STRUCTURE-PRESERVING DIAGONALIZATION OF MATRICES IN INDEFINITE INNER PRODUCT SPACES*

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Abstract. In this work, some results on the structure-preserving diagonalization of selfadjoint and skewadjoint matrices in indefinite inner product spaces are presented. In particular, necessary and sufficient conditions on the symplectic diagonalizability of (skew)-Hamiltonian matrices and the perplectic diagonalizability of per(skew)-Hermitian matrices are provided. Assuming the structured matrix at hand is additionally normal, it is shown that any symplectic or perplectic diagonalization can always be constructed to be unitary. As a consequence of this fact, the existence of a unitary, structure-preserving diagonalization is equivalent to the existence of a specially structured additive decomposition of such matrices. The implications of this decomposition are illustrated by several examples.

Key words. Sesquilinear forms, (Skew)-Hamiltonian matrices, Per(skew)-Hermitian matrices, Symplectic matrices, Perplectic matrices, Unitary matrices, Diagonalization, Lagrangian subspaces.

AMS subject classifications. 15B57, 15A23, 15A63, 11E39.

1. Introduction. Structured matrices are omnipresent in many areas of mathematics. For instance, structured eigenvalue problems arise in engineering, physics and statistics [17, 22] in the form of optimal control problems, the analysis of mechanical and electrical vibrations [14], the computational analysis and theory of matrix function [10, Chapter 14] or of matrix equations [13]. Thereby, special structures arising from the consideration of selfadjoint and skewadjoint matrices with respect to certain inner products play a crucial role. Often, these inner products are indefinite, so that the underlying bilinear or sesquilinear form does not define a scalar product. Hence, results from Hilbert-space-theory are not available in this case and an independent mathematical analysis is required. Over the last decades, a great amount of research has been done on these structured matrices, especially with regard to structure-preserving decompositions and algorithms (see, e.g. [19, 5, 18] or [14, Section 8] and the references therein). In this work, some results in this direction are presented.

Considering the (definite) standard Euclidean inner product $\langle x, y \rangle = x^H y, x, y \in \mathbb{C}^m$, on $\mathbb{C}^m \times \mathbb{C}^m$, it is well-known that selfadjoint and skewadjoint matrices (i.e., Hermitian and skew-Hermitian matrices) have very special properties. For example, (skew)-Hermitian matrices are always diagonalizable by a unitary matrix. The unitary matrices constitute the automorphism group of the scalar product $\langle \cdot, \cdot \rangle$ which means that $\langle Gx, Gy \rangle = \langle x, y \rangle$ always holds for any unitary matrix G and all vectors $x, y \in \mathbb{C}^m$. The automorphism group is sometimes called the *Lie-group* with respect to $\langle \cdot, \cdot \rangle$ whereas the selfadjoint and skewadjoint matrices are referred to as the Jordan and Lie algebras [16]. The Euclidean scalar product is a special case of a sesquilinear form $[x, y] = x^H By$ on $\mathbb{C}^m \times \mathbb{C}^m$ with $B = I_m$ being the $m \times m$ identity matrix. Often, sesquilinear forms $[x, y] = x^H By$ appear in mathematics where $B \neq I_m$. In particular, cases that have been intensively studied are those where B is some (positive/negative definite or indefinite) Hermitian matrix [8] or a skew-Hermitian

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matrix [4]. The Lie-group, the Lie algebra and the Jordan algebra are defined analogously to the Euclidean scalar product for such forms as the group of automorphisms, selfadjoint and skewadjoint matrices with respect to $[x, y] = x^H By$.

In this work, selfadjoint and skewadjoint matrices with respect to indefinite Hermitian or skew-Hermitian sesquilinear forms are considered from the viewpoint of diagonalizability. In particular, since Hermitian and skew-Hermitian matrices are always diagonalizable by a unitary matrix (i.e., an automorphism with respect to $\langle \cdot, \cdot \rangle$), we will consider the question under what conditions a similar statement holds for the automorphic diagonalization of selfadjoint and skewadjoint matrices with respect to other (indefinite) sesquilinear forms. For two particular sesquilinear forms (the symplectic and the perplectic sesquilinear form) this question will be fully analyzed and answered in Sections 3 and 4. For the symplectic bilinear form, this question was already addressed in [5]. In Section 5, we consider these results in the context of normal matrices for which there always exists a unitary diagonalization. In particular, the results presented in this section apply to selfadjoint and skewadjoint matrices for which a unitary diagonalization exists. We will show that this subclass of matrices has very nice properties with respect to unitary and automorphic diagonalization and how both types of diagonalizations interact. In Section 2, the notation used throughout this work is introduced, whereas in Section 6, some concluding remarks are given.

2. Notation and definitions. For any $m \in \mathbb{N}$ and $\mathbb{K} = \mathbb{R}, \mathbb{C}$, we denote by \mathbb{K}^m the *m*-dimensional vector space over \mathbb{K} and by $M_{m \times m}(\mathbb{K})$ the vector space of all $m \times m$ matrices over \mathbb{K} . The vector subspace \mathcal{X} of \mathbb{K}^m which is obtained from all possible linear combinations of some vectors $x_1, \ldots, x_k \in \mathbb{K}^m$ is called the span of x_1, \ldots, x_k and is denoted by $\operatorname{span}(x_1, \ldots, x_k)$. A basis of some subspace $\mathcal{X} \subseteq \mathbb{K}^m$ is a linearly independent set of vectors $x_1, \ldots, x_k \in \mathcal{X}$ such that $\mathcal{X} = \operatorname{span}(x_1, \ldots, x_k)$. In this case we say that the dimension of \mathcal{X} equals k, that is, $\dim(\mathcal{X}) = k$. The symbol $\mathbb{K}^m \times \mathbb{K}^m$ is used to denote the direct product of \mathbb{K}^m with itself, i.e., $\mathbb{K}^m \times \mathbb{K}^m = \{(x, y) \mid x, y \in \mathbb{K}^m\}$. For any matrix $A \in M_{m \times m}(\mathbb{K})$, the notions $\operatorname{im}(A)$ and $\operatorname{null}(A)$ refer to the image and the nullspace (kernel) of A, i.e., $\operatorname{im}(A) = \{Ax \mid x \in \mathbb{K}^m\}$ and $\operatorname{null}(A) = \{x \in \mathbb{K}^m \mid Ax = 0\}$. The rank of $A \in M_{m \times m}(\mathbb{K})$ is defined as the dimension of its image. For any matrix $A \in M_{m \times m}(\mathbb{K})$ the superscripts T and H denote the transpose A^T of A and the Hermitian transpose $A^{H} = \overline{A}^{T}$. The overbar denotes the conjugation of a complex number and applies entrywise to matrices. The $m \times m$ identity matrix is throughout denoted by I_m whereas the $m \times m$ zero matrix, the zero vector in \mathbb{K}^m or the number zero are simply denoted by 0 (to specify dimensions $0_{m \times m}$ is used in some places to refer to the $m \times m$ zero matrix). A Hermitian matrix $A \in M_{m \times m}(\mathbb{K})$ satisfies $A^H = A$ and a skew-Hermitian matrix $A^H = -A$. Moreover, a matrix $A \in M_{m \times m}(\mathbb{K})$ is called unitary if $A^H A = AA^H = I_m$ holds and normal in case $A^H A = A A^H$ holds. For two matrices $A, B \in M_{m \times m}(\mathbb{K})$ the notation $A \oplus B$ is used to denote their direct sum, i.e., the matrix $C \in M_{2m \times 2m}(\mathbb{K})$ given by

$$C = \begin{bmatrix} A & 0_{m \times m} \\ 0_{m \times m} & B \end{bmatrix}.$$

For a given matrix $A \in M_{m \times m}(\mathbb{K})$ any scalar $\lambda \in \mathbb{C}$ which satisfies $Ax = \lambda x$ for some nonzero vector $x \in \mathbb{C}^m$ is called an eigenvalue of A. The set of all eigenvalues of A is denoted by $\sigma(A)$ and equals the zero set of the degree-m polynomial det $(A - zI_m)$. The algebraic multiplicity of λ as an eigenvalue of A equals the multiplicity of λ as a zero of det $(A - zI_m)$. Whenever $\lambda \in \mathbb{C}$ is some eigenvalue of A any vector $x \in \mathbb{C}^m$ satisfying $Ax = \lambda x$ is called an eigenvector of A (for λ). The set of all eigenvectors of A for $\lambda \in \sigma(A)$ is a vector subspace of \mathbb{C}^m and is called the corresponding eigenspace (of A for λ). Its dimension is referred to as the geometric multiplicity of λ . The matrix A is called diagonalizable if there exist m linearly independent

eigenvectors of A. These vectors consequently form a basis of \mathbb{C}^m . A matrix $A \in M_{m \times m}(\mathbb{K})$ is diagonalizable if and only if the geometric and algebraic multiplicities of all eigenvalues of A coincide.

3. Sesquilinear forms. In this section, we introduce the notion of a sesquilinear form on $\mathbb{C}^m \times \mathbb{C}^m$ and some related basic concepts. Notice that Definition 3.1 slightly deviates from the definition of a sesquilinear form given in [12, Section 5.1].

