

STRUCTURED EIGENVALUE/EIGENVECTOR BACKWARD ERRORS OF MATRIX PENCILS ARISING IN OPTIMAL CONTROL*

CHRISTIAN MEHL[†], VOLKER MEHRMANN[†], AND PUNIT SHARMA[‡]

Abstract. Eigenvalue and eigenpair backward errors are computed for matrix pencils arising in optimal control. In particular, formulas for backward errors are developed that are obtained under block-structure-preserving and symmetry-structure-preserving perturbations. It is shown that these eigenvalue and eigenpair backward errors are sometimes significantly larger than the corresponding backward errors that are obtained under perturbations that ignore the special structure of the pencil.

Key words. Eigenvalue backward error, Eigenvector backward error, Structured matrix pencil, Dissipative Hamiltonian system, H_∞ control, Linear quadratic optimal control.

AMS subject classifications. 93D20, 93D09, 65F15, 15A21, 15A22.

1. Introduction. In this paper, we consider the perturbation theory, in particular the calculation of structured backward errors, for eigenvalues and eigenvectors of structured matrix pencils $L(z)$ of the form

$$(1.1) \quad L(z) = M + zN := \begin{bmatrix} 0 & J - R & B \\ (J - R)^H & Q & 0 \\ B^H & 0 & S \end{bmatrix} + z \begin{bmatrix} 0 & E & 0 \\ -E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

where $J, R, E, Q \in \mathbb{C}^{n,n}$, $B \in \mathbb{C}^{n,m}$ and $S \in \mathbb{C}^{m,m}$ satisfy $J^H = -J$, $R^H = R$, $E^H = E$, $Q^H = Q$, and $S^H = S > 0$, i.e., S is positive definite. These pencils are special cases of so-called *even pencils*, i.e., matrix pencils $P(z)$ satisfying $P(z) = P(-z)^H$; see, e.g., [21]. Even pencils with an additional block-structure as in (1.1) arise in optimal control and H_∞ control problems as well as in the passivity analysis of dynamical systems. For instance, if one considers the optimal control problem of minimizing the cost functional

$$\int_{t_0}^{\infty} x^H Q x + u^H S u \, dt$$

subject to the constraint

$$(1.2) \quad E\dot{x} = Ax + Bu, \quad x(t_0) = x^0,$$

then it is well known (see [20, 23]) that the optimal solution is associated with the deflating subspace of a pencil of the form (1.1) associated with the finite eigenvalues in the open left half plane. If there exist exactly

*Received by the editors on December 21, 2017. Accepted for publication on September 19, 2018. Handling Editor: Françoise Tisseur. Corresponding Author: Volker Mehrmann.

[†]Institut für Mathematik, MA 4-5 TU Berlin, Str. d. 17. Juni 136, D-10623 Berlin, Germany (mehl@math.tu-berlin.de, mehrmann@math.tu-berlin.de). C. Mehl and V. Mehrmann gratefully acknowledge support from Einstein Center ECMath via project SE3: Stability analysis of power networks and power network models. V. Mehrmann also acknowledges support Deutsche Forschungsgemeinschaft through CRC 910 *Control of Self-Organizing Nonlinear Systems* via project A02: Analysis and computation of stability exponents for delay differential-algebraic equations.

[‡]Department of Mathematics, Indian Institute of Technology Delhi, Hauz Khas, New Delhi-110016, India (punit.sharma@maths.iitd.ac.in).

n eigenvalues in the open left half plane then this deflating subspace is an *extended Lagrangian subspace*. (For other applications in passivity analysis and robust control, see [7].) Note that for general descriptor systems we need not have that $E = E^H$. However, if this is not the case then we can just carry out the polar decomposition (see [15]) to obtain $E = U\tilde{E}$ with U unitary and $\tilde{E} = \tilde{E}^H$. Multiplying equation (1.2) from the left with U^H we obtain a new system that has the desired property $E = E^H$, so w.l.o.g. we assume that $E = E^H$ and then partition $A = J - R$ into its skew-symmetric and symmetric part. Note that the condition $E = E^H$ holds by assumption if (1.2) is a *port-Hamiltonian descriptor system*; see [5, 27]. In this case, we furthermore have that $R \geq 0$, i.e., it is positive semidefinite.

The solution of the optimal control problem becomes highly ill-conditioned when eigenvalues are close to the imaginary axis and the solution usually ceases to exist when the eigenvalues are on the imaginary axis [6, 11]. When eigenvalues on the imaginary axis exist then it is an important question to find small perturbations to the system (1.2) or the pencil (1.1) that remove the eigenvalues from the imaginary axis [4, 13]. These questions motivate the principle aims of this paper to determine backward errors associated with eigenvalues on the imaginary axis of pencils of the form (1.1). We will consider in this paper the special case of pencils with $Q = 0$, which arises in optimal control without state weighting, and in the context of passivity analysis [12, 13]. Thus, we will consider a pencil of the form

$$(1.3) \quad L(z) = M + zN := \begin{bmatrix} 0 & J - R & B \\ (J - R)^H & 0 & 0 \\ B^H & 0 & S \end{bmatrix} + z \begin{bmatrix} 0 & E & 0 \\ -E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Unfortunately many of our results do not carry over easily to the case $Q \neq 0$ where the perturbation theory becomes much more involved and highly technical.

In the following, $\|\cdot\|$ denotes the spectral norm of a vector or a matrix and $\|A\|_F$ denotes the Frobenius norm of a matrix A . $\text{Herm}(n)$ and $\text{SHerm}(n)$ respectively denote the set of Hermitian and skew-Hermitian matrices of size n . By $i\mathbb{R}$ we denote the set of nonzero purely imaginary numbers, i.e., $i\mathbb{R} = \{i\alpha \mid \alpha \in \mathbb{R} \setminus \{0\}\}$, and by I_n the identity matrix of size n . For a matrix A we write $A = 0$ if each entry of A is equal to zero.

The sensitivity analysis of eigenvalues and eigenvalue/eigenvector pairs (in the following, called eigenpairs) of matrix pencils and matrix polynomials with various structures has recently received a lot of attention; see, e.g., [1, 2, 3, 16, 18, 25]. In particular, backward error formulas for structured matrix pencils and polynomials with respect to structure preserving perturbations have been obtained in [1, 2] and in [8, 9], respectively.

For pencils of the form (1.3), if the structure of the pencil is ignored, then for a given pair $(\lambda, x) \in \mathbb{C} \times (\mathbb{C}^{2n+m} \setminus \{0\})$ the *eigenpair backward error* is defined as

$$\eta(L, \lambda, x) = \inf \left\{ \left\| \begin{bmatrix} \Delta_M & \Delta_N \end{bmatrix} \right\|_F \mid \Delta_M, \Delta_N \in \mathbb{C}^{2n+m, 2n+m}, ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0 \right\}.$$

It can be interpreted as the Frobenius norm of the smallest perturbation that makes (λ, x) being an eigenpair of the perturbed pencil. Minimizing this expression over all $(\lambda, x) \in (i\mathbb{R}) \times (\mathbb{C}^{2n+m})$ we obtain the distance of $L(z)$ to the next pencil having eigenvalues on the imaginary axis and thus, the passivity radius of $L(z)$; see [14, 24]. If the even structure of the pencil is taken into account, then a structured eigenpair backward

error with respect to structure-preserving perturbations can be defined as

$$\eta^{\text{even}}(L, \lambda, x) = \inf \left\{ \|\begin{bmatrix} \Delta_M & \Delta_N \end{bmatrix}\|_F \mid \Delta_M \in \text{Herm}(2n+m), \Delta_N \in \text{SHerm}(2n+m), \right. \\ \left. ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0 \right\}.$$

Clearly, we have $\eta(L, \lambda, x) \leq \eta^{\text{even}}(L, \lambda, x)$. In fact, for a given $(\lambda, x) \in \mathbb{C} \times (\mathbb{C}^{2n+m} \setminus \{0\})$, it is well known by [3, Theorem 4.6] that

$$(1.4) \quad \eta(L, \lambda, x) = \frac{\|L(\lambda)x\|}{\|x\|\sqrt{1+|\lambda|^2}},$$

and by [1, Theorem 3.3.7] that

$$(1.5) \quad \eta^{\text{even}}(L, \lambda, x) = \sqrt{\frac{2\|x\|^2\|L(\lambda)x\|^2 - |x^H L(\lambda)x|^2}{\|x\|^4(1+|\lambda|^2)}}.$$

However, both formulas ignore the special block-structure of the pencil $L(z)$, in particular the zero structure and the definiteness of the matrix S , and as we will show in this paper, eigenpair backward errors with respect to perturbations that preserve the block-structure and possibly also the symmetry-structure may be significantly larger than the more generally obtained backward errors $\eta(L, \lambda, x)$ and $\eta^{\text{even}}(L, \lambda, x)$.

This is, in particular, the case when only one or two blocks are perturbed, while others are unperturbed, a situation that arises in many applications, e.g. when E is the incidence matrix of a network [10], in the case of semi-explicit differential-algebraic equations [19] where E is block-diagonal with an identity and a zero block, when J is the structure matrix in a port-Hamiltonian system [27], or when the weight matrix is just a scalar multiple of the identity as is common in optimal control problems for partial differential equations [26].

We will mainly consider complex backward errors. In some situations, the corresponding minimal-norm perturbations turn out to be real if the original pencil was real to start with. In those cases, we easily obtain a corresponding result on real backward errors which we will explicitly state. In other situations, however, this is not the case and the techniques developed in this paper cannot be used to compute the corresponding real backward errors. In those cases, the development of real structure-preserving backward errors remains a challenging open problem.

