R M) \subseteq \mathcal{N}\left(\lfloor R M\rfloor_{r}\right)$, and therefore, $\mathcal{N}(M) \subseteq \mathcal{N}\left(\lfloor R M\rfloor_{r}\right)$. As a result, (a) follows from Lemma 2.4. The proof of $(\mathrm{b})$ is similar to the proof of (a).

## 3. Main Result.

ThEOREM 3.1. Let $A \in \mathbb{R}^{p \times q}, B \in \mathbb{R}^{p \times m}, C \in \mathbb{R}^{n \times q}$ and $r \leq \min \{m, n\}$. The error of the solution of the problem (1.1) is given by

$$
\begin{equation*}
\min _{X \in \mathbb{R}_{r}^{m \times n}}\|A-B X C\|^{2}=\|A\|^{2}-\sum_{i=1}^{r} \lambda_{i}(T), \tag{3.3}
\end{equation*}
$$

where $T=B^{\dagger} A C^{\dagger} C A^{T} B \in \mathbb{R}^{m \times m}$ and $\lambda_{i}(T)$ is the $i-$ th eigenvalue of $T$ with $\lambda_{1}(T) \geq \lambda_{2}(T) \geq \ldots \geq \lambda_{m}(T)$.
Proof. It follows from the identity $\|D\|^{2}=\operatorname{tr}\left\{D D^{T}\right\}$ and the linearity of the trace operator that

$$
\begin{equation*}
\|A-B X C\|^{2}=\|A\|^{2}-\|M\|^{2}+\left\|M-\left(B^{T} B\right)^{1 / 2} X\left(C C^{T}\right)^{1 / 2}\right\|^{2} \tag{3.4}
\end{equation*}
$$

where $M=\left(B^{T} B\right)^{1 / 2 \dagger} B^{T} A C^{T}\left(C C^{T}\right)^{1 / 2 \dagger}$. Note that $\left\|M-\left(B^{T} B\right)^{1 / 2} X\left(C C^{T}\right)^{1 / 2}\right\|^{2}$ is the only term in (3.4) that depends on $X$. Therefore, problem (1.1) is equivalent to

$$
\begin{equation*}
\min _{X \in \mathbb{R}_{r}^{m \times n}}\left\|M-\left(B^{T} B\right)^{1 / 2} X\left(C C^{T}\right)^{1 / 2}\right\|^{2} \tag{3.5}
\end{equation*}
$$

Based on Theorem 1.1, the solution of the problem (3.5) is given by

$$
\begin{equation*}
\widehat{X}_{r}=\left(B^{T} B\right)^{1 / 2 \dagger}\left\lfloor P_{\left(B^{T} B\right)^{1 / 2}, L} M P_{\left(C C^{T}\right)^{1 / 2}, R}\right\rfloor_{r}\left(C C^{T}\right)^{1 / 2 \dagger} \tag{3.6}
\end{equation*}
$$

Note that $\left(B^{T} B\right)^{1 / 2 \dagger}$ and $\left(C C^{T}\right)^{1 / 2 \dagger}$ are symmetric matrices. Therefore, it follows from Lemma 2.2 that

$$
\begin{equation*}
P_{\left(B^{T} B\right)^{1 / 2}, L}\left(B^{T} B\right)^{1 / 2 \dagger}=\left(B^{T} B\right)^{1 / 2}\left(B^{T} B\right)^{1 / 2 \dagger}\left(B^{T} B\right)^{1 / 2 \dagger}=\left(B^{T} B\right)^{1 / 2 \dagger} \tag{3.7}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(C C^{T}\right)^{1 / 2 \dagger} P_{\left(C C^{T}\right)^{1 / 2}, R}=\left(C C^{T}\right)^{1 / 2 \dagger}\left(C C^{T}\right)^{1 / 2 \dagger}\left(C C^{T}\right)^{1 / 2}=\left(C C^{T}\right)^{1 / 2 \dagger} \tag{3.8}
\end{equation*}
$$

Further, (3.7) and (3.8) imply

$$
\begin{align*}
\left\lfloor P_{\left(B^{T} B\right)^{1 / 2}, L} M P_{\left(C C^{T}\right)^{1 / 2}, R}\right\rfloor_{r} & =\left\lfloor P_{\left(B^{T} B\right)^{1 / 2}, L}\left(B^{T} B\right)^{1 / 2 \dagger} B^{T} A C^{T}\left(C C^{T}\right)^{1 / 2 \dagger} P_{\left(C C^{T}\right)^{1 / 2}, R}\right\rfloor_{r} \\
& =\left\lfloor\left(B^{T} B\right)^{1 / 2 \dagger} B^{T} A C^{T}\left(C C^{T}\right)^{1 / 2 \dagger}\right\rfloor_{r} \\
& =\lfloor M\rfloor_{r} \tag{3.9}
\end{align*}
$$