DEFINITION 3.1. A sesquilinear form $[\cdot, \cdot]$ on $\mathbb{C}^m \times \mathbb{C}^m$ is a mapping $[\cdot, \cdot] : \mathbb{C}^m \times \mathbb{C}^m \to \mathbb{C}$ so that for all $u, v, w \in \mathbb{C}^m$ and all $\alpha, \beta \in \mathbb{C}$ the following relations (i) and (ii) hold:

(i) $[\alpha u + \beta v, w] = \overline{\alpha}[u, w] + \overline{\beta}[v, w]$ (ii) $[u, \alpha v + \beta w] = \alpha[u, v] + \beta[u, w].$

If $[\cdot, \cdot]$ is some sesquilinear form and $x := \alpha e_j, y := \beta e_k \in \mathbb{C}^m$ with $\alpha, \beta \in \mathbb{C}$ are two vectors that are multiples of the *j*th and *k*th unit vectors e_j and e_k , then $[x, y] = \overline{\alpha}\beta[e_j, e_k]$. Thus, any sesquilinear form is uniquely determined by the images of the standard unit vectors $[e_j, e_k], j, k = 1, \ldots, m$. In particular, $[\cdot, \cdot]$ on $\mathbb{C}^m \times \mathbb{C}^m$ can be expressed as

$$[x,y] = x^H B y$$

for the particular matrix $B = [b_{jk}]_{jk} \in M_{m \times m}(\mathbb{C})$ with $b_{jk} = [e_j, e_k]$, $j, k = 1, \ldots, m$. A form $[\cdot, \cdot]$ as in (3.1) is called Hermitian if [x, y] = [y, x] holds for all $x, y \in \mathbb{C}^m$. It is easy to see that $[\cdot, \cdot]$ is Hermitian if and only if $B \in M_{m \times m}(\mathbb{C})$ is Hermitian, i.e., $B = B^H$ [8, Section 2.1]. The form $[\cdot, \cdot]$ is called skew-Hermitian if $[x, y] = -\overline{[y, x]}$ holds for all $x, y \in \mathbb{C}^m$. This is the case if and only if $B = -B^H$.

The following Definition 3.2 introduces two classes of subspaces $S \subseteq \mathbb{C}^m$ related in a particular fashion to a sesquilinear form $[\cdot, \cdot]$ (see, e.g., [8, Section 2.3]).

DEFINITION 3.2. Let $[x, y] = x^H B y$ be some sesquilinear form on $\mathbb{C}^m \times \mathbb{C}^m$.

- 1. A subspace $S \subseteq \mathbb{C}^m$ of dimension dim $(S) = k \ge 1$ is called neutral (with respect to $[\cdot, \cdot]$) if rank $(V^H B V) = 0$ for any basis v_1, \ldots, v_k of S and $V = [v_1 \cdots v_k]$.
- 2. A subspace $S \subseteq \mathbb{C}^m$ of dimension dim $(S) = k \ge 1$ is called nondegenerate (with respect to $[\cdot, \cdot]$) if $V^H B V$ is nonsingular, i.e., rank $(V^H B V) = k$, for any basis v_1, \ldots, v_k of S and $V = [v_1 \cdots v_k]$. Otherwise, S is called degenerate.

In case m = 2n is even, any neutral subspace $S \subseteq \mathbb{C}^m$ with dim(S) = n is called Lagrangian (subspace) (see, e.g., [6, Definition 1.2]). Some analysis on this kind of subspaces is presented in Section 5.1. A sesquilinear form as in (3.1) is called *nondegenerate*, if $S = \mathbb{C}^m$ is nondegenerate with respect to $[\cdot, \cdot]$. In the sequel, nondegenerate sesquilinear forms are called *indefinite inner products*. Note that the sesquilinear form in (3.1) is nondegenerate, i.e., an indefinite inner product, if and only if $B \in M_{m \times m}(\mathbb{C})$ is nonsingular [15, Section 2.1].

PROPOSITION 3.3. For any indefinite inner product $[x, y] = x^H By$ on $\mathbb{C}^m \times \mathbb{C}^m$ and any $A \in M_{m \times m}(\mathbb{C})$ there exists a unique matrix $A^* \in M_{m \times m}(\mathbb{C})$ such that

$$[Ax, y] = [x, A^*y]$$
 holds for all $x, y \in \mathbb{C}^m$.

The matrix $A^* \in M_{m \times m}(\mathbb{C})$ corresponding to $A \in M_{m \times m}(\mathbb{C})$ in Proposition 3.3 is called the *adjoint* of A. It can be expressed as $A^* = B^{-1}A^H B$ and also satisfies $[x, Ay] = [A^*x, y]$ for all $x, y \in \mathbb{C}^m$ [15, Section 2.2]. A

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TABLE 1 Structures with respect to the indefinite inner products $[x, y] = x^H J_{2n} y$ and $[x, y] = x^H R_{2n} y$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$.

Structure	$[x,y] = x^H J_{2n} y$		$[x,y] = x^H R_{2n} y$	
selfadjoint	skew-Hamiltonian	$J_{2n}^T A^H J_{2n} = A$	per-Hermitian	$R_{2n}A^H R_{2n} = A$
skewadjoint	Hamiltonian	$J_{2n}^T A^H J_{2n} = -A$	perskew-Hermitian	$R_{2n}A^H R_{2n} = -A$
automorph	symplectic	$J_{2n}^T A^H J_{2n} = A^{-1}$	perplectic	$R_{2n}A^{H}R_{2n} = A^{-1}$

matrix A that commutes with its adjoint A^* , i.e., $AA^* = A^*A$, is called *normal with respect to* $[x, y] = x^H By$ or simply *B-normal*. For any indefinite inner product $[x, y] = x^H By$ on $\mathbb{C}^m \times \mathbb{C}^m$ there are three classes of *B*-normal matrices that deserve special attention (see also [15, Section 2.2]).

DEFINITION 3.4. Let $[x, y] = x^H B y$ be some indefinite inner product on $\mathbb{C}^m \times \mathbb{C}^m$.

- 1. A matrix $G \in M_{m \times m}(\mathbb{C})$ with the property $G^{-1} = G^*$ is called an automorphism for $[\cdot, \cdot]$.
- 2. A matrix $J \in M_{m \times m}(\mathbb{C})$ satisfying $J^* = B^{-1}J^H B = J$ is called selfadjoint (with respect to $[\cdot, \cdot]$) whereas a matrix $L \in M_{m \times m}(\mathbb{C})$ satisfying $L^* = B^{-1}L^H B = -L$ is called skewadjoint.

Notice that, if $G \in M_{m \times m}(\mathbb{C})$ is an automorphism, [Gx, Gy] = [x, y] holds for all $x, y \in \mathbb{C}^m$ since $[Gx, Gy] = [x, G^*Gy]$ and $G^*G = G^{-1}G = I_m$. In particular, any automorphism is nonsingular. For the standard Euclidean scalar product $(x, y) = [x, y] = x^H I_m y$, automorphisms, selfadjoint and skewadjoint matrices are those which are unitary, Hermitian or skew-Hermitian, respectively. Beside these, special names have also been given to matrices which are automorph, selfadjoint or skewadjoint with respect to the indefinite inner products $[x, y] = x^H By$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$ induced by the matrices $B = J_{2n} \in M_{2n \times 2n}(\mathbb{R})$ and $B = R_{2n} \in M_{2n \times 2n}(\mathbb{R})$ given by

$$J_{2n} = \begin{bmatrix} I_n \\ -I_n \end{bmatrix}, \quad R_{2n} = \begin{bmatrix} R_n \\ R_n \end{bmatrix} \text{ with } R_n = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}.$$

These names are listed in the table from Figure 1¹. For instance, a skew-Hamiltonian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ and a per-Hermitian matrix $C \in M_{2n \times 2n}(\mathbb{C})$ have expressions of the form

(3.2)
$$A = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_1^H \end{bmatrix} \text{ and } C = \begin{bmatrix} C_1 & C_2 \\ C_3 & R_n C_1^H R_n \end{bmatrix}, \quad A_j, C_j \in \mathcal{M}_{n \times n}(\mathbb{C}),$$

where it holds that $A_2 = -A_2^H, A_3 = -A_3^H$ and that $C_2, C_3 \in M_{n \times n}(\mathbb{C})$ are themselves per-Hermitian with respect to $[x, y] = x^H R_n y$ on $\mathbb{C}^n \times \mathbb{C}^n$. Notice that for any indefinite inner product $[x, y] = x^H B y$ on $\mathbb{C}^m \times \mathbb{C}^m$ the selfadjoint and skewadjoint structures are preserved under similarity transformations with automorphisms. This fact is well known and easily confirmed for unitary similarity transformations of Hermitian and skew-Hermitian matrices. In our setting this means that, whenever $A \in M_{2n \times 2n}(\mathbb{C})$ is (skew)-Hamiltonian (per(skew)-Hermitian) and $G \in M_{2n \times 2n}(\mathbb{C})$ is symplectic (perplectic), then $G^{-1}AG$ is again (skew)-Hamiltonian (per(skew)-Hermitian). We will only be considering the indefinite inner products induced by J_{2n} and R_{2n} on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$ from now on.

¹Notice that these names are not consistently used in the literature. For instance, a Hamiltonian matrix here and in [6] is called J-Hermitian in [15].

The result from Proposition 3.5 below is central for the upcoming discussion and can be found in, e.g., [11, Section 4.5] (for the case $A = A^H$). The statement for $A = -A^H$ is easily verified by noting that $A = A^H$ is Hermitian if and only if iA is skew-Hermitian.

PROPOSITION 3.5 (Sylvesters Law of Inertia). Let $A \in M_{m \times m}(\mathbb{C})$ and assume that either $A = A^H$ or $A = -A^H$ holds. Then there exists a nonsingular matrix $U \in M_{m \times m}(\mathbb{C})$ so that

$$U^{H}AU = \begin{bmatrix} -\alpha I_{p} & | \\ & | \\ \hline & \alpha I_{q} & \\ \hline & | & 0_{r \times r} \end{bmatrix},$$

where $\alpha = 1$ if A is Hermitian and $\alpha = i$ otherwise. Hereby, p coincides with the number of negative real/purely imaginary eigenvalues of A, q coincides with the number of positive real/purely imaginary eigenvalues of A and r is the algebraic multiplicity of zero as an eigenvalue of A.