The remainder of this paper is organized as follows. In Section 2, we review some minimal norm mapping problems. In Section 3, we introduce a terminology and define block- and symmetry-structure-preserving eigenpair or eigenvalue backward errors for pencils $L(z)$ of the form (1.3). These backward errors are computed while perturbing any two, three or all of the blocks J, R, E or B in Sections 4, 5 and 6, respectively. The significance of these block- and symmetry-structure-preserving backward errors over $\eta(L, \lambda, x)$ and $\eta^{\text{even}}(L, \lambda, x)$ is shown via some numerical examples in Section 7.

2. Preliminaries. An important tool for the computation of backward errors are minimal norm solutions to mapping problems. In this section, we will review some of these results and restate them in a form that we need in the following sections.

The solution to the *skew-Hermitian mapping problem*, i.e., to find $\Delta \in \text{SHerm}(n)$ that maps a matrix $X \in \mathbb{C}^{n,k}$ to $Y \in \mathbb{C}^{n,k}$, is well known; see, e.g., [1], where also solutions that are minimal with respect to

the spectral and the Frobenius norms are characterized. The following theorem is a particular case of [1, Theorem 2.2.3].

THEOREM 2.1. *Let $X, Y \in \mathbb{C}^{n,k}$. Then there exists $\Delta \in \text{SHerm}(n)$ satisfying $\Delta X = Y$ if and only if $YX^\dagger X = Y$ and $Y^H X = -X^H Y$. If the latter conditions are satisfied, then*

$$\min \{ \|\Delta\|_F \mid \Delta \in \text{SHerm}(n), \Delta X = Y \} = \sqrt{2\|YX^\dagger\|_F^2 - \text{trace}(YX^\dagger(YX^\dagger)^H(XX^\dagger))}$$

and the unique minimum is attained for

$$\hat{\Delta} = YX^\dagger - (YX^\dagger)^H - (X^\dagger)^H X^H YX^\dagger.$$

The second mapping problem that we will need is the following; see [17, Theorem 2], [22, Theorem 2.1].

THEOREM 2.2. *Let $u \in \mathbb{C}^m \setminus \{0\}$, $r \in \mathbb{C}^n$, $w \in \mathbb{C}^n \setminus \{0\}$ and $s \in \mathbb{C}^m$. Define*

$$\mathcal{S} = \{ \Delta \in \mathbb{C}^{n,m} \mid \Delta u = r, \Delta^H w = s \}.$$

Then $\mathcal{S} \neq \emptyset$ if and only if $u^H s = r^H w$. If the latter condition is satisfied, then

$$\hat{\Delta} = \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} - \frac{(s^H u)wu^H}{\|w\|^2\|u\|^2}$$

is the unique matrix such that $\hat{\Delta}u = r$ and $\hat{\Delta}^H w = s$, and

$$\inf_{\Delta \in \mathcal{S}} \|\Delta\|_F = \|\hat{\Delta}\|_F = \sqrt{\frac{\|r\|^2}{\|u\|^2} + \frac{\|s\|^2}{\|w\|^2} - \frac{|s^H u|^2}{\|w\|\|u\|}}.$$

Moreover,

$$\inf_{\Delta \in \mathcal{S}} \|\Delta\| = \max \left\{ \frac{\|r\|}{\|u\|}, \frac{\|s\|}{\|w\|} \right\}.$$

The following result (see [22, Remark 2.1]) gives a real minimal Frobenius norm solution of the mapping problem considered in Theorem 2.2.

THEOREM 2.3. *Let $u \in \mathbb{C}^m$, $r \in \mathbb{C}^n$, $w \in \mathbb{C}^n$ and $s \in \mathbb{C}^m$ be such that $\text{rank}([u \ \bar{u}]) = 2$ and $\text{rank}([w \ \bar{w}]) = 2$ and define*

$$\mathcal{S}_{\mathbb{R}} = \{ \Delta \in \mathbb{R}^{n,m} \mid \Delta u = r, \Delta^H w = s \}.$$

Then $\mathcal{S}_{\mathbb{R}} \neq \emptyset$ if and only if $u^H s = r^H w$ and $u^T s = r^T w$. If the latter conditions are satisfied, then

$$\inf_{\Delta \in \mathcal{S}_{\mathbb{R}}} \|\Delta\|_F = \|\tilde{\Delta}\|,$$

where

$$\tilde{\Delta} = [r \ \bar{r}][u \ \bar{u}]^\dagger + ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H - ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H [u \ \bar{u}][u \ \bar{u}]^\dagger.$$

We mention that the form of the minimal norm perturbation given in [22, Remark 2.4] slightly differs from the one given here, because in [22] it was presented using real and imaginary parts rather than complex vectors and their complex conjugates.

3. Structured eigenpair backward errors. In this section, we consider structured matrix pencils $L(z)$ of the form (1.3). We use the results on the mapping problems from the previous section to estimate structure-preserving backward errors for eigenvalues λ or eigenpairs (λ, x) of $L(z)$, while perturbing only certain block entries of $L(z)$ for the case when λ is purely imaginary and S is definite. To distinguish between different cases, we introduce a terminology for perturbations $\Delta_M + z\Delta_N$ of the pencil $L(z) = M + zN$ that affect only some of the blocks J, R, E, B of $L(z)$. For example, suppose that only the blocks J and E in $L(z)$ are subject to perturbations. Then the corresponding perturbations to M and N are given by

$$(3.1) \quad \Delta_M = \begin{bmatrix} 0 & \Delta_J & 0 \\ \Delta_J^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad \Delta_N = \begin{bmatrix} 0 & \Delta_E & 0 \\ -\Delta_E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

where $\Delta_J, \Delta_E \in \mathbb{C}^{n,n}$. For $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$ we then define

- 1) the *block-structure-preserving eigenpair backward error* $\eta^{\mathcal{B}}(J, E, \lambda, x)$ with respect to perturbations only to J and E by

$$(3.2) \quad \eta^{\mathcal{B}}(J, E, \lambda, x) = \inf \left\{ \|\begin{bmatrix} \Delta_J & \Delta_E \end{bmatrix}\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\},$$

where \mathcal{B} denotes the set of all pencils $\Delta_M + z\Delta_N$ as in (3.1) with $\Delta_J, \Delta_E \in \mathbb{C}^{n,n}$;

- 2) the *symmetry-structure-preserving eigenpair backward error* $\eta^{\mathcal{S}}(J, E, \lambda, x)$ with respect to structure-preserving perturbations only to J and E by

$$(3.3) \quad \eta^{\mathcal{S}}(J, E, \lambda, x) = \inf \left\{ \|\begin{bmatrix} \Delta_J & \Delta_E \end{bmatrix}\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\},$$

where \mathcal{S} denotes the set of all pencils $\Delta_M + z\Delta_N$ as in (3.1) with $\Delta_J \in \text{SHerm}(n)$ and $\Delta_E \in \text{Herm}(n)$.

For a given $\lambda \in \mathbb{C}$, we also define the *block-structure-preserving* and *symmetry-structure-preserving eigenvalue backward errors* $\eta^{\mathcal{B}}(J, E, \lambda)$ and $\eta^{\mathcal{S}}(J, E, \lambda)$, respectively, by

$$\eta^{\mathcal{B}}(J, E, \lambda) := \inf_{x \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^{\mathcal{B}}(J, E, \lambda, x) \quad \text{and} \quad \eta^{\mathcal{S}}(J, E, \lambda) := \inf_{x \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^{\mathcal{S}}(J, E, \lambda, x).$$

For other combinations of perturbations to the blocks J, R, E, B in $L(z)$, the corresponding sets \mathcal{B} and \mathcal{S} as well as the block- and symmetry-structure-preserving eigenpair or eigenvalue backward errors are defined analogously.

4. Perturbation in any two of the blocks J, R, E and B . In this section, we compute block- and symmetry-structure-preserving backward errors of $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$ as approximate eigenpair, resp. eigenvalue of the pencil $L(z)$ defined in (1.3) while perturbing any two of the blocks J, R, E , or B at a time. As we have discussed in the introduction, it is a common situation in many applications that not all blocks are perturbed. Although restrictions in the perturbation structure are more common in some blocks than in the others, for completeness we also discuss several other perturbation combinations.

4.1. Perturbation only in J and E . Let $L(z)$ be a pencil as in (1.3) and furthermore let $(\lambda, x) \in \mathbb{C} \times (\mathbb{C}^{2n+m} \setminus \{0\})$. Suppose that only the blocks J and E of $L(z)$ are subject to perturbations. Then by Section 3, \mathcal{B} is the set of all pencils $\Delta L(z) = \Delta_M + z\Delta_N$, where Δ_M and Δ_N have the block structure as in (3.1), and \mathcal{S} is the set of all pencils from \mathcal{B} where in addition we have $\Delta_J^H = -\Delta_J$ and $\Delta_E^H = \Delta_E$ for the blocks in (3.1).

531 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

The corresponding block-structure- and symmetry-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(J, E, \lambda, x)$ and $\eta^{\mathcal{S}}(J, E, \lambda, x)$ are defined by (3.2) and (3.3), respectively. We first discuss under which conditions these backward errors are finite.