It follows from (3.6) and (3.9) that $\widehat{X}_{r}=\left(B^{T} B\right)^{1 / 2 \dagger}\lfloor M\rfloor_{r}\left(C C^{T}\right)^{1 / 2 \dagger}$. On the basis of Lemma 2.6, we obtain that

$$
\begin{equation*}
\left(B^{T} B\right)^{1 / 2} \widehat{X}_{r}\left(C C^{T}\right)^{1 / 2}=\left(B^{T} B\right)^{1 / 2}\left(B^{T} B\right)^{1 / 2 \dagger}\lfloor M\rfloor_{r}\left(C C^{T}\right)^{1 / 2 \dagger}\left(C C^{T}\right)^{1 / 2}=\lfloor M\rfloor_{r} \tag{3.10}
\end{equation*}
$$

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By equations (3.4) and (3.10) and the facts that $\|M\|^{2}=\operatorname{tr}\left\{M M^{T}\right\}=\sum_{i=1}^{m} \lambda_{i}\left(M M^{T}\right)$ and $\|\cdot\|$ is unitary invariant [6], we obtain the following identity

$$
\begin{align*}
\min _{X \in \mathbb{R}_{r}^{p x q}}\|A-B X C\|^{2} & =\|A\|^{2}-\|M\|^{2}+\left\|M-\left(B^{T} B\right)^{1 / 2} \widehat{X}_{r}\left(C C^{T}\right)^{1 / 2}\right\|^{2} \\
& =\|A\|^{2}-\|M\|^{2}+\left\|M-\lfloor M\rfloor_{r}\right\|^{2} \\
& =\|A\|^{2}-\sum_{i=1}^{m} \lambda_{i}\left(M M^{T}\right)+\sum_{i=r+1}^{m} \lambda_{i}\left(M M^{T}\right) \\
& =\|A\|^{2}-\sum_{i=1}^{r} \lambda_{i}\left(M M^{T}\right) . \tag{3.11}
\end{align*}
$$

Note that $M M^{T}=\left(B^{T} B\right)^{1 / 2 \dagger} B^{T} A C^{\dagger} C A^{T} B\left(B^{T} B\right)^{1 / 2 \dagger}$. From Lemmas 2.1 and 2.2, we obtain that

$$
\begin{equation*}
\lambda_{i}\left(M M^{T}\right)=\lambda_{i}\left(B^{\dagger} A C^{\dagger} C A^{T} B\right) \tag{3.12}
\end{equation*}
$$

for all $i=1, \ldots, m$. Finally, (3.3) follows from (3.11) and (3.12).
4. Advantage and Numerical Example. The error formula given by (3.3) is useful for choosing an optimal value for the rank $r$, before computing the matrix $\widehat{X}_{r}$ in (1.2). For example, we consider matrices $A \in \mathbb{R}^{20 \times 35}, B \in \mathbb{R}^{20 \times 30}$ and $C \in \mathbb{R}^{40 \times 35}$ generated from a uniform distribution with zero-mean and standard deviation 1. Figure 1 shows the relationship between the error associated with the solution of problem (1.1) and the rank $r$. It follows from Figure 1 that the associated error is 0 when $r \geq 20$. Therefore, the smallest value of $r$ that implies the minimal error of the solution of problem (1.1) is given by $r=20$. Note that it was not necessary to compute each optimal matrix $\widehat{X}_{r}$, for $r=1, \ldots, 30$, to obtain the associated error. In this example, we only compute the eigenvalues of $T=B^{\dagger} A C^{\dagger} C A^{T} B \in \mathbb{R}^{30 \times 30}$ and use the formula (3.3). Furthermore, in this numerical simulation, we obtain that $\operatorname{rank}(T)=20$ and $\sigma_{i}^{2}(A)=\lambda_{i}(T)$, for all $i=1, \ldots, 20$. Thus,

$$
\min _{X \in \mathbb{R}_{r}^{30 \times 40}}\|A-B X C\|^{2}=\|A\|^{2}-\sum_{i=1}^{r} \lambda_{i}(T)=0
$$

for all $r \geq 20$.


Figure 1. Diagram of the error associated with the solution of problem (1.1) versus rank r.

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