The triple (p, q, r) from Proposition 3.5 is usually referred to as the inertia of A [11, Section 4.5]. Two Hermitian or skew-Hermitian matrices $A, C \in M_{m \times m}(\mathbb{C})$ with the same inertia are called *congruent*. Following directly from Proposition 3.5 we obtain the following proposition (see also [11, Theorem 4.5.8]).

PROPOSITION 3.6. Let $A, C \in M_{m \times m}(\mathbb{C})$ be two matrices which are either both Hermitian or skew-Hermitian. Then there exists a nonsingular matrix $S \in M_{n \times n}(\mathbb{C})$ so that $S^H A S = C$ if and only if A and C have the same inertia.

4. Symplectic and perplectic diagonalizability. In this section, the symplectic and perplectic diagonalization of (skew)-Hamiltonian and per(skew)-Hermitian matrices is analyzed. As those matrices need not be diagonalizable per se, cf. [8, Example 4.2.1], their diagonalizability has to be assumed throughout the whole section. At first, we consider arbitrary (skew)-Hermitian indefinite inner products and provide two auxiliary results related to their selfadjoint matrices. These results will turn out to be useful in Sections 4.1 and 4.2, where we derive necessary and sufficient conditions for (skew)-Hamiltonian or per(skew)-Hermitian matrices to be diagonalizable by a symplectic (respectively, perplectic) similarity transformation. This section is based on [20, Chapter 9].

Let $[x, y] = x^H By$ be some (skew)-Hermitian indefinite inner product on $\mathbb{C}^m \times \mathbb{C}^m$ and let $A \in M_{m \times m}(\mathbb{C})$ be selfadjoint with respect to $[\cdot, \cdot]$. Then, as $A^* = B^{-1}A^H B = A$, we have $\sigma(A) = \overline{\sigma(A)}$. In particular, for each $\lambda \in \sigma(A), \lambda \notin \mathbb{R}, \overline{\lambda}$ is an eigenvalue of A, too, with the same multiplicity. Proposition 4.1 shows that, among the eigenvectors of A, those $x, y \in \mathbb{C}^m$ corresponding to λ and $\overline{\lambda}$, respectively, are the only candidates for having a nonzero inner product [x, y]. This result can also be found in, e.g., [15, Theorem 7.8].

PROPOSITION 4.1. Let $[x, y] = x^H By$ be some (skew)-Hermitian indefinite inner product and $A = A^* \in M_{2n \times 2n}(\mathbb{C})$ be selfadjoint. Moreover, assume $x, y \in \mathbb{C}^{2n}$ are eigenvectors of A corresponding to some eigenvalues $\lambda, \mu \in \sigma(A)$, respectively. Then $\mu \neq \overline{\lambda}$ implies that [x, y] = [y, x] = 0. Consequently, each eigenspace of A for an eigenvalue $\lambda \notin \mathbb{R}$ of A is neutral.

Proof. Under the given assumptions, we have

$$\overline{\lambda}[x, y] = [\lambda x, y] = [Ax, y] = [x, A^*y] = [x, Ay] = [x, \mu y] = \mu[x, y],$$

so, whenever $[x, y] \neq 0$, then $\mu = \overline{\lambda}$ has to hold. This proves the statement by contraposition noting that [x, y] = 0 if and only if [y, x] = 0.

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Now assume that $A = A^* \in M_{m \times m}(\mathbb{C})$ is diagonalizable. Let $\lambda \in \sigma(A)$, $\lambda \neq \overline{\lambda}$, and suppose v_1, \ldots, v_ℓ and $v_{\ell+1}, \ldots, v_{2\ell}$ are eigenbases corresponding to λ and $\overline{\lambda}$, respectively. Additionally, let $v_{2\ell+1}, \ldots, v_m$ be eigenvectors of A completing $v_1, \ldots, v_{2\ell}$ to a basis of \mathbb{C}^m and set $V = [v_1 \cdots v_m] \in M_{m \times m}(\mathbb{C})$. According to Proposition 4.1 we have

(4.3)
$$V^H B V = \begin{bmatrix} 0 & S_\ell & 0 \\ \pm S_\ell^H & 0 & 0 \\ \hline 0 & X \end{bmatrix} \in \mathcal{M}_{m \times m}(\mathbb{C})$$

for some matrices $S_{\ell} \in M_{\ell \times \ell}(\mathbb{C})$ and $X \in M_{(m-2\ell) \times (m-2\ell)}(\mathbb{C})$. In case $B = -B^H$ we have $-S_{\ell}^H$ in (4.3) and $X = -X^H$ whereas we have $+S_{\ell}$ and $X = X^H$ in case $B = B^H$. As V and B are nonsingular, so is $V^H B V$. This implies S_{ℓ} and X in (4.3) to be nonsingular, too. As $\operatorname{span}(v_1, \ldots, v_{2\ell})$ equals the direct sum of the eigenspaces of A corresponding to λ and $\overline{\lambda}$, the nonsingularity of S_{ℓ} gives the following Corollary 4.2 taking Definition 3.2 (1) into account.

COROLLARY 4.2. Let $[x, y] = x^H By$ be some (skew)-Hermitian indefinite inner product and let $A = A^* \in M_{m \times m}(\mathbb{C})$ be selfadjoint and diagonalizable. Then, for any $\lambda \in \sigma(A)$, $\lambda \neq \overline{\lambda}$, the direct sum of the eigenspaces of A corresponding to λ and $\overline{\lambda}$ is always nondegenerate.

Similarly to the derivation preceding Corollary 4.2, one shows that the eigenspace of a selfadjoint matrix $A = A^* \in M_{m \times m}(\mathbb{C})$ corresponding to some real eigenvalue $\mu \in \sigma(A)$ is always nondegenerate, too. We are now in the position to derive statements on the symplectic and perplectic diagonalizability of (skew)-Hamiltonian and per(skew)-Hermitian matrices.

4.1. Symplectic diagonalization of (skew)-Hamiltonian matrices. The following Theorem 4.3 states the main result of this section characterizing those (diagonalizable) (skew)-Hamiltonian matrices which can be brought to diagonal form by a symplectic similarity transformation. Recall that, according to (3.2), a diagonal skew-Hamiltonian matrix $\widetilde{D} \in M_{2n \times 2n}(\mathbb{C})$ has the form

(4.4)
$$\widetilde{D} = \begin{bmatrix} D & 0\\ 0 & D^H \end{bmatrix} \quad \text{with } D = \text{diag}(\lambda_1, \dots, \lambda_n) \in \mathcal{M}_{n \times n}(\mathbb{C}).$$

THEOREM 4.3. Let $A \in M_{2n \times 2n}(\mathbb{C})$ be diagonalizable.

- 1. Assume that A is skew-Hamiltonian. Then A is symplectic diagonalizable if and only if for any real eigenvalue $\lambda \in \sigma(A)$ and some basis v_1, \ldots, v_m of the corresponding eigenspace, the matrix $V^H J_{2n} V$ for $V = [v_1 \cdots v_m]$ has equally many positive and negative imaginary eigenvalues.
- 2. Assume that A is Hamiltonian. Then A is symplectic diagonalizable if and only if for any purely imaginary eigenvalue $\lambda \in \sigma(A)$ and some basis v_1, \ldots, v_m of the corresponding eigenspace, the matrix $V^H J_{2n} V$ for $V = [v_1 \cdots v_m]$ has equally many positive and negative imaginary eigenvalues.

Proof. 1. (\Rightarrow) Let $A \in M_{2n \times 2n}(\mathbb{C})$ be skew-Hamiltonian, that is $A = A^*$, and $S = [s_1 \cdots s_{2n}] \in M_{2n \times 2n}(\mathbb{C})$ symplectic such that

(4.5)
$$S^{-1}AS = \begin{bmatrix} D \\ D^H \end{bmatrix} = S^{-1}A^*S, \quad S^H J_{2n}S = J_{2n},$$

with $D = \text{diag}(\lambda_1, \ldots, \lambda_n) \in \mathcal{M}_{n \times n}(\mathbb{C})$ is a (symplectic) diagonalization of A. If $\lambda_j \in \sigma(A)$ is real, it follows from (4.5) that λ_j has even multiplicity, 2k say, with k instances of λ_j appearing in D and D^H , respectively

(w.l.o.g. on the diagonal positions j_1, \ldots, j_k). Let $s_{j_1}, \ldots, s_{j_k}, s_{n+j_1}, \ldots, s_{n+j_k}$ be the corresponding 2k eigenvectors (appearing as columns in the corresponding positions in S) which span the eigenspace of A and A^* for λ_j . Now set $S_j := [s_{j_1} \cdots s_{j_k} s_{n+j_1} \cdots s_{n+j_k}] \in M_{2n \times 2k}(\mathbb{C})$. Then we have

$$S_j^H J_{2n} S_j = \begin{bmatrix} I_k \\ -I_k \end{bmatrix} \in \mathcal{M}_{2k \times 2k}(\mathbb{C})$$

which follows directly from $S^H J_{2n} S = J_{2n}$. The eigenvalues of $S_j^H J_{2n} S_j$ are +i and -i both with the same multiplicity k. As λ_i was arbitrary, this holds for any real eigenvalue of A.