REMARK 4.1. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then for any $\Delta_J, \Delta_E \in \mathbb{C}^{n,n}$ and corresponding $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$(4.1) \quad (\Delta_J + \lambda\Delta_E)x_2 = (J - R + \lambda E)x_2 + Bx_3,$$

$$(4.2) \quad (\Delta_J + \lambda\Delta_E)^H x_1 = (-J - R - \lambda E)x_1,$$

$$(4.3) \quad 0 = B^H x_1 + Sx_3,$$

i.e., $\eta^{\mathcal{B}}(J, E, \lambda, x)$ is finite if and only if there exist matrices Δ_J and Δ_E such that these equations are satisfied.

In the next lemma, we present conditions that are equivalent to the existence of matrices Δ_J and Δ_E that satisfy the first two of the three equations in Remark 4.1.

LEMMA 4.2. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Furthermore, set $r := (J - R + \lambda E)x_2 + Bx_3$ and $s := (-J - R - \lambda E)x_1$. Then the following statements are equivalent.

- 1) There exist $\Delta_J \in \mathbb{C}^{n,n}$ and $\Delta_E \in \mathbb{C}^{n,n}$ satisfying (4.1) and (4.2).
- 2) There exists $\Delta \in \mathbb{C}^{n,n}$ such that $\Delta x_2 = r$ and $\Delta^H x_1 = s$.
- 3) The identity $x_3^H B^H x_1 = 0$ is satisfied.

Moreover, we have

$$(4.4) \quad \begin{aligned} & \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_J, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (4.1) and (4.2)} \right\} \\ &= \inf \left\{ \frac{\|\Delta\|_F^2}{1 + |\lambda|^2} \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}. \end{aligned}$$

Proof. “1) \Rightarrow 2)”: Let $\Delta_J \in \mathbb{C}^{n,n}$ and $\Delta_E \in \mathbb{C}^{n,n}$ be such that (4.1) and (4.2) are satisfied. Then by setting $\Delta = \Delta_J + \lambda\Delta_E$ we get $\Delta x_2 = r$, $\Delta^H x_1 = s$ which shows 2). Furthermore, using the Cauchy-Schwarz inequality (in \mathbb{R}^2), we obtain

$$\|\Delta\|_F^2 \leq (\|\Delta_J\|_F + |\lambda| \|\Delta_E\|_F)^2 \leq (1 + |\lambda|^2)(\|\Delta_J\|_F^2 + \|\Delta_E\|_F^2).$$

This implies

$$\begin{aligned} & \inf \left\{ \frac{\|\Delta\|_F^2}{1 + |\lambda|^2} \mid \Delta_J, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (4.1) and (4.2)}, \Delta = \Delta_J + \lambda\Delta_E \right\} \\ & \leq \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_J, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (4.1) and (4.2)} \right\}, \end{aligned}$$

and thus,

$$(4.5) \quad \begin{aligned} & \inf \left\{ \frac{\|\Delta\|_F^2}{1 + |\lambda|^2} \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\} \\ & \leq \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_J, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (4.1) and (4.2)} \right\}, \end{aligned}$$

which yields “ \geq ” in (4.4).

“2) \Rightarrow 1)”: Conversely, suppose that $\Delta \in \mathbb{C}^{n,n}$ satisfies $\Delta x_2 = r$ and $\Delta^H x_1 = s$. Then by setting $\Delta_J = \frac{\Delta}{1+|\lambda|^2}$ and $\Delta_E = \frac{\bar{\lambda}\Delta}{1+|\lambda|^2}$ we get $\Delta_J + \lambda\Delta_E = \Delta$, and hence, Δ_J and Δ_E satisfy (4.1) and (4.2) which proves 1). Furthermore, we obtain

$$\|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 = \frac{\|\Delta\|_F^2}{(1+|\lambda|^2)^2} + \frac{|\lambda|^2\|\Delta\|_F^2}{(1+|\lambda|^2)^2} = \frac{\|\Delta\|_F^2}{1+|\lambda|^2}.$$

This implies

$$\begin{aligned} & \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s, \Delta_J = \frac{\Delta}{1+|\lambda|^2}, \Delta_E = \frac{\bar{\lambda}\Delta}{1+|\lambda|^2} \right\} \\ &= \inf \left\{ \frac{\|\Delta\|_F^2}{1+|\lambda|^2} \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}, \end{aligned}$$

and hence,

$$\begin{aligned} & \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_J, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (4.1) and (4.2)} \right\} \\ & \leq \inf \left\{ \frac{\|\Delta\|_F^2}{1+|\lambda|^2} \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}, \end{aligned}$$

which proves “ \leq ” in (4.4).

“2) \Leftrightarrow 3)”: This follows from Theorem 2.2, because there exists $\Delta \in \mathbb{C}^{n,n}$ satisfying $\Delta x_2 = r$ and $\Delta^H x_1 = s$ if and only if $x_2^H s = r^H x_1$. Since λ is purely imaginary, this latter equation is equivalent to $x_3^H B^H x_1 = 0$. \square

THEOREM 4.3. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and set $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = -(J + R + \lambda E)x_1$. Then $\eta^{\mathcal{B}}(J, E, \lambda, x)$ is finite if and only if $x_3 = 0$ and $B^H x_1 = 0$. If the latter conditions hold then*

$$(4.6) \quad \eta^{\mathcal{B}}(J, E, \lambda, x) = \frac{\|\hat{\Delta}\|_F}{\sqrt{1+|\lambda|^2}} \quad \text{and} \quad \eta^{\mathcal{B}}(J, E, \lambda) = \frac{\sigma_{\min}(J - R + \lambda E)}{\sqrt{1+|\lambda|^2}},$$

where $\hat{\Delta}$ is given by

$$\hat{\Delta} = \begin{cases} \frac{rx_2^H}{\|x_2\|^2} & \text{if } x_1 = 0, \\ \frac{x_1 s^H}{\|x_1\|^2} & \text{if } x_2 = 0, \\ \frac{rx_2^H}{\|x_2\|^2} + \frac{x_1 s^H}{\|x_1\|^2} \left(I_n - \frac{x_2 x_2^H}{\|x_2\|^2} \right) & \text{otherwise.} \end{cases}$$

Proof. Combining Remark 4.1 and Lemma 4.2, we obtain that $\eta^{\mathcal{B}}(J, E, \lambda, x)$ is finite if and only if x satisfies $x_3^H B^H x_1 = 0$ and $B^H x_1 + Sx_3 = 0$, or equivalently, $x_3 = 0$ and $B^H x_1 = 0$, since S is definite. Thus,

533 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

assume that x satisfies $x_3 = 0$ and $B^H x_1 = 0$. Then, we obtain

$$\begin{aligned}
 \eta^{\mathcal{B}}(J, E, \lambda, x) &= \inf \left\{ \|\Delta_J \Delta_E\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\} \\
 &= \inf \left\{ \|\Delta_J \Delta_E\|_F \mid \Delta_J, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (4.1) and (4.2)} \right\} \\
 &= \inf \left\{ \frac{\|\Delta\|_F}{\sqrt{1+|\lambda|^2}} \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\} \\
 (4.7) \quad &= \frac{1}{\sqrt{1+|\lambda|^2}} \inf \left\{ \|\Delta\|_F \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\},
 \end{aligned}$$

where the second last equality is due to Lemma 4.2. Thus, the formula for $\eta^{\mathcal{B}}(J, E, \lambda, x)$ in (4.6) follows from Theorem 2.2 for the case $x_1, x_2 \neq 0$ and for the case $x_1 = 0$ or $x_2 = 0$ it is straightforward. (Indeed, in the case $x_1 = 0$, any matrix Δ with $\Delta x_2 = r$ satisfies $\|\Delta\|_F \geq \frac{\|r\|}{\|x_2\|}$ and $\hat{\Delta} = \frac{rx_2^H}{\|x_2\|^2}$ is a matrix for which equality is attained. The case $x_2 = 0$ is analogous.)

Next we will prove the formula for $\eta^{\mathcal{B}}(J, E, \lambda)$ in (4.6). To this end, let

$$\mathcal{M} := \left\{ y = \begin{bmatrix} y_1^T & y_2^T & 0 \end{bmatrix} \in \mathbb{C}^{2n+m} \mid y_1, y_2 \in \mathbb{C}^n, (y_1, y_2) \neq (0, 0), B^H y_1 = 0 \right\}.$$