 (\Leftarrow) Now let $A \in M_{2n \times 2n}(\mathbb{C})$ be skew-Hamiltonian and diagonalizable. Moreover assume that the condition stated above holds for all real eigenvalues of A. We now generate bases for the different eigenspaces of A according to the following rules:

(a) For each pair of eigenvalues $\lambda_j, \overline{\lambda_j} \in \sigma(A), \lambda_j \neq \overline{\lambda_j}$, both with multiplicity m_j , let s_1, \ldots, s_{m_j} be corresponding eigenvectors of A for λ_j and t_1, \ldots, t_{m_j} corresponding eigenvectors of A for $\overline{\lambda_j}$. Set $S_j = [s_1 \cdots s_{m_j} t_1 \cdots t_{m_j}] \in M_{2n \times 2m_j}(\mathbb{C})$. Then, according to Proposition 4.1 and Corollary 4.2 $\operatorname{span}(s_1, \ldots, s_{m_j})$ and $\operatorname{span}(t_1, \ldots, t_{m_j})$ are both neutral and $S_j^H J_{2n} S_j$ is nonsingular. Therefore, the form of $S_j^H J_{2n} S_j$ is

$$S_j^H J_{2n} S_j = \begin{bmatrix} 0 & \widehat{S}_j \\ -\widehat{S}_j^H & 0 \end{bmatrix} \in \mathcal{M}_{2m_j \times 2m_j}(\mathbb{C})$$

for some nonsingular matrix $\widehat{S}_j \in \mathcal{M}_{m_j \times m_j}(\mathbb{C})$. Now, multiplying $S_j^H J_{2n} S_j$ by $\widehat{S}_j^{-H} \oplus I_{m_j}$ and $(\widehat{S}_j^{-H} \oplus I_{m_j})^H$ (from the right and the left) we observe that

$$\left(\widehat{S}_{j}^{-H} \oplus I_{m_{j}}\right)^{H} S_{j}^{H} J_{2n} S_{j} \left(\widehat{S}_{j}^{-H} \oplus I_{m_{j}}\right) = \begin{bmatrix} \widehat{S}_{j}^{-1} \\ I_{m_{j}} \end{bmatrix} \begin{bmatrix} 0 & \widehat{S}_{j} \\ -\widehat{S}_{j}^{H} & 0 \end{bmatrix} \begin{bmatrix} \widehat{S}_{j}^{-H} \\ I_{m_{j}} \end{bmatrix} = \begin{bmatrix} I_{m_{j}} \\ -I_{m_{j}} \end{bmatrix}.$$

Let w_1, \ldots, w_{2m_j} denote the columns of $S_j(\widehat{S}_j^{-H} \oplus I_{m_j})$ and notice that, due to the form of $\widehat{S}_j^{-H} \oplus I_{m_j}$, w_1, \ldots, w_{m_j} and $w_{m_j+1} = t_1, \ldots, w_{2m_j} = t_{m_j}$ are still bases for the eigenspaces of A for λ_j and $\overline{\lambda_j}$, respectively. According to Proposition 4.1, the inner products $[w_\ell, x]$ for any $\ell = 1, \ldots, 2m_j$ and any eigenvector x of A corresponding to some eigenvalue $\mu \in \sigma(A) \setminus \{\lambda_j, \overline{\lambda_j}\}$ are zero.

(b) For each λ_k ∈ σ(A), λ_k ∈ ℝ, let s₁,..., s_{2m_k} be a basis of the corresponding eigenspace (assuming the even multiplicity of λ_k is 2m_k). For S_k := [s₁ ··· s_{2m_k}] ∈ M_{2n×2m_k}(ℂ) the skew-Hermitian matrix S^H_k J_{2n}S_k ∈ M_{2m_k×2m_k}(ℂ) is nonsingular and has, according to our assumptions, exactly m_k positive and m_k negative purely imaginary eigenvalues. Thus, it has the same inertia as J_{2m_k} and there exists some nonsingular matrix T_k ∈ M_{2m_k×2m_k}(ℂ) such that T^H_k(S^H_k J_{2n}S_k)T_k = J_{2m_k} according to Proposition 3.5. Let w₁,..., w_{2m_k} denote the columns of S_kT_k and note that w₁,..., w_{2m_k} is still a basis for the eigenspace of A corresponding to λ_k. According to Proposition 4.1, the inner products [w_ℓ, x] for any ℓ = 1,..., 2m_k and any eigenvector x of A corresponding to some eigenvalue μ ∈ σ(A) \ {λ_k} are zero.

If bases of the eigenspaces for all eigenvalues of A have been constructed according to (a) if $\lambda_j \notin \mathbb{R}$ and (b) if $\lambda_k \in \mathbb{R}$, the new eigenvectors w_1, \ldots, w_{2n} obtained this way are collected in a matrix $W \in M_{2n \times 2n}(\mathbb{C})$, i.e., $W = [w_1 \cdots w_{2n}]$. Note that W is nonsingular and that $W^{-1}AW = D$ is diagonal. Due to the construction of w_1, \ldots, w_{2n} , the skew-Hermitian matrix $W^H J_{2n} W$ has only +1 and -1 as nonzero entries. Hence, it is permutation-similar to J_{2n} . In other words, there exists a (real) permutation matrix $P \in M_{2n \times 2n}(\mathbb{R})$ with

 $P^{H}W^{H}J_{2n}WP = J_{2n}$. Now $P^{H}W^{H}J_{2n}WP = J_{2n}$ so V := WP is symplectic. Moreover, $V^{-1}AV = P^{T}DP$ remains to be diagonal as P is a permutation matrix and the statement 1. is proven.

2. If $A \in M_{2n \times 2n}(\mathbb{C})$ is Hamiltonian notice that $\widehat{A} := iA$ is skew-Hamiltonian. Thus, whenever $S \in M_{2n \times 2n}(\mathbb{C})$ is symplectic and $S^{-1}AS = D \oplus (-D^H)$ is a symplectic diagonalization of A for some diagonal matrix $D \in M_{n \times n}(\mathbb{C})$ we have that

$$S^{-1}\widehat{A}S = S^{-1}(iA)S = iS^{-1}AS = \begin{bmatrix} iD \\ & -iD^H \end{bmatrix} = \begin{bmatrix} \widehat{D} \\ & \widehat{D}^H \end{bmatrix}$$

for $\widehat{D} = iD$ is a symplectic diagonalization of \widehat{A} . From 1. it is known that the diagonalization $S^{-1}\widehat{A}S = \widehat{D} \oplus \widehat{D}^H$ exists if and only if for each real eigenvalue $\lambda \in \sigma(\widehat{A})$ has even multiplicity m and, given any basis v_1, \ldots, v_m of the corresponding eigenspace, the matrix $V^H J_{2n} V$ for $V = [v_1 \cdots v_m]$ has equally many positive and negative purely imaginary eigenvalues. Vice versa this implies that the symplectic diagonalization $S^{-1}AS = D \oplus (-D^H)$ exists if and only if each purely imaginary eigenvalue $\mu \in \sigma(A)$ has even multiplicity m and, given any basis v_1, \ldots, v_m of the corresponding eigenspace, the matrix $V^H J_{2n} V$ for $V = [v_1 \cdots v_m]$ has equally many positive and negative purely imaginary eigenvalues.

The following Corollary 4.4 is a direct consequence of Theorem 4.3 which guarantees the existence of a symplectic diagonalization whenever no real or purely imaginary eigenvalues are present. To understand Corollary 4.4 correctly, zero should be regarded as both, real and purely imaginary.

Corollary 4.4.

- 1. A diagonalizable skew-Hamiltonian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is always symplectic diagonalizable if A has no purely real eigenvalues.
- 2. A diagonalizable Hamiltonian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is always symplectic diagonalizable if A has no purely imaginary eigenvalues.

4.2. Perplectic diagonalization of per(skew)-Hermitian matrices. The main result on the perplectic diagonalization of per-Hermitian and perskew-Hermitian matrices $A \in M_{2n \times 2n}(\mathbb{C})$ is similar to the statement from Theorem 4.3. In particular, the proof of Theorem 4.5 below is analogous to the proof of Theorem 4.3 with the only significant change being the replacement of the skew-Hermitian structures appearing in the proof of Theorem 4.3 (due to the skew-Hermitian matrix J_{2n}) by Hermitian structures caused by R_{2n} . Therefore, statements on purely imaginary eigenvalues turn into statements on real eigenvalues. The proof is consequently omitted.

THEOREM 4.5. Let $A \in M_{2n \times 2n}(\mathbb{C})$ be diagonalizable.

- 1. Assume that A is per-Hermitian. Then A is perplectic diagonalizable if and only if for any real eigenvalue $\lambda \in \sigma(A)$ and some basis v_1, \ldots, v_m of the corresponding eigenspace, the matrix $V^H R_{2n} V$ for $V = [v_1 \cdots v_m]$ has equally many positive and negative real eigenvalues.
- 2. Assume that A is perskew-Hermitian. Then A is perplectic diagonalizable if and only if for any purely imaginary eigenvalue $\lambda \in \sigma(A)$ and some basis v_1, \ldots, v_m of the corresponding eigenspace, the matrix $V^H R_{2n} V$ for $V = [v_1 \cdots v_m]$ has equally many positive and negative real eigenvalues.

The following Corollary 4.6 is an immediate consequence of Theorem 4.5 and is the analogous result to Corollary 4.4 for per(skew)-Hermitian matrices.

COROLLARY 4.6.

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- 1. A diagonalizable per-Hermitian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is always perplectic diagonalizable if A has no purely real eigenvalues.
- 2. A diagonalizable perskew-Hermitian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is always perplectic diagonalizable if A has no purely imaginary eigenvalues.