Then, we obtain

$$\begin{aligned}
 (\sqrt{1+|\lambda|^2}) \cdot \eta^{\mathcal{B}}(J, E, \lambda) &= (\sqrt{1+|\lambda|^2}) \cdot \inf_{y \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^{\mathcal{B}}(J, E, \lambda, y) \\
 &= \inf_{y \in \mathcal{M}} \inf \left\{ \|\Delta\|_F \mid \Delta \in \mathbb{C}^{n,n}, \Delta y_2 = (J - R + \lambda E)y_2, \Delta^H y_1 = -(J + R + \lambda E)y_1 \right\} \\
 (4.8) \quad &\geq \inf_{y \in \mathcal{M}} \inf \left\{ \|\Delta\| \mid \Delta \in \mathbb{C}^{n,n}, \Delta y_2 = (J - R + \lambda E)y_2, \Delta^H y_1 = -(J + R + \lambda E)y_1 \right\},
 \end{aligned}$$

where the second equality is due to (4.7) and the inequality in the last line follows from the fact that for any $\Delta \in \mathbb{C}^{n,n}$, we have $\|\Delta\| \leq \|\Delta\|_F$. Defining

$$\mu := \inf_{y \in \mathcal{M}} \inf \left\{ \|\Delta\| \mid \Delta \in \mathbb{C}^{n,n}, \Delta y_2 = (J - R + \lambda E)y_2, \Delta^H y_1 = -(J + R + \lambda E)y_1 \right\},$$

we get by applying Theorem 2.2 for the case of the spectral norm that

$$(4.9) \quad \mu = \inf_{y \in \mathcal{M}} \max \left\{ \frac{\|(J - R + \lambda E)^H y_1\|}{\|y_1\|}, \frac{\|(J - R + \lambda E)y_2\|}{\|y_2\|} \right\}$$

$$(4.10) \quad = \min \left\{ \inf_{y_1 \in \mathbb{C}^n \setminus \{0\}, B^H y_1 = 0} \frac{\|(J - R + \lambda E)^H y_1\|}{\|y_1\|}, \inf_{y_2 \in \mathbb{C}^n \setminus \{0\}} \frac{\|(J - R + \lambda E)y_2\|}{\|y_2\|} \right\},$$

where in (4.9) we interpret the undefined expressions $\frac{0}{0}$ that occur in the cases $y_1 = 0$ or $y_2 = 0$ as being equal to zero. Let the columns of $U = [u_1, \dots, u_k] \in \mathbb{C}^{n,k}$ form an orthonormal basis of $\text{null}(B^H)$. Then

$$\begin{aligned}
 \inf_{y_1 \in \mathbb{C}^n \setminus \{0\}, B^H y_1 = 0} \frac{\|(J - R + \lambda E)^H y_1\|^2}{\|y_1\|^2} &= \inf_{y_1 \in \text{null}(B^H) \setminus \{0\}} \frac{\|(J - R + \lambda E)^H y_1\|^2}{\|y_1\|^2} \\
 &= \inf_{\alpha \in \mathbb{C}^k \setminus \{0\}} \frac{\|(J - R + \lambda E)^H U \alpha\|^2}{\|\alpha\|^2} \\
 (4.11) \quad &= \left(\sigma_{\min}((J - R + \lambda E)^H U) \right)^2.
 \end{aligned}$$

By inserting (4.11) in (4.10), we get

$$(4.12) \quad \begin{aligned} \mu &= \min \{ \sigma_{\min}((J - R + \lambda E)^H), \sigma_{\min}((J - R + \lambda E)^H U) \} \\ &= \sigma_{\min}((J - R + \lambda E)^H) = \sigma_{\min}(J - R + \lambda E), \end{aligned}$$

Using the value of μ from (4.12), we show that equality holds in (4.8) by constructing Δ such that $\|\Delta\| = \|\Delta\|_F = \mu$. For this, let u and v , respectively, be unit left and right singular vectors of $(J - R + \lambda E)$ corresponding to the singular value $\sigma^* := \sigma_{\min}(J - R + \lambda E)$ and consider $\tilde{\Delta} := \sigma^* uv^H$. Then, clearly $\|\tilde{\Delta}\| = \|\tilde{\Delta}\|_F = \sigma^*$ as $\tilde{\Delta}$ is of rank one, and

$$\tilde{\Delta}v = \sigma^*u = (J - R + \lambda E)v \quad \text{and} \quad \tilde{\Delta}^H u = \sigma^*v = (J - R + \lambda E)^H u.$$

Thus, we have equality in (4.8), i.e.,

$$\eta^{\mathcal{B}}(J, E, \lambda) = \frac{\mu}{\sqrt{1 + |\lambda|^2}} = \frac{\|\tilde{\Delta}\|_F}{\sqrt{1 + |\lambda|^2}} = \frac{\sigma_{\min}(J - R + \lambda E)}{\sqrt{1 + |\lambda|^2}}$$

which finishes the proof. \square

Next we aim to compute the symmetry-structure-preserving eigenpair error $\eta^{\mathcal{S}}(J, E, \lambda, x)$, i.e., when we have $\Delta_J^H = -\Delta_J$ and $\Delta_E^H = \Delta_E$ in the pencils $L(z) = \Delta_M + z\Delta_N \in \mathcal{S}$. We start with a criterion for the finiteness of the eigenpair error, where we focus on the case that λ is on the imaginary axis.

REMARK 4.4. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then using $\Delta_J^H = -\Delta_J$ and $\Delta_E^H = \Delta_E$ and also the fact that λ is purely imaginary, the equations (4.1)–(4.3) take the form

$$\begin{aligned} (\Delta_J + \lambda\Delta_E)x_2 &= (J - R + \lambda E)x_2 + Bx_3, \\ (-\Delta_J - \lambda\Delta_E)x_1 &= (-J - R - \lambda E)x_1, \\ 0 &= B^H x_1 + Sx_3. \end{aligned}$$

Thus, combining the first two of these equations, we find that $\eta^{\mathcal{S}}(J, E, \lambda, x)$ is finite if and only if there exist $\Delta_J \in \text{SHerm}(n)$ and $\Delta_E \in \text{Herm}(n)$ such that the equations

$$(4.13) \quad \begin{aligned} (\Delta_J + \lambda\Delta_E) \begin{bmatrix} x_2 & x_1 \end{bmatrix} &= \begin{bmatrix} (J - R + \lambda E)x_2 + Bx_3 & (J + R + \lambda E)x_1 \end{bmatrix}, \\ 0 &= B^H x_1 + Sx_3 \end{aligned}$$

are satisfied.

We start with a lemma that contains equivalent conditions for equation (4.13) to be satisfied.

LEMMA 4.5. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, and define

$$X = \begin{bmatrix} x_2 & x_1 \end{bmatrix} \quad \text{and} \quad Y = \begin{bmatrix} (J - R + \lambda E)x_2 + Bx_3 & (J + R + \lambda E)x_1 \end{bmatrix}.$$

Then the following statements are equivalent.

- 1) There exist $\Delta_J \in \text{SHerm}(n)$ and $\Delta_E \in \text{Herm}(n)$ satisfying (4.13).
- 2) There exists $\Delta \in \text{SHerm}(n)$ such that $\Delta X = Y$.

3) X and Y satisfy $Y^H X = -X^H Y$ and $Y X^\dagger X = Y$.

Moreover, we have

$$(4.14) \quad \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_J \in \text{SHerm}(n), \Delta_E \in \text{Herm}(n) \text{ satisfying (4.13)} \right\} \\ = \inf \left\{ \frac{\|\Delta\|_F^2}{1 + |\lambda|^2} \mid \Delta \in \text{SHerm}(n), \Delta X = Y \right\}.$$

Proof. “1) \Rightarrow 2)”: Let $\Delta_J \in \text{SHerm}(n)$ and $\Delta_E \in \text{Herm}(n)$ be such that they satisfy (4.13), then by setting $\Delta = \Delta_J + \lambda \Delta_E$ we get $\Delta X = Y$, and $\Delta \in \text{SHerm}(n)$ as $\lambda \in i\mathbb{R}$. The inequality “ \geq ” in (4.14) then follows by the same arguments as in “1) \Rightarrow 2)” in the proof of Lemma 4.2.

“2) \Rightarrow 1)”: Conversely, let $\Delta \in \text{SHerm}(n)$ be such that $\Delta X = Y$. Then, setting

$$\Delta_J = \frac{\Delta}{1 + |\lambda|^2} \quad \text{and} \quad \Delta_E = \frac{\bar{\lambda} \Delta}{1 + |\lambda|^2},$$

we obtain $(\Delta_J + \lambda \Delta_E)X = Y$ as well as $\Delta_J \in \text{SHerm}(n)$ and $\Delta_E \in \text{Herm}(n)$, since $\lambda \in i\mathbb{R}$. Again, the proof “ \leq ” in (4.14) follows by arguments similar to those in the part “2) \Rightarrow 1)” in the proof of Lemma 4.2.

“2) \Leftrightarrow 3)”: This follows immediately by Theorem 2.1. \square

THEOREM 4.6. Let $L(z)$ be a pencil defined as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and set

$$X = \begin{bmatrix} x_2 & x_1 \end{bmatrix} \quad \text{and} \quad Y = \begin{bmatrix} (J - R + \lambda E)x_2 + Bx_3 & (J + R + \lambda E)x_1 \end{bmatrix}.$$

Then $\eta^S(J, E, \lambda, x)$ is finite if and only if $Y^H X = -X^H Y$, $Y X^\dagger X = Y$ and $B^H x_1 + Sx_3 = 0$. If the three latter conditions are satisfied, then

$$(4.15) \quad \eta^S(J, E, \lambda, x) = \sqrt{\frac{1}{1 + |\lambda|^2} \left(2\|Y X^\dagger\|_F^2 - \text{trace}(Y X^\dagger (Y X^\dagger)^H X X^\dagger) \right)}.$$

Proof. Combining Remark 4.4 and Lemma 4.5 it follows that $\eta^S(J, E, \lambda, x)$ is finite if and only if x satisfies

$$Y^H X = -X^H Y, \quad Y X^\dagger X = Y \quad \text{and} \quad B^H x_1 + Sx_3 = 0.$$

In the following, let us assume that these conditions on x are satisfied. Then we obtain

$$\eta^S(J, E, \lambda, x) = \inf \left\{ \|\Delta_J \ \Delta_E\|_F \mid \Delta_J \in \text{SHerm}(n), \Delta_E \in \text{Herm}(n) \text{ satisfy (4.13)} \right\} \\ = \frac{1}{\sqrt{1 + |\lambda|^2}} \cdot \inf \left\{ \|\Delta\|_F \mid \Delta \in \text{SHerm}(n), \Delta X = Y \right\},$$

where the last equality is due to Lemma 4.5. Hence, (4.15) follows by using Theorem 2.1. \square