EXAMPLE 4.7. According to Corollary 4.6 a skew-Hermitian and per-Hermitian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is always perplectic diagonalizable, since it is diagonalizable and has only purely imaginary eigenvalues. Moreover, according to the discussion preceding Proposition 4.1, any eigenvalue $\mu \in i\mathbb{R}$ of A comes with its complex conjugate $\overline{\mu}$ with μ and $\overline{\mu}$ having the same multiplicity. Therefore, if $i\lambda_1, \ldots, i\lambda_n, -i\lambda_1, \ldots, -i\lambda_n$ are the eigenvalues of A ($\lambda_1, \ldots, \lambda_n \in \mathbb{R}$), a similar analysis as in the proof of Theorem 4.3 shows that there exists a perplectic matrix $P \in M_{2n \times 2n}(\mathbb{C})$ such

$$D = P^{-1}AP = \begin{bmatrix} -i\tilde{D} & \\ & iR_n\tilde{D}R_n \end{bmatrix}, \quad \text{with } \tilde{D} = \begin{bmatrix} \lambda_1 & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \in \mathcal{M}_{n \times n}(\mathbb{R}).$$

Now let $Q = \frac{1}{\sqrt{2}} \begin{bmatrix} I_n & -iR_n \\ -iR_n & I_n \end{bmatrix} \in \mathcal{M}_{2n \times 2n}(\mathbb{C})$. It follows from a direct calculation, that Q is perplectic. In consequence, the product $P_1 = PQ$ is perplectic, too, and we obtain

$$(4.6) \qquad P_1^{-1}AP_1 = Q^{-1}(P^{-1}AP)Q = Q^{-1}DQ = \begin{bmatrix} & -\hat{D} \\ R_n\hat{D}R_n \end{bmatrix}, \quad \hat{D} = \begin{bmatrix} & \lambda_1 \\ & \ddots & \\ \lambda_n & & \end{bmatrix} \in \mathcal{M}_{n \times n}(\mathbb{R}).$$

This shows that a skew-Hermitian and per-Hermitian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ can always be perplectic diagonalized as well as perplectic "anti"-diagonalized. Notice that, in the form (4.6), the elements on the anti-diagonal of $P_1^{-1}AP_1$ are real. In the context of real matrices and the bilinear form $[x, y] = x^T R_{2n} y$ (for $x, y \in \mathbb{R}^{2n}$), the existence of the form (4.6) with $A, P_1 \in M_{2n \times 2n}(\mathbb{R})$, has already been proven in [14, Theorem 7.1]. In particular, it is shown in [14] that P_1 can be constructed to be orthogonal, too. The perplectic matrix P_1 in (4.6) can be constructed to be unitary as a consequence of the results from [20, Section 10.2].

5. Normal structured matrices. In this section, we analyze the matrix structures from Section 4 assuming the matrix at hand is additionally normal. Recall that a matrix A is called normal if $A^H A = AA^H$ holds. It is well-known that for any normal matrix $A \in M_{2n \times 2n}(\mathbb{C})$ there exists a unitary matrix $Q \in M_{2n \times 2n}(\mathbb{C})$, so that $Q^H AQ = D = \text{diag}(\lambda_1, \ldots, \lambda_{2n})$ is diagonal (where $\lambda_1, \ldots, \lambda_{2n} \in \mathbb{C}$ are the eigenvalues of A) [9]. Now partition Q and D as $Q = [Q_1 \ Q_2]$ with $Q_1, Q_2 \in M_{2n \times n}(\mathbb{C})$ and $D = D_1 \oplus D_2$ with $D_1 = \text{diag}(\lambda_1, \ldots, \lambda_n), D_2 = \text{diag}(\lambda_{n+1}, \ldots, \lambda_{2n}) \in M_{n \times n}(\mathbb{C})$. We now obtain from $Q^H AQ = D$ that

(5.7)
$$A = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} D_1 & \\ & D_2 \end{bmatrix} \begin{bmatrix} Q_1^H \\ Q_2^H \end{bmatrix} = Q_1 D_1 Q_1^H + Q_2 D_2 Q_2^H =: E + F$$

holds, where $E = Q_1 D_1 Q_1^H$, $F = Q_2 D_2 Q_2^H \in M_{2n \times 2n}(\mathbb{C})$. Notice that E and F are normal for themselves. Moreover, since Q is unitary, i.e., $Q^H Q = Q Q^H = I_n$, we have $Q_1^H Q_2 = Q_2^H Q_1 = 0$. It is now seen directly that EF = FE = 0 holds. Beside this property there are no more obvious relations between E and F.

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This situation changes whenever the normal matrix A is (skew)-Hamiltonian or per(skew)-Hermitian. In case of symplectic or perplectic diagonalizability, the matrices E and F are related in a particular way. This relation between E and F is investigated in this section giving some new insights on the symplectic and perplectic diagonalization of those matrices. To this end, the following subsection provides some facts about Lagrangian and neutral subspaces which will be of advantage for our discussion in the sequel. This section is based on [20, Chapter 10].

5.1. Lagrangian subspaces. Let $[x, y] = x^H By$ be either the perplectic form with $B = R_{2n}$ or the symplectic form with $B = J_{2n}$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$. In this section, we briefly collect some information about neutral subspaces² with respect to the indefinite inner product $[x, y] = x^H By$. At first, it is obvious that the set of all neutral subspaces in \mathbb{C}^{2n} constitutes a partial order under the relation of set-inclusion. That is, for any neutral subspaces $F, G, H \subseteq \mathbb{C}^{2n}$ we have reflexivity $(F \subseteq F)$, transitivity $(F \subseteq G, G \subseteq H$ yields $F \subseteq H)$ and anti-symmetry $(F \subseteq G, G \subseteq F)$ yields F = G. Moreover, for any chain of neutral subspaces $F_1 \subseteq F_2 \subseteq \cdots \subseteq F_k$ the space F_k contains all other spaces from this chain [7, Definition O-1.6]. In other words, each chain of subspaces has an neutral subspace as an upper bound. According to the lemma of Zorn [23], these facts lead to the observation that the (partially ordered) set of neutral subspaces has maximal elements. The next proposition presents an upper bound for the dimensions of neutral subspaces.

PROPOSITION 5.1. For the symplectic inner product $[x, y] = x^H J_{2n} y$ and the perplectic inner product $[x, y] = x^H R_{2n} y$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$ the maximal possible dimension of an neutral subspace is n.

Proof. For the Hermitian form $[x, y] = x^H R_{2n} y$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$ the statement is proven in [8, Theorem 2.3.4] noting that R_{2n} has only the eigenvalues +1 and -1 with multiplicity n. The statement for the symplectic form follows from the same theorem taking into account that the skew-Hermitian form $[x, y] = x^H J_{2n} y$ and the Hermitian form $[x, y] = x^H (iJ_{2n})y$ have the same neutral subspaces and iJ_{2n} has eigenvalues +1 and -1 again with multiplicities n.

Notice that $\operatorname{im}(S_1)$ and $\operatorname{im}(S_2)$ for any symplectic matrix $[S_1 \ S_2] \in M_{2n \times 2n}(\mathbb{C})$, $S_j \in M_{2n \times n}(\mathbb{C})$, are neutral of dimension n, i.e., Lagrangian (the same holds analogously for perplectic matrices). Thus, the bound given in Proposition 5.1 is in both cases sharp. Now it is clear that $\operatorname{im}(S_1)$ has to be a maximal neutral subspace. The following proposition makes a statement on the dimensions of all other maximal neutral subspaces.

PROPOSITION 5.2. For the symplectic inner product $[x, y] = x^H J_{2n} y$ and the perplectic inner product $[x, y] = x^H R_{2n} y$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$ all maximal neutral subspaces have the same dimension. In particular, an neutral subspace is maximal if and only if it is Lagrangian.

Proof. The statement for the Hermitian form $[x, y] = x^H R_{2n} y$ is proven in $[2, \S 4.2]$. The statement on the symplectic form $[x, y] = x^H J_{2n} y$ follows again from the fact that the Hermitian form $[x, y] = x^H (iJ_{2n}) y$ has the same neutral subspaces as $[x, y] = x^H J_{2n} y$.

The statement of the following corollary will be important in the upcoming sections.

COROLLARY 5.3. For the symplectic inner product $[x, y] = x^H J_{2n} y$ and the perplectic inner product $[x, y] = x^H R_{2n} y$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$, each neutral subspace of \mathbb{C}^{2n} is contained in a Lagrangian subspace.

Proof. Let $F \subseteq \mathbb{C}^{2n}$ be any neutral subspace. Then $\dim(F) \leq n$ holds according to Proposition 5.1.

 $^{^{2}}$ The results from this section (in particular, Corollary 5.3) are likely to be known although they are not readily found in the literature. They have already been stated in [20, Section 10.1].

 \Box

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As the set of all neutral subspaces of \mathbb{C}^{2n} is partially ordered and has maximal elements, there is always a maximal neutral subspace $G \subseteq \mathbb{C}^{2n}$ that contains S. As all maximal neutral subspaces are Lagrangian according to Proposition 5.2, the statement follows.

5.2. Normal (skew)-Hamiltonian matrices and symplectic diagonalizability. In this section, we consider normal (skew)-Hamiltonian matrices and analyze their properties with respect to (simultaneous) symplectic and unitary diagonalization. A key fact used in the subsequent analysis is that matrices which are unitary and symplectic (for which we use the abbreviation *unitary-symplectic*) have a very special form, cf. Proposition 5.4 (see also [19]). Theorem 5.5 shows that unitary and symplectic diagonalizations of any normal (skew)-Hamiltonian matrix are always compatible and simultaneously achievable. This is the basic insight underlying the decompositions presented in Theorem 5.6.

PROPOSITION 5.4. A matrix $Q \in M_{2n \times 2n}(\mathbb{C})$ is unitary-symplectic if and only if $Q = \begin{bmatrix} V & J_{2n}^T V \end{bmatrix}$ for some matrix $V \in M_{2n \times n}(\mathbb{C})$ with $V^H V = I_n$ and $V^H J_{2n} V = 0$.