4.2. Perturbations only in R and E . In this section, we consider the case where only the blocks R and E in a pencil $L(z)$ as in (1.3) are perturbed. Let $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Then by the terminology outlined in Section 3, the block- and symmetry-structure-preserving eigenpair backward errors $\eta^B(R, E, \lambda, x)$ and $\eta^S(R, E, \lambda, x)$ are defined by

$$(4.16) \quad \eta^B(R, E, \lambda, x) = \inf \left\{ \|\Delta_R \ \Delta_E\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\},$$

and

$$(4.17) \quad \eta^S(R, E, \lambda, x) = \inf \left\{ \left\| [\Delta_R \ \Delta_E] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\},$$

respectively, where \mathcal{B} is the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with the block-structure

$$(4.18) \quad \Delta_M = \begin{bmatrix} 0 & -\Delta_R & 0 \\ -\Delta_R^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad \Delta_N = \begin{bmatrix} 0 & \Delta_E & 0 \\ -\Delta_E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

and $\Delta_R, \Delta_E \in \mathbb{C}^{n,n}$, while \mathcal{S} is the corresponding set of pencils $\Delta L(z) = \Delta_M + z\Delta_N$ as in (4.18) with $\Delta_R, \Delta_E \in \text{Herm}(n)$.

We highlight that in the case that only the block-structure is preserved, the perturbation matrices in (4.18) have exactly the same structure as the ones in (3.1), and hence, by following exactly the same lines as in the previous section, we obtain the following theorem which shows that the values of $\eta^B(R, E, \lambda, x)$, and also of $\eta^B(R, E, \lambda) := \inf_{x \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^B(R, E, \lambda, x)$ are equal to the corresponding values $\eta^B(J, E, \lambda, x)$ and $\eta^B(J, E, \lambda)$.

THEOREM 4.7. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and set $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = -(J + R + \lambda E)x_1$. Then $\eta^B(R, E, \lambda, x)$ is finite if and only if $x_3 = 0$ and $B^H x_1 = 0$. If the latter conditions hold then*

$$\eta^B(R, E, \lambda, x) = \eta^B(J, E, \lambda, x) = \frac{\|\hat{\Delta}\|_F}{\sqrt{1 + |\lambda|^2}},$$

and

$$\eta^B(R, E, \lambda) = \eta^B(J, E, \lambda) = \frac{\sigma_{\min}(J - R + \lambda E)}{\sqrt{1 + |\lambda|^2}},$$

where $\hat{\Delta}$ is given by

$$\hat{\Delta} = \begin{cases} \frac{rx_2^H}{\|x_2\|^2} & \text{if } x_1 = 0, \\ \frac{x_1 s^H}{\|x_1\|^2} & \text{if } x_2 = 0, \\ \frac{rx_2^H}{\|x_2\|^2} + \frac{x_1 s^H}{\|x_1\|^2} \left(I_n - \frac{x_2 x_2^H}{\|x_2\|^2} \right) & \text{otherwise.} \end{cases}$$

Proof. The proof is similar to the proof of Theorem 4.3. □

Next, we turn to the eigenpair backward error $\eta^S(R, E, \lambda, x)$ for purely imaginary $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T \in \mathbb{C}^{2n+m} \setminus \{0\}$. Note that in this case, $\Delta_R^H = \Delta_R$ and $\Delta_E^H = \Delta_E$. In particular, the perturbations now have a different symmetry structure than the corresponding ones from the previous section, so that we expect the backward error $\eta^S(R, E, \lambda, x)$ to differ from $\eta^S(J, E, \lambda, x)$. We start again with a criterion for the finiteness of $\eta^S(R, E, \lambda, x)$ and continue with a lemma giving equivalent conditions.

REMARK 4.8. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then using $\Delta_R^H = \Delta_R$ and $\Delta_E^H = \Delta_E$ and also the fact that λ is purely imaginary, we find that there exist $\Delta_R, \Delta_E \in \text{Herm}(n)$ and correspondingly $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{S}$ such

537 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

that $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$(4.19) \quad (-\Delta_R + \lambda \Delta_E)x_2 = (J - R + \lambda E)x_2 + Bx_3$$

$$(4.20) \quad (-\Delta_R + \lambda \Delta_E)^H x_1 = (-J - R - \lambda E)x_1$$

$$(4.21) \quad 0 = B^H x_1 + Sx_3.$$

Thus, $\eta^S(R, E, \lambda, x)$ is finite if and only if there exist $\Delta_R, \Delta_E \in \text{Herm}(n)$ such that (4.19)–(4.21) are satisfied.

LEMMA 4.9. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and let $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = (-J - R - \lambda E)x_1$. Then the following statements are equivalent.*

- 1) *There exist $\Delta_R, \Delta_E \in \text{Herm}(n)$ satisfying (4.19) and (4.20).*
- 2) *There exists $\Delta \in \mathbb{C}^{n,n}$ such that $\Delta x_2 = r$ and $\Delta^H x_1 = s$.*
- 3) *The identity $x_3^H B^H x_1 = 0$ is satisfied.*

Moreover, we have

$$(4.22) \quad \inf \left\{ \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_R, \Delta_E \in \text{Herm}(n) \text{ satisfy (4.19) and (4.20)} \right\} \\ = \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}.$$

Proof. “1) \Rightarrow 2)”: Let $\Delta_R, \Delta_E \in \text{Herm}(n)$ be such that they satisfy (4.19) and (4.20). Setting $\Delta = -\Delta_R + \lambda \Delta_E$, we get $\Delta x_2 = r$, $\Delta^H x_1 = s$. Also note that $-\Delta_R$ and $\lambda \Delta_E$ are the unique Hermitian and skew-Hermitian parts of Δ , respectively, i.e., $\Delta_R = -(\Delta + \Delta^H)/2$ and $\lambda \Delta_E = (\Delta - \Delta^H)/2$. This implies

$$\|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 = \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2$$

and

$$\inf \left\{ \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_R, \Delta_E \in \text{Herm}(n) \text{ satisfy (4.19) and (4.20)} \right\} \\ = \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta = -\Delta_R + \lambda \Delta_E, \Delta_R, \Delta_E \in \text{Herm}(n) \right. \\ \left. \text{satisfy (4.19) and (4.20)} \right\}.$$

Thus, we obtain

$$(4.23) \quad \inf \left\{ \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_R, \Delta_E \in \text{Herm}(n) \text{ satisfy (4.19) and (4.20)} \right\} \\ \geq \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}$$

which gives “ \geq ” in (4.22).

“2) \Rightarrow 1)”: Suppose that $\Delta \in \mathbb{C}^{n,n}$ is such that $\Delta x_2 = r$ and $\Delta^H x_1 = s$. Then, by setting $\Delta_R = -\frac{\Delta + \Delta^H}{2}$ and $\Delta_E = \frac{\lambda}{|\lambda|^2} \left(\frac{\Delta - \Delta^H}{2} \right)$, we get $\Delta_R, \Delta_E \in \text{Herm}(n)$ such that (4.19) and (4.20) are satisfied, because

$-\Delta_R + \lambda \Delta_E = \Delta$. Also, we have

$$\|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 = \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2$$

which implies

$$\begin{aligned} & \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\} \\ &= \inf \left\{ \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s, \Delta_R = -\frac{\Delta + \Delta^H}{2}, \Delta_E = \frac{\bar{\lambda}}{|\lambda|^2} \cdot \left(\frac{\Delta - \Delta^H}{2} \right) \right\} \end{aligned}$$

and hence

$$(4.24) \quad \begin{aligned} & \inf \left\{ \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 \mid \Delta_R, \Delta_E \in \text{Herm}(n) \text{ satisfying (4.19) and (4.20)} \right\} \\ & \leq \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta u = r, \Delta^H w = s \right\} \end{aligned}$$

which finishes the proof of (4.22).

“2) \Leftrightarrow 3)”: By Theorem 2.2, there exists $\Delta \in \mathbb{C}^{n,n}$ satisfying $\Delta x_2 = r$ and $\Delta^H x_1 = s$ if and only if $x_2^H s = r^H x_1$ which in turn is equivalent to $x_3^H B^H x_1 = 0$. \square

In contrast to Theorem 4.6 and 4.7, we only obtain bounds for the symmetry-structure-preserving eigenpair backward error $\eta^S(R, E, \lambda, x)$.

THEOREM 4.10. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ so that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, and set $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = -(J + R + \lambda E)x_1$. Then $\eta^S(R, E, \lambda, x)$ is finite if and only if $x_3 = 0$ and $B^H x_1 = 0$. If the latter conditions are satisfied, then*

$$(4.25) \quad \|\hat{\Delta}\|_F \leq \eta^S(R, E, \lambda, x) \leq \sqrt{\left\| \frac{\hat{\Delta} + \hat{\Delta}^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\hat{\Delta} - \hat{\Delta}^H}{2} \right\|_F^2} \quad \text{if } |\lambda| \leq 1$$

and

$$(4.26) \quad \frac{\|\hat{\Delta}\|_F}{|\lambda|} \leq \eta^S(R, E, \lambda, x) \leq \sqrt{\left\| \frac{\hat{\Delta} + \hat{\Delta}^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\hat{\Delta} - \hat{\Delta}^H}{2} \right\|_F^2} \quad \text{if } |\lambda| \geq 1,$$

where $\hat{\Delta}$ is given by

$$\hat{\Delta} = \begin{cases} \frac{rx_2^H}{\|x_2\|^2} & \text{if } x_1 = 0, \\ \frac{x_1 s^H}{\|x_1\|^2} & \text{if } x_2 = 0, \\ \frac{rx_2^H}{\|x_2\|^2} + \frac{x_1 s^H}{\|x_1\|^2} \left(I_n - \frac{x_2 x_2^H}{\|x_2\|^2} \right) & \text{otherwise.} \end{cases}$$

Proof. Combining Remark 4.8 and Lemma 4.9, we obtain that $\eta^S(R, E, \lambda, x)$ is finite if and only if $x_3^H B^H x_1 = 0$ and $B^H x_1 + Sx_3 = 0$. The latter conditions hold if and only if $x_3 = 0$ and $B^H x_1 = 0$, because

539 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

S is definite. Thus, let $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_3 = 0$ and $B^H x_1 = 0$. Then we obtain from (4.17) and by using Lemma 4.9 that

$$(4.27) \quad \begin{aligned} (\eta^S(R, E, \lambda, x))^2 &= \inf \left\{ \|\Delta_R \ \Delta_E\|_F^2 \mid \Delta_R, \Delta_E \in \text{Herm}(n), \text{ satisfying (4.19) and (4.20)} \right\} \\ &= \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}, \end{aligned}$$

where the last equality is due to Lemma 4.9. Note that for any $\Delta \in \mathbb{C}^{n,n}$, the Hermitian and skew-Hermitian parts of Δ satisfy $\|\Delta\|_F^2 = \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2$. This implies

$$(4.28) \quad \|\Delta\|_F^2 \leq \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \quad \text{if } |\lambda| \leq 1$$

and

$$(4.29) \quad \frac{\|\Delta\|_F^2}{|\lambda|^2} \leq \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \quad \text{if } |\lambda| \geq 1$$

for all $\Delta \in \mathbb{C}^{n,n}$. Then taking the infimum over all Δ satisfying $\Delta x_2 = r$ and $\Delta^H x_1 = s$ in (4.28) and (4.29), and by using the minimal Frobenius norm mapping from Theorem 2.2 we obtain (4.25) and (4.26). \square

EXAMPLE 4.11. The reason why we only obtain bounds in Theorem 4.10 is the fact that the infimum in (4.27) need not be attained by the matrix $\hat{\Delta}$ from Theorem 4.10. As an example, consider the pencil $L(z)$ as in (1.3) with

$$J = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \quad R = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \quad E = B = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \quad \text{and } S = I_2,$$

and let $\lambda = \frac{1}{4}i$ and $x = [0 \ 0 \ 1 \ 1 \ 0 \ 0]^T$, i.e., $x_1 = x_3 = 0 \in \mathbb{C}^2$ and $x_2 = [1 \ 1]^T$. We then obtain $s = -(J + R + \lambda E)x_1 = 0$ as well as

$$r = (J - R - \lambda E)x_2 + Bx_3 = \begin{bmatrix} -1 \\ 0 \end{bmatrix} \quad \text{and} \quad \hat{\Delta} = \frac{rx_2^H}{\|x_2\|^2} = \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2} \\ 0 & 0 \end{bmatrix}$$

which by (4.25) gives the bounds

$$\frac{1}{2} = \|\hat{\Delta}\|_F \leq \eta^S(R, E, \lambda, x) \leq \sqrt{\left\| \begin{bmatrix} -\frac{1}{2} & -\frac{1}{4} \\ -\frac{1}{4} & 0 \end{bmatrix} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \begin{bmatrix} 0 & -\frac{1}{4} \\ \frac{1}{4} & 0 \end{bmatrix} \right\|_F^2} = \sqrt{2.375}.$$

On the other hand, for the Hermitian matrix

$$\Delta := \begin{bmatrix} -1 & 0 \\ 0 & 0 \end{bmatrix},$$

we have $\Delta x_2 = r$, and thus, we obtain from (4.27) that $\eta^S(R, E, \lambda, x) \leq \|\Delta\|_F = 1$.

It remains an open problem to determine the exact value for $\eta^S(R, E, \lambda, x)$ and for the same reason, also the computation of the eigenvalue backward error $\eta^S(R, E, \lambda)$ is a challenging problem.

4.3. Perturbations only in J and R . Next, we consider perturbations that only effect the blocks J and R in a pencil $L(z)$ as in (1.3). Let $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Then by the terminology outlined in Section 3, the block- and symmetry-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(J, R, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, \lambda, x)$ are defined by

$$(4.30) \quad \eta^{\mathcal{B}}(J, R, \lambda, x) = \inf \left\{ \|\Delta_J \Delta_R\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\}$$

and

$$(4.31) \quad \eta^{\mathcal{S}}(J, R, \lambda, x) = \inf \left\{ \|\Delta_J \Delta_R\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\},$$

respectively, where \mathcal{B} is the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with the block-structure

$$\Delta_M = \begin{bmatrix} 0 & \Delta_J - \Delta_R & 0 \\ (\Delta_J - \Delta_R)^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad \Delta_N = 0,$$

and $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$, while \mathcal{S} is the corresponding set of pencils $\Delta L(z) = \Delta_M + z\Delta_N$ as in (4.18) with $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R \in \text{Herm}(n)$. If the perturbations are restricted to be real, then the above backward errors are denoted by $\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, \lambda, x)$ and $\eta^{\mathcal{S}_{\mathbb{R}}}(J, R, \lambda, x)$, respectively. As usual, we first investigate conditions for the finiteness of $\eta^{\mathcal{B}}(J, R, \lambda, x)$.

REMARK 4.12. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in \mathbb{C}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then for any $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$ and corresponding $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$(4.32) \quad (\Delta_J - \Delta_R)x_2 = (J - R + \lambda E)x_2 + Bx_3,$$

$$(4.33) \quad (\Delta_J - \Delta_R)^H x_1 = (-J - R - \lambda E)x_1,$$

$$(4.34) \quad 0 = B^H x_1 + Sx_3.$$

Consequently, $\eta^{\mathcal{B}}(J, R, \lambda, x)$ is finite if and only if (4.32)–(4.34) are satisfied.

LEMMA 4.13. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and set $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = (-J - R - \lambda E)x_1$. Then the following statements are equivalent.

- 1) There exist $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$ satisfying (4.32) and (4.33).
- 2) There exists $\Delta \in \mathbb{C}^{n,n}$ such that $\Delta x_2 = r$ and $\Delta^H x_1 = s$.
- 3) There exist $\Delta_J \in \text{SHerm}(n), \Delta_R \in \text{Herm}(n)$ satisfying (4.32) and (4.33).
- 4) The identity $x_3^H B^H x_1 = 0$ is satisfied.

Moreover,

$$(4.35) \quad \begin{aligned} & \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 \mid \Delta_J, \Delta_R \in \mathbb{C}^{n,n} \text{ satisfy (4.32) and (4.33)} \right\} \\ &= \inf \left\{ \frac{\|\Delta\|_F^2}{2} \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}, \end{aligned}$$

and

$$(4.36) \quad \begin{aligned} & \inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 \mid \Delta_J \in \text{SHerm}(n), \Delta_R \in \text{Herm}(n) \text{ satisfying (4.32) and (4.33)} \right\} \\ &= \inf \left\{ \|\Delta\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta x_2 = r, \Delta^H x_1 = s \right\}. \end{aligned}$$

541 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

Proof. “1) \Rightarrow 2)”: Let $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$ be such that they satisfy (4.32) and (4.33). By setting $\Delta = \Delta_J - \Delta_R$ we get $\Delta x_2 = r$ and $\Delta^H x_1 = s$. Furthermore, we have

$$\|\Delta\|_F^2 \leq (\|\Delta_J\|_F + \|\Delta_R\|_F)^2 \leq 2(\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2),$$

where the last inequality is an elementary application of the Cauchy Schwartz inequality (in \mathbb{R}^2). But then the inequality “ \geq ” in (4.35) can be easily shown by following the arguments in the proof of “1) \Rightarrow 2)” in Lemma 4.2.

“2) \Rightarrow 1)”: Suppose that $\Delta \in \mathbb{C}^{n,n}$ is such that $\Delta x_2 = r$ and $\Delta^H x_1 = s$ and define $\Delta_J = \frac{1}{2}\Delta$ and $\Delta_R = -\frac{1}{2}\Delta$. Then Δ_J and Δ_R satisfy (4.32) and (4.33). Also, we obtain

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 = \frac{\|\Delta\|_F^2}{2},$$

and hence, “ \leq ” in (4.35) can be easily shown by following the arguments of the proof of “2) \Rightarrow 1)” in Lemma 4.2.

“2) \Rightarrow 3)”: Let $\Delta \in \mathbb{C}^{n,n}$ be such that $\Delta u = r$ and $\Delta^H w = s$. Then by setting $\Delta_J = \frac{\Delta - \Delta^H}{2}$ and $\Delta_R = -\frac{\Delta + \Delta^H}{2}$, we get $\Delta_J \in \text{SHerm}(n)$, $\Delta_R \in \text{Herm}(n)$ such that (4.32) and (4.33) hold. Furthermore, we have

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 = \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 + \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 = \|\Delta\|_F^2.$$

Thus, arguments similar to those in the proof of “2) \Rightarrow 1)” in Lemma 4.2 give “ \leq ” in (4.36).