Proof. Let $Q = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix}$ be unitary-symplectic with $Q_1, Q_2 \in M_{2n \times n}(\mathbb{C})$. As Q is unitary we have $Q^H Q = I_{2n}$ and as it is symplectic $Q^H J_{2n} Q = J_{2n}$ holds. Multiplying the latter with Q from the left gives $J_{2n}Q = QJ_{2n}$, so Q commutes with J_{2n} . From this relation it follows that $J_{2n}Q_1 = -Q_2$, i.e., $Q_2 = J_{2n}^T Q_1$. Moreover, from $Q^H J_{2n}Q = J_{2n}$ it follows that $Q_1^H J_{2n}Q_1 = 0$. Now let $Q = \begin{bmatrix} V & J_{2n}^T V \end{bmatrix}$ with $V^H V = I_n$ and $V^H J_{2n} V = 0$ be given. We have

$$\begin{bmatrix} V & J_{2n}^T V \end{bmatrix}^H J_{2n} \begin{bmatrix} V & J_{2n}^T V \end{bmatrix} = \begin{bmatrix} V^H \\ V^H J_{2n} \end{bmatrix} J_{2n} \begin{bmatrix} V & J_{2n}^T V \end{bmatrix} = \begin{bmatrix} V^H J_{2n} V & V^H V \\ -V^H V & -V^H J_{2n}^T V \end{bmatrix} = \begin{bmatrix} I_n \\ -I_n \end{bmatrix}.$$

which yields $Q^H J_{2n} Q = J_{2n}$. This completes the proof.

In other words, Proposition 5.4 states that $Q = \begin{bmatrix} V & J_{2n}^T V \end{bmatrix} \in M_{2n \times 2n}(\mathbb{C})$ is unitary-symplectic if and only if the columns of $V \in M_{2n \times n}(\mathbb{C})$ are orthonormal and span a Lagrangian subspace. Recall that a diagonal Hamiltonian matrix $\widetilde{D} \in M_{2n \times 2n}(\mathbb{C})$ has the form

(5.8)
$$\widetilde{D} = \begin{bmatrix} D & 0 \\ 0 & -D^H \end{bmatrix} \text{ with } D = \operatorname{diag}(\lambda_1, \dots, \lambda_n) \in \operatorname{M}_{n \times n}(\mathbb{C}).$$

The following Theorem 5.5 gives a condition for the existence of a unitary-symplectic diagonalization of a normal (skew)-Hamiltonian matrix. In particular, it turns out that the symplectic diagonalizability is always sufficient. We prove the statement only for Hamiltonian matrices as the proof works analogously in the skew-Hamiltonian case.

THEOREM 5.5. A normal (skew)-Hamiltonian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is symplectic diagonalizable if and only if it is unitary-symplectic diagonalizable.

Proof. (⇒) Let $A \in M_{2n \times 2n}(\mathbb{C})$ be normal Hamiltonian and symplectic diagonalizable via $T \in M_{2n \times 2n}(\mathbb{C})$, i.e.,

$$T^{-1}AT = \begin{bmatrix} D \\ & -D^H \end{bmatrix}, \quad T^H J_{2n}T = J_{2n}, \quad D = \operatorname{diag}(\lambda_1, \dots, \lambda_n)$$

Let $T = \begin{bmatrix} T_1 & T_2 \end{bmatrix}$ with $T_1 = \begin{bmatrix} t_1 & \cdots & t_n \end{bmatrix}, T_2 \in M_{2n \times n}(\mathbb{C})$. The fact that $T^H J_{2n}T = J_{2n}$ holds reveals that span (t_1, \ldots, t_n) is a Lagrangian subspaces (as is span (T_2)). Due to the normality of A, eigenspaces for different eigenvalues of A are orthogonal to each other. Whenever any λ_j appears r times in D (in positions j_1, \ldots, j_r , say), we orthogonalize and normalize the corresponding eigenvectors t_{j_1}, \ldots, t_{j_r} from

 T_1 obtaining s_{j_1}, \ldots, s_{j_r} . In particular, whenever λ_k appears only once in D (in position k), the sole eigenvector t_k is replaced by its normalized version $s_k = t_k/||t_k||_2$. The n vectors obtained from this orthogonalization procedure are collected in a matrix $S \in M_{2n \times n}(\mathbb{C})$, that is, $S = [s_1 \cdots s_n]$, and we set $\widehat{S} = [S \quad J_{2n}^T S] \in M_{2n \times 2n}(\mathbb{C})$. Now s_1, \ldots, s_n are n orthonormal eigenvectors of A with $\operatorname{span}(T_1) = \operatorname{span}(S)$, i.e., $\operatorname{span}(S)$ is still Lagrangian. According to Proposition 5.4 \widehat{S} is unitary-symplectic. Moreover,

(5.9)
$$\widehat{A} := \widehat{S}^H A \widehat{S} = \begin{bmatrix} S^H \\ S^H J_{2n} \end{bmatrix} A \begin{bmatrix} S & J_{2n}^T S \end{bmatrix} = \begin{bmatrix} S^H A S & S^H A J_{2n}^T S \\ S^H J_{2n} A S & S^H J_{2n} A J_{2n} S \end{bmatrix}.$$

As AS = SD holds (following from $AT_1 = T_1D$ and the construction of S), we have $S^HAS = D$ in (5.9) using the fact that $S^HS = I_n$. Moreover, $S^HJ_{2n}AS = S^HJ_{2n}SD = 0$ holds since im(S) is a Lagrangian subspace, i.e., $S^HJ_{2n}S = 0$. As \hat{S} is symplectic, \hat{A} remains to be Hamiltonian. This implies $S^HJ_{2n}AJ_{2n}S$ in (5.9) to be equal to $-D^H$. Therefore, we showed that \hat{A} is actually upper-triangular. However, since \hat{S} is unitary, the normality of A is preserved in \hat{A} . As a normal upper-triangular matrix must be diagonal, $\hat{S}^HA\hat{S}$ is a unitary-symplectic diagonalization of A.

$$(\Leftarrow)$$
 This is clear

The next Theorem 5.6 states a special property of normal Hamiltonian matrices $A \in M_{2n \times 2n}(\mathbb{C})$ which are symplectic diagonalizable. In this case, the unitary-symplectic diagonalizability according to Theorem 5.5 reveals the existence of a specially structured additive decomposition of A similar to the one from (5.7). As will be shown next, this decomposition is actually equivalent to A being symplectic diagonalizable. Theorem 5.6 is the main result of this section.

THEOREM 5.6. A matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is normal Hamiltonian and symplectic diagonalizable if and only if $A = N - N^*$ for some normal matrix $N \in M_{2n \times 2n}(\mathbb{C})$ satisfying $NN^* = N^*N = 0$.

Proof. (\Rightarrow) Let $A \in M_{2n \times 2n}(\mathbb{C})$ be normal Hamiltonian and assume that A is symplectic diagonalizable. According to Theorem 5.5, there exists a unitary-syplectic diagonalization $U^H A U = \widetilde{D}$ of A and, by Proposition 5.4, $U = [V \ J_{2n}^H V]$ for some matrix $V \in M_{2n \times n}(\mathbb{C})$ with $V^H V = I_n$ and $V^H J_{2n} V = 0$. Moreover, \widetilde{D} has the form given in (5.8) for some matrix $D = \text{diag}(\lambda_1, \ldots, \lambda_n) \in M_{n \times n}(\mathbb{C})$. Then

(5.10)
$$A = U\widetilde{D}U^{H} = \begin{bmatrix} V & J_{2n}^{H}V \end{bmatrix} \begin{bmatrix} D & 0 \\ 0 & -D^{H} \end{bmatrix} \begin{bmatrix} V^{H} \\ V^{H}J_{2n} \end{bmatrix}$$
$$= VDV^{H} - J_{2n}^{H}VD^{H}V^{H}J_{2n} = N - N^{\star}$$

for $N := VDV^H$. Moreover, N is normal as $NN^H = VDV^HVD^HV^H = VDD^HV^H$ coincides with $N^HN = VD^HDV^H$ since D is diagonal. Furthermore, we have

$$NN^{\star} = VDV^{H} \left(J_{2n}^{H} VD^{H} V^{H} J_{2n} \right) = -VD \left(V^{H} J_{2n} V \right) D^{H} V^{H} J_{2n} = 0$$

as $V^H J_{2n} V = 0$. Similarly, it can be seen that $N^* N = 0$ holds.

(⇐) Now assume that $A = N - N^*$ holds for some normal matrix $N \in M_{2n \times 2n}(\mathbb{C})$ with $NN^* = N^*N = 0_{2n \times 2n}$. Then A is Hamiltonian since $A^* = (N - N^*)^* = N^* - N = -(N - N^*) = -A$. Furthermore, we have

(5.11)
$$A^{H}A = (N - N^{*})^{H}(N - N^{*}) = N^{H}N - (N^{*})^{H}N - N^{H}N^{*} + (N^{*})^{H}N^{*},$$
$$AA^{H} = (N - N^{*})(N - N^{*})^{H} = NN^{H} - N^{*}N^{H} - N(N^{*})^{H} + N^{*}(N^{*})^{H}.$$

Recall that the normality of N^* follows directly from the normality of N. With this observation, the assumption $NN^* = N^*N$ and the normality of N^* imply $N(N^*)^H = (N^*)^H N$ according to [9, Section 2(6)]. Similarly, we obtain $N^*N^H = N^H N^*$ and both expressions in (5.11) coincide. Thus, A is normal.

Moreover, as $N^*N = J_{2n}^T N^H J_{2n} N = 0$, multiplication from the left with J_{2n} yields $N^H J_{2n} N = 0$, so the columns of N span an neutral subspace. Furthermore, $N^*N = 0$ implies $im(N) \subseteq null(N^*)$ which yields $rank(N) \leq n \operatorname{since}^3$

$$\operatorname{rank}(N) = \dim(\operatorname{im}(N)) \le \dim(\operatorname{null}(N^*)) = 2n - \operatorname{rank}(N^*) = 2n - \operatorname{rank}(N).$$

Now, the normality of N and $\operatorname{rank}(N) \leq n$ imply that there exists a diagonal matrix $D \in M_{n \times n}(\mathbb{C})$, rank $(D) = \operatorname{rank}(N)$, and a matrix $V \in M_{2n \times n}(\mathbb{C})$ with orthonormal columns (i.e., $V^H V = I_n$) so that $N = VDV^H$. If $\operatorname{rank}(N) = k < n$, then D has n - k eigenvalues equal to zero. Without loss of generality, we assume that these zeros appear in the trailing n - k diagonal positions in D. The expression of N implies $N^* = J_{2n}^T N^H J_{2n} = J_{2n}^T V D^H V^H J_{2n}$. Therefore, A can be expressed as

(5.12)
$$A = N - N^* = V D V^H - J_{2n}^T V D^H V^H J_{2n}.$$

With $\widetilde{D} := \begin{bmatrix} D \\ -D^H \end{bmatrix}$ and $U := \begin{bmatrix} V & J_{2n}^T V \end{bmatrix}$, we observe in accordance with (5.12) that

(5.13)
$$U\widetilde{D}U^{H} = \begin{bmatrix} V & J_{2n}^{T}V \end{bmatrix} \begin{bmatrix} D \\ & -D^{H} \end{bmatrix} \begin{bmatrix} V^{H} \\ V^{H}J_{2n} \end{bmatrix} = VDV^{H} - J_{2n}^{T}VD^{H}V^{H}J_{2n} = A.$$

Then, obviously, $U^H A U = \tilde{D}$ is diagonal. Unfortunately, as long as $V^H J_{2n} V = 0$ does not holds, U will neither be unitary nor symplectic. This will only hold if im(V) is a Lagrangian subspace. Then, in fact, Proposition 5.4 applies and the theorem is proven. We have to distinguish between the two cases rank(N) = n and rank(N) = k < n.

- Case 1: rank(N) = n. Obviously rank(N) = n is equivalent to dim(im(N)) = n. Then we have rank(D) = n, and therefore, im(N) = im(V) is a Lagrangian subspace. As $V^H V = I_n$ holds, Proposition 5.4 yields that U is unitary-symplectic and $U^H A U = \tilde{D}$ is a unitary-symplectic diagonalization of A.
- Case 2: rank(N) = k < n. Recall that we assumed the n k eigenvalues of D which are equal to zero to appear in its trailing n - k diagonal positions. Then, if $V = [v_1 \cdots v_n]$ it is immediate that im(N)coincides with the span (v_1, \ldots, v_k) . In other words, the last n - k columns v_{k+1}, \ldots, v_n of V have no contribution to the matrices N, N^* or A at all. Therefore, as long as the orthogonality constraint is met, v_{k+1}, \ldots, v_n can be replaced by any other columns without changing the expression of Ain (5.13). Now we take Corollary 5.3 into account. As $span(v_1, \ldots, v_k) = im(N)$ is an neutral subspace (of dimension k), it is properly contained in a Lagrangian subspace. Therefore, there exist n - k vectors $\tilde{v}_{k+1}, \ldots, \tilde{v}_n \in \mathbb{C}^{2n}$ such that $span(v_1, \ldots, v_k, \tilde{v}_{k+1}, \ldots, \tilde{v}_n)$ is a Lagrangian subspace. If $\tilde{v}_{k+1}, \ldots, \tilde{v}_n$ are chosen so that

$$\widetilde{V} := \left[v_1 \cdots v_k \, \widetilde{v}_{k+1} \cdots \widetilde{v}_n \, \right] \in \mathcal{M}_{2n \times n}(\mathbb{C})$$

has orthonormal columns, i.e., $\widetilde{V}^H \widetilde{V} = I_n$, we obtain

(5.14)
$$\begin{bmatrix} \widetilde{V} & J_{2n}^T \widetilde{V} \end{bmatrix} \begin{bmatrix} D \\ & -D^H \end{bmatrix} \begin{bmatrix} \widetilde{V}^H \\ \widetilde{V}^H J_{2n} \end{bmatrix} = \widetilde{V} D \widetilde{V}^H - J_{2n}^T \widetilde{V} D^H \widetilde{V}^H J_{2n} = A.$$

³Alternatively, rank $(N) \leq n$ follows from the isotropy of im(N) using the result from Proposition 5.1.

Now the matrix $\widetilde{U} := \begin{bmatrix} \widetilde{V} & J_{2n}^T \widetilde{V} \end{bmatrix} \in \mathcal{M}_{2n \times 2n}(\mathbb{C})$ is unitary-symplectic according to Proposition 5.4 and $\widetilde{U}^H A \widetilde{U} = \widetilde{D}$ is a unitary-symplectic diagonalization of A.

REMARK 5.7. Consider once again the proof of Theorem 5.6 and a decomposition $A = N - N^*$ for some normal Hamiltonian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ with $NN^* = N^*N = 0$ and normal $N \in M_{2n \times 2n}(\mathbb{C})$.

- 1. For the matrix $N \in M_{2n \times 2n}(\mathbb{C})$ it always holds that $\operatorname{rank}(N) = \operatorname{rank}(N^*) \leq n$ and $\operatorname{im}(N)$, $\operatorname{im}(N^*)$ are neutral subspaces. Moreover, as $AN = (N N^*)N = N^2$ and $AN^* = (N^*)^2$, both $\operatorname{im}(N)$ and $\operatorname{im}(N^*)$ are invariant for A. In conclusion, $\operatorname{im}(N)$ and $\operatorname{im}(N^*)$ are invariant Lagrangian subspaces for A if $\operatorname{rank}(N) = \operatorname{rank}(N^*) = n$.
- 2. If (λ, v) is an eigenpair of N, i.e., $Nv = \lambda v$, and $\lambda \neq 0$, then

$$Av = \frac{1}{\lambda}(N - N^{\star})(\lambda v) = \frac{1}{\lambda}(N - N^{\star})Nv = \frac{1}{\lambda}N^{2}v = \lambda v,$$

so λ is an eigenvalue of A with eigenvector v. In particular, we have $\sigma(N) \setminus \{0\} \subseteq \sigma(A)$. Similarly, it can be shown that $\sigma(N^*) \setminus \{0\} \subseteq \sigma(A)$. In conclusion, whenever rank $(N) = \operatorname{rank}(N^*) = n$, the matrix A is nonsingular (i.e., $0 \notin \sigma(A)$) and it holds that $(\sigma(N) \cup \sigma(N^*)) \setminus \{0\} = \sigma(A)$.

The additive decomposition $A = N - N^* \in M_{2n \times 2n}(\mathbb{C})$ (for N being normal with $NN^* = N^*N = 0$) proven in Theorem 5.6 can be used to easily derive some nice consequences whenever not A itself but some *expression in A* is considered. One such situation is given by considering the exponential of A [10, Section 10]. Recall that the exponential of a Hamiltonian matrix yields a symplectic matrix [21, Section 7.2].

EXAMPLE 5.8. Let $A = N - N^* \in M_{2n \times 2n}(\mathbb{C})$ be normal Hamiltonian with some normal $N \in M_{2n \times 2n}(\mathbb{C})$ satisfying $NN^* = N^*N = 0$. Considering the exponential $\exp(A)$ of A we obtain

$$\exp(A) = \exp(N - N^*) = \exp(N) \exp(-N^*) = \exp(N) \exp(N^*)^{-1} = \exp(N) \exp(J_{2n}^T N^H J_{2n})^{-1} = \exp(N) (J_{2n}^T \exp(N^H) J_{2n})^{-1} = \exp(N) (J_{2n}^T \exp(N)^H J_{2n})^{-1} = \exp(N) (\exp(N)^*)^{-1},$$

where we have used the facts that $\exp(-N^*) = \exp(N^*)^{-1}$ and $\exp(J_{2n}^{-1}N^H J_{2n}) = J_{2n}^{-1}\exp(N)^H J_{2n}$, cf. [10]. Notice that the exponential of a normal matrix remains to be normal. Therefore, the symplectic and normal matrix $\exp(A)$ can be decomposed as $S(S^*)^{-1} = SS^{-*}$ for some normal matrix $S \in M_{2n \times 2n}(\mathbb{C})$. If $A = N + N^*$ is skew-Hamiltonian with N normal and $NN^* = N^*N = 0$, the same derivation shows that $\exp(A) = SS^*$ (for $S = \exp(N)$) revealing nicely the maintained skew-Hamiltonian structure. Certainly, $\exp(A)$ is again normal.

Theorem 5.6 directly extends to normal skew-Hamiltonian matrices which are unitary-symplectic diagonalizable. To this end, notice that a diagonal skew-Hamiltonian matrix $\tilde{D} \in M_{2n \times 2n}(\mathbb{C})$ has the form given in (4.4). Thus, the only significant difference comparing the proofs of Theorem 5.9 and Theorem 5.6 above is a change of sign. Consequently, the proof of Theorem 5.9 is omitted.

THEOREM 5.9. A matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is normal skew-Hamiltonian and symplectic diagonalizable if and only if $A = N + N^*$ for some normal matrix $N \in M_{2n \times 2n}(\mathbb{C})$ satisfying $NN^* = N^*N = 0$.