“3) \Rightarrow 2)”: Let $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R \in \text{Herm}(n)$ be such that they satisfy (4.32) and (4.33). Define $\Delta = \Delta_J - \Delta_R$ then $\Delta x_2 = r$ and $\Delta^H x_1 = s$. Note that Δ_J and $-\Delta_R$ are, respectively, the unique skew-Hermitian and Hermitian parts of Δ , i.e., $\Delta_J = \frac{\Delta - \Delta^H}{2}$ and $\Delta_R = -\frac{\Delta + \Delta^H}{2}$. This implies

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 = \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 + \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 = \|\Delta\|_F^2.$$

Then again arguments similar to those in the proof of “1) \Rightarrow 2)” in Lemma 4.2 give “ \geq ” in (4.36).

“2) \Leftrightarrow 4)”: This follows immediately from Theorem 2.2. \square

The following theorem yields the values of $\eta^{\mathcal{B}}(J, R, \lambda, x)$, $\eta^{\mathcal{S}}(J, R, \lambda, x)$, and also of their real counterparts if $L(z)$ is real. It also gives the values of $\eta^{\mathcal{B}}(J, R, \lambda) := \inf_{x \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^{\mathcal{B}}(J, R, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, \lambda) := \inf_{x \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^{\mathcal{S}}(J, R, \lambda, x)$.

THEOREM 4.14. *Let $L(z)$ be a pencil defined by (1.3), $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, and set $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = -(J + R + \lambda E)x_1$. Then the following statements hold:*

- 1) $\eta^{\mathcal{B}}(J, R, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, \lambda, x)$ are finite if and only if $x_3 = 0$ and $B^H x_1 = 0$. If the latter conditions are satisfied, then

$$\eta^{\mathcal{B}}(J, R, \lambda, x) = \frac{\|\hat{\Delta}\|_F}{\sqrt{2}} \quad \text{and} \quad \eta^{\mathcal{S}}(J, R, \lambda, x) = \|\hat{\Delta}\|_F,$$

as well as

$$\eta^{\mathcal{B}}(J, R, \lambda) = \frac{\sigma_{\min}(J - R + \lambda E)}{\sqrt{2}} \quad \text{and} \quad \eta^{\mathcal{S}}(J, R, \lambda) = \sigma_{\min}(J - R + \lambda E),$$

where $\hat{\Delta}$ is given by

$$\hat{\Delta} = \begin{cases} \frac{rx_2^H}{\|x_2\|^2} & \text{if } x_1 = 0, \\ \frac{x_1 s^H}{\|x_1\|^2} & \text{if } x_2 = 0, \\ \frac{rx_2^H}{\|x_2\|^2} + \frac{x_1 s^H}{\|x_1\|^2} \left(I_n - \frac{x_2 x_2^H}{\|x_2\|^2} \right) & \text{otherwise.} \end{cases}$$

2) Suppose that $L(z)$ is real. If $\text{rank}([x_1 \bar{x}_1]) = \text{rank}([x_2 \bar{x}_2]) = 2$, then $\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, \lambda, x)$ and $\eta^{\mathcal{S}_{\mathbb{R}}}(J, R, \lambda, x)$ are finite if and only if $x_3 = 0$, $B^T x_1 = 0$ and $\lambda x_2^T E x_1 = 0$. If the latter conditions are satisfied, then

$$(4.37) \quad \eta^{\mathcal{B}_{\mathbb{R}}}(J, R, \lambda, x) = \frac{\|\tilde{\Delta}\|_F}{\sqrt{2}} \quad \text{and} \quad \eta^{\mathcal{S}_{\mathbb{R}}}(J, R, \lambda, x) = \|\tilde{\Delta}\|_F,$$

where $\tilde{\Delta} \in \mathbb{R}^{n,n}$ is given by

$$\tilde{\Delta} = [r \bar{r}][x_2 \bar{x}_2]^{\dagger} + ([s \bar{s}][x_1 \bar{x}_1]^{\dagger})^H - ([s \bar{s}][x_1 \bar{x}_1]^{\dagger})^H ([x_2 \bar{x}_2][x_2 \bar{x}_2]^{\dagger}).$$

Proof. The proof of 1) follows the same lines as that of Theorem 4.3 by using Lemma 4.13 and Theorem 2.2.

Concerning the proof of 2), recall that when $L(z)$ is real, then $\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, \lambda, x)$ is the eigenpair backward error obtained by allowing only real perturbations to the blocks J and R of $L(z)$. Now for any $\Delta_J, \Delta_R \in \mathbb{R}^{n,n}$ and corresponding real $\Delta L(z) = \Delta_M + z \Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$(4.38) \quad (\Delta_J - \Delta_R)x_2 = (J - R + \lambda E)x_2 + Bx_3,$$

$$(4.39) \quad (\Delta_J - \Delta_R)^T x_1 = (-J - R - \lambda E)x_1,$$

$$(4.40) \quad 0 = B^T x_1 + Sx_3.$$

Since Δ_J and Δ_R are real, (4.38) and (4.39) can be equivalently written as

$$(4.41) \quad (\Delta_J - \Delta_R)[x_2 \bar{x}_2] = [r \bar{r}] \quad \text{and} \quad (\Delta_J - \Delta_R)^T [x_1 \bar{x}_1] = [s \bar{s}].$$

Following the lines of the proof of Lemma 4.13, there exist real matrices Δ_J and Δ_R satisfying (4.41) if and only if there exists $\Delta \in \mathbb{R}^{n,n}$ such that $\Delta[x_2 \bar{x}_2] = [r \bar{r}]$ and $\Delta^T [x_1 \bar{x}_1] = [s \bar{s}]$. Applying Theorem 2.3, we find that this is the case if and only if

$$x_2^H s = r^H x_1 \quad \text{and} \quad x_2^T s = r^T x_1$$

which, using the definition of r and s , is in turn equivalent to the conditions

$$x_3^H B^H x_1 = 0 \quad \text{and} \quad 2\lambda x_2^T E x_1 = x_3^T B^T x_1.$$

The latter conditions together with $B^T x_1 + Sx_3 = 0$ give $x_3 = 0$, $B^T x_1 = 0$ and $\lambda x_2^T E x_1 = 0$, because S is assumed to be positive definite. Therefore, from (4.30), $\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, \lambda, x)$ is finite if and only if x satisfies

543 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

$x_3 = 0$, $B^T x_1 = 0$ and $\lambda x_2^T E x_1 = 0$. If this is the case, then we find that

$$\begin{aligned}\eta^{\mathcal{B}_R}(J, R, \lambda, x) &= \inf \left\{ \left\| [\Delta_J \ \Delta_R] \right\|_F \mid \Delta_J, \Delta_R \in \mathbb{R}^{n,n} \text{ satisfy (4.41)} \right\} \\ &= \inf \left\{ \frac{\|\Delta\|_F}{\sqrt{2}} \mid \Delta \in \mathbb{R}^{n,n}, \Delta[x_2 \ \bar{x}_2] = [r \ \bar{r}] \text{ and } \Delta^T[x_1 \ \bar{x}_1] = [s \ \bar{s}] \right\}.\end{aligned}$$

Thus (4.37) follows for $\eta^{\mathcal{B}_R}(J, R, \lambda, x)$ by using Theorem 2.3. Similarly, we can also establish (4.37) for $\eta^{\mathcal{S}_R}(J, R, \lambda, x)$. \square

4.4. Perturbation only to J and B , or R and B , or E and B . In this section, we obtain block-structure-preserving eigenpair or eigenvalue backward errors when only the blocks J and B in a pencil $L(z)$ as in (1.3) are perturbed. Unfortunately, it seems that this approach cannot be generalized to obtain the corresponding symmetry-structure-preserving backward errors.

Let $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$, then by the terminology outlined in Section 3, the block-structure-preserving eigenpair backward error $\eta^{\mathcal{B}}(J, B, \lambda, x)$ is defined by

$$(4.42) \quad \eta^{\mathcal{B}}(J, B, \lambda, x) = \inf \left\{ \left\| [\Delta_J \ \Delta_B] \right\|_F \mid \Delta_J \in \mathbb{C}^{n,n}, \Delta_B \in \mathbb{C}^{n,m}, \Delta_M + z\Delta_N \in \mathcal{B}, \right. \\ \left. ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0 \right\},$$

where \mathcal{B} is the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with

$$\Delta_M = \begin{bmatrix} 0 & \Delta_J & \Delta_B \\ \Delta_J^H & 0 & 0 \\ \Delta_B^H & 0 & 0 \end{bmatrix} \quad \text{and} \quad \Delta_N = 0.$$

If the perturbations are restricted to be real then the above error is denoted by $\eta^{\mathcal{B}_R}(J, B, \lambda, x)$.

REMARK 4.15. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in \mathbb{C}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then for any $\Delta_J \in \mathbb{C}^{n,n}$, $\Delta_B \in \mathbb{C}^{n,m}$, and corresponding $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$\begin{aligned}\Delta_J x_2 + \Delta_B x_3 &= (J - R + \lambda E)x_2 + Bx_3, \\ \Delta_J^H x_1 &= (-J - R - \lambda E)x_1, \\ \Delta_B^H x_1 &= B^H x_1 + Sx_3,\end{aligned}$$

which in turn is equivalent to

$$(4.43) \quad \begin{bmatrix} \Delta_J & \Delta_B \end{bmatrix} \underbrace{\begin{bmatrix} x_2 \\ x_3 \end{bmatrix}}_{=u} = \underbrace{(J - R + \lambda E)x_2 + Bx_3}_{=r},$$

$$(4.44) \quad \begin{bmatrix} \Delta_J & \Delta_B \end{bmatrix}^H \underbrace{x_1}_{=w} = \underbrace{\begin{bmatrix} -(J + R + \lambda E)x_1 \\ B^H x_1 + Sx_3 \end{bmatrix}}_{=s}.$$

In particular, $\eta^{\mathcal{B}}(J, B, \lambda, x)$ is finite if and only if (4.43)–(4.44) are satisfied.