As the next example shows, the special additive decomposability of a normal skew-Hamiltonian matrix $A = N + N^* \in M_{2n \times 2n}(\mathbb{C})$ (with N normal and $NN^* = N^*N = 0$) carries over to other matrix functions as, e.g., matrix roots. In particular, a matrix root of A can be expressed by an analogous decomposition as A replacing N by its matrix root.

EXAMPLE 5.10. Let $A = N + N^* \in M_{2n \times 2n}(\mathbb{C})$ be nonsingular, normal and skew-Hamiltonian with $N = VDV^H$ as in (5.10) and $D = \text{diag}(\lambda_1, \ldots, \lambda_n)$ such that

$$A = U\widetilde{D}U^{H} = \begin{bmatrix} V & J_{2n}^{H}V \end{bmatrix} \begin{bmatrix} D & 0 \\ 0 & D^{H} \end{bmatrix} \begin{bmatrix} V^{H} \\ V^{H}J_{2n} \end{bmatrix}$$
$$= VDV^{H} + J_{2n}^{H}VD^{H}V^{H}J_{2n} = N + N^{*}$$

Define $D^{1/2} = \operatorname{diag}(\lambda_1^{1/2}, \dots, \lambda_n^{1/2})$ and $N^{1/2} := VD^{1/2}V^H$ (where $^{1/2}$ denotes any square root). Then $N^{1/2}$ is a square root of N, that is, $(N^{1/2})^2 = N$. Moreover, $((N^{1/2})^*)^2 = N^*$ can be verified by a direct calculation and it still holds that $N^{1/2}(N^{1/2})^* = (N^{1/2})^*N^{1/2} = 0$ due to the construction of $N^{1/2}$. Therefore, we obtain

$$(N^{1/2} + (N^{1/2})^*) (N^{1/2} + (N^{1/2})^*) = (N^{1/2})^2 + N^{1/2} (N^{1/2})^* + (N^{1/2})^* N^{1/2} + ((N^{1/2})^*)^2$$

= N + N* = A,

and $N^{1/2} + (N^{1/2})^*$ is a normal skew-Hamiltonian square root of A which is, by Theorem 5.9, again symplectic diagonalizable. Certainly, this result can be generalized to arbitrary matrix pth roots for any $p \in \mathbb{N}$.

5.3. Normal per(skew)-Hermitian matrices and perplectic diagonalizability. Now we turn our attention to normal matrices which are per-Hermitian or perskew-Hermitian and analyze their properties with respect to unitary and perplectic diagonalization. The main statements are similar to the previous results from Section 5.2 although the indefinite inner product $[x, y] = x^H R_{2n} y$ on $\mathbb{C}^{2n} \times \mathbb{C}^{2n}$ under consideration is now Hermitian instead of skew-Hermitian. We begin with the characterization of matrices which are both unitary and perplectic in Proposition 5.11 (we use the abbreviation *unitary-perplectic* for these matrices). The statement analogous to Theorem 5.5 on unitary-perplectic diagonalizability is presented in Theorem 5.12 whereas the analogous results to Theorem 5.6 and 5.9 are given in Theorem 5.13.

PROPOSITION 5.11. A matrix $Q \in M_{2n \times 2n}(\mathbb{C})$ is unitary-perplectic if and only if $Q = \begin{bmatrix} V & R_{2n}VR_n \end{bmatrix}$ for some matrix $V \in M_{2n \times n}(\mathbb{C})$ with $V^H V = I_n$ and $V^H R_{2n}V = 0$.

Proof. Let $Q = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix}$ be unitary-perplectic with $Q_1, Q_2 \in M_{2n \times n}(\mathbb{C})$. As Q is unitary we have $Q^H Q = I_{2n}$ and as it is perplectic $Q^H R_{2n} Q = R_{2n}$ holds. Multiplying the latter with Q from the left gives $R_{2n}Q = QR_{2n}$, so Q commutes with R_{2n} . Matrices satisfying this condition are known as centrosymmetric [1, Definition 2.2]. It is easy to see that any centrosymmetric matrix $C \in M_{2n \times 2n}(\mathbb{C})$ is symmetric with respect to the center of it and thus can be expressed as $C = \begin{bmatrix} W & R_{2n}WR_n \end{bmatrix}$ for some $W \in M_{2n \times n}(\mathbb{C})$. Moreover, any matrix of the form of C is centrosymmetric for any W. Now let $Q = \begin{bmatrix} V & R_{2n}VR_n \end{bmatrix}$ with $V^H V = I_n$ and $V^H R_{2n} V = 0$ be given. Then we have

$$\begin{bmatrix} V & R_{2n}VR_n \end{bmatrix}^H R_{2n} \begin{bmatrix} V & R_{2n}^T VR_n \end{bmatrix} = \begin{bmatrix} V^H \\ R_n V^H R_{2n} \end{bmatrix} R_{2n} \begin{bmatrix} V & R_{2n}VR_n \end{bmatrix}$$
$$= \begin{bmatrix} V^H R_{2n}V & V^H VR_n \\ R_n V^H V & R_n V^H R_{2n}VR_n \end{bmatrix} = \begin{bmatrix} R_n \\ R_n \end{bmatrix},$$

which gives $Q^H R_{2n} Q = R_{2n}$. This completes the proof.

The analogous result to Theorem 5.5 is stated in the following proposition.

THEOREM 5.12. A normal per(skew)-Hermitian matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is perplectic diagonalizable if and only if it is unitary-perplectic diagonalizable.

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The proof of Theorem 5.12 goes along the same lines as that of Theorem 5.5 noting that, for any perplectic matrix $P = \begin{bmatrix} P_1 & P_2 \end{bmatrix} \in M_{2n \times 2n}(\mathbb{C})$ with $P_1, P_2 \in M_{2n \times n}(\mathbb{C})$, $\operatorname{span}(P_1)$ and $\operatorname{span}(P_2)$ are Lagrangian subspaces. The same orthogonalization procedure of the eigenvectors of A given by the columns of P_1 as discussed in the proof of Theorem 5.5 then admits the construction of a unitary-perplectic matrix (characterized by Proposition 5.11) which diagonalizes A.

Notice that a diagonal per(skew)-Hermitian matrix $\tilde{D} \in M_{2n \times 2n}(\mathbb{C})$ has the form

(5.15)
$$\widetilde{D} = \begin{bmatrix} D \\ \pm R_n D^H R_n \end{bmatrix} \text{ with } D = \operatorname{diag}(\lambda_1, \dots, \lambda_n) \in \mathcal{M}_{n \times n}(\mathbb{C}).$$

The characterization of unitary-perplectic matrices in Proposition 5.11 together with (5.15) admit a proof analogous to that of Theorem 5.6 for the following results.

Theorem 5.13.

- 1. A matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is normal per-Hermitian and perplectic diagonalizable if and only if $A = N + N^*$ for some normal matrix $N \in M_{2n \times 2n}(\mathbb{C})$ satisfying $NN^* = N^*N = 0$.
- 2. A matrix $A \in M_{2n \times 2n}(\mathbb{C})$ is normal perskew-Hermitian and perplectic diagonalizable if and only if $A = N N^*$ for some normal matrix $N \in M_{2n \times 2n}(\mathbb{C})$ satisfying $NN^* = N^*N = 0$.

Comparing Theorem 5.6 and Theorem 5.9 to Theorem 5.13 notice that the decomposition $A = N \pm N^*$ always carries a '-' sign whenever A is skewadjoint and a '+' sign if A is selfadjoint with respect to the indefinite inner products $[x, y] = x^H J_{2n} y$ and $[x, y] = x^H R_{2n} y$, respectively. It can be shown analogously to Example 5.8 that the exponential $\exp(A)$ of any normal $\operatorname{per}(\operatorname{skew})$ -Hermitian matrix $A = N \pm N^*$ (with normal $N \in M_{2n \times 2n}(\mathbb{C})$ satisfying $NN^* = N^*N = 0$) can be expressed as $\exp(A) = PP^{\pm *}$ for the normal matrix $P = \exp(N)$. In particular, whenever A is normal perskew-Hermitian, then $\exp(A)$ is normal and perplectic with an expression of the form $\exp(A) = PP^{-*}$ for a normal matrix P. Similarly, the result from Example 5.10 extends by the same reasoning to per-Hermitian matrices.

6. Conclusions. In this work, we analyzed (skew)-Hamiltonian and per(skew)-Hermitian matrices under the viewpoint of structure-preserving diagonalizability. We showed that the symplectic and perplectic diagonalization of such matrices is possible if and only if certain conditions apply to their real or purely imaginary eigenvalues and corresponding eigenspaces (cf. Theorems 4.3 and 4.5). This diagonalizability condition turned out to be essentially the same for (skew)-Hamiltonian and per(skew)-Hermitian matrices although their structures are determined by a skew-Hermitian indefinite inner product and a Hermitian indefinite inner product, respectively. We conferred special attention to those structured matrices which are additionally normal. In this case, it was shown that an existing symplectic or perplectic diagonalization is a sufficient criterion to guarantee a diagonalization by a unitary-symplectic or unitary-perplectic similarity transformation to exist (Theorems 5.12 and 5.5). For normal (skew)-Hamiltonian and per(skew)-Hermitian matrices it was proven that a symplectic or perplectic transformation to diagonal form implies the existence of a structured additive decomposition of such matrices. In turn, such an additive decomposition was shown to imply the matrix at hand to be unitary-symplectic or unitary-perplectic diagonalizable and gave an alternative characterization of such matrices (Theorems 5.6, 5.9 and 5.13). The proof of this fact essentially required the knowledge that every neutral subspace is contained in a maximal neutral subspace (the latter has been called Lagrangian subspace, cf. Corollary 5.3). Throughout this work, some examples have been provided to illustrate the obtained results.

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