LEMMA 4.16. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, and let u, w, r and s be defined as in (4.43) and (4.44). Then the following statements are equivalent.

- 1) There exist $\Delta_J \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$ satisfying (4.43) and (4.44).
- 2) There exists $\Delta \in \mathbb{C}^{n,n+m}$ such that $\Delta u = r$ and $\Delta^H w = s$.
- 3) x satisfies $x_3 = 0$.

Moreover, we have

$$\inf \left\{ \|\Delta_J\|_F^2 + \|\Delta_B\|_F^2 \mid \Delta_J \in \mathbb{C}^{n,n}, \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (4.43) and (4.44)} \right\} \\ = \inf \left\{ \|\Delta\|_F^2 \mid \Delta \in \mathbb{C}^{n,n+m}, \Delta u = r, \Delta^H w = s \right\}.$$

Proof. “1) \Rightarrow 2)” is obvious while “2) \Rightarrow 3)” is implied by Theorem 2.2 using the fact that S is definite. The last part then follows from the observation that any $\Delta \in \mathbb{C}^{n,n+m}$ can be written as $\Delta = [\Delta_1 \ \Delta_2]$, where $\Delta_1 \in \mathbb{C}^{n,n}$ and $\Delta_2 \in \mathbb{C}^{n,m}$ such that

$$\|\Delta\|_F = \|[\Delta_1 \ \Delta_2]\|_F = \sqrt{\|\Delta_1\|_F^2 + \|\Delta_2\|_F^2}. \quad \square$$

THEOREM 4.17. Let $L(z)$ be a pencil as in (1.3), let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and set $u = [x_2^T \ x_3^T]^T$, $w = x_1$,

$$r = (J - R + \lambda E)x_2 + Bx_3 \quad \text{and} \quad s = -((J + R + \lambda E)x_1)^T (B^H x_1 + Sx_3)^T.$$

Then the following statements hold.

- 1) $\eta^{\mathcal{B}}(J, B, \lambda, x)$ is finite if and only if $x_3 = 0$. In that case, we have

$$\eta^{\mathcal{B}}(J, B, \lambda, x) = \sqrt{\|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2},$$

and

$$\eta^{\mathcal{B}}(J, B, \lambda) = \min \left\{ \sigma_{\min} \left(\begin{bmatrix} J - R + \lambda E & B \end{bmatrix}^H \right), \sigma_{\min}(J - R + \lambda E) \right\},$$

where $\hat{\Delta}_1$ and $\hat{\Delta}_2$ are given by

$$[\hat{\Delta}_1 \ \hat{\Delta}_2] = \begin{cases} \frac{ru^H}{\|u\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} \left(I_{n+m} - \frac{uu^H}{\|u\|^2} \right) & \text{otherwise.} \end{cases}$$

- 2) Suppose that $L(z)$ is real. If $\text{rank}([x_1 \ \bar{x}_1]) = \text{rank}([x_2 \ \bar{x}_2]) = 2$ then $\eta^{\mathcal{B}_{\mathbb{R}}}(J, B, \lambda, x)$ is finite if and only if $x_3 = 0$ and $\lambda x_2^T E x_1 = 0$. If the latter conditions are satisfied, then

$$(4.45) \quad \eta^{\mathcal{B}_{\mathbb{R}}}(J, B, \lambda, x) = \sqrt{\|\tilde{\Delta}_1\|_F^2 + \|\tilde{\Delta}_2\|_F^2},$$

where $\tilde{\Delta}_1 \in \mathbb{R}^{n,n}$ and $\tilde{\Delta}_2 \in \mathbb{R}^{n,m}$ are given by

$$[\tilde{\Delta}_1 \ \tilde{\Delta}_2] = [r \ \bar{r}][u \ \bar{u}]^\dagger + ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H - ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H ([u \ \bar{u}][u \ \bar{u}]^\dagger).$$

545 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

Proof. The proof is analogous to the one of Theorem 4.3 by using Lemma 4.16 as well as Theorem 2.2 in the complex case and Theorem 2.3 in the real case. \square

REMARK 4.18. A result similar to Theorem 4.17 can be obtained for the complex and real block-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(R, B, \lambda, x)$ and $\eta^{\mathcal{B}_{\mathbb{R}}}(R, B, \lambda, x)$ of a pair $(\lambda, x) \in (i\mathbb{R}) \times (\mathbb{C}^{2n+m} \setminus \{0\})$ when only the blocks R and B in a pencil $L(z)$ as in (1.3) are subject to perturbation. In fact, one easily obtains

$$\eta^{\mathcal{B}}(R, B, \lambda, x) = \eta^{\mathcal{B}}(J, B, \lambda, x) \quad \text{and} \quad \eta^{\mathcal{B}_{\mathbb{R}}}(R, B, \lambda, x) = \eta^{\mathcal{B}_{\mathbb{R}}}(J, B, \lambda, x).$$

As a consequence, we also have

$$\eta^{\mathcal{B}}(R, B, \lambda) = \eta^{\mathcal{B}}(J, B, \lambda).$$

Finally, also the backward errors $\eta^{\mathcal{B}}(E, B, \lambda, x)$ and $\eta^{\mathcal{B}}(E, B, \lambda)$ with respect to perturbations only in the blocks E and B of $L(z)$ as in (1.3) can be obtained in a similar manner. Since the actual result differs slightly from the previous formulas, we present it as a theorem, but we omit the proof, since it is similar to the one of Theorem 4.3.

THEOREM 4.19. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, and set $u = [\lambda x_2^T \ x_3^T]^T$, $w = x_1$,

$$r = (J - R + \lambda E)x_2 + Bx_3 \quad \text{and} \quad s = \left[\frac{1}{\lambda} ((J + R + \lambda E)x_1)^T (B^H x_1 + Sx_3)^T \right]^T.$$

Then the following statements hold.

- 1) $\eta^{\mathcal{B}}(E, B, \lambda, x)$ is finite if and only if $x_3 = 0$. In that case, we have

$$\eta^{\mathcal{B}}(E, B, \lambda, x) = \sqrt{\|\widehat{\Delta}_1\|_F^2 + \|\widehat{\Delta}_2\|_F^2},$$

and

$$\eta^{\mathcal{B}}(E, B, \lambda) = \min \left\{ \sigma_{\min} \left(\begin{bmatrix} -\frac{(J-R+\lambda E)}{\lambda} & B \end{bmatrix}^H \right), \frac{\sigma_{\min}(J - R + \lambda E)}{|\lambda|} \right\},$$

where $\widehat{\Delta}_1 \in \mathbb{C}^{n,n}$ and $\widehat{\Delta}_2 \in \mathbb{C}^{n,m}$ are given by

$$[\widehat{\Delta}_1 \ \widehat{\Delta}_2] = \begin{cases} \frac{ru^H}{\|u\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} \left(I_{n+m} - \frac{uu^H}{\|u\|^2} \right) & \text{otherwise.} \end{cases}$$

- 2) Suppose that $L(z)$ is real. If $\text{rank}([x_1 \ \bar{x}_1]) = \text{rank}([x_2 \ \bar{x}_2]) = 2$ then $\eta^{\mathcal{B}_{\mathbb{R}}}(E, B, \lambda, x)$ is finite if and only if $x_3 = 0$ and $\lambda x_2^T E x_1 = 0$. If the latter conditions are satisfied, then

$$\eta^{\mathcal{B}_{\mathbb{R}}}(E, B, \lambda, x) = \sqrt{\|\widetilde{\Delta}_1\|_F^2 + \|\widetilde{\Delta}_2\|_F^2},$$

where $\widetilde{\Delta}_1 \in \mathbb{R}^{n,n}$ and $\widetilde{\Delta}_2 \in \mathbb{R}^{n,m}$ are given by

$$[\widetilde{\Delta}_1 \ \widetilde{\Delta}_2] = [r \ \bar{r}][u \ \bar{u}]^\dagger + ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H - ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H ([u \ \bar{u}][u \ \bar{u}]^\dagger).$$

5. Perturbation in any three of the matrices J , R , E and B . In this section, we define and compute block- and symmetry-structure-preserving eigenpair or eigenvalue backward errors for pencils $L(z)$ as in (1.3), while we consider perturbations in any three of the blocks J, R, E, B of $L(z)$.

5.1. Perturbations in the blocks J , R and B . We first concentrate on the case that perturbations are allowed to affect only the blocks J , R , and B of a pencil $L(z)$ as in (1.3). If $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$, then following the terminology of Section 3, the block- and symmetry-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(J, R, B, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, B, \lambda, x)$, respectively, are defined by

$$\eta^{\mathcal{B}}(J, R, B, \lambda, x) = \inf \left\{ \left\| \begin{bmatrix} \Delta_J & \Delta_R & \Delta_B \end{bmatrix} \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\},$$

$$\eta^{\mathcal{S}}(J, R, B, \lambda, x) = \inf \left\{ \left\| \begin{bmatrix} \Delta_J & \Delta_R & \Delta_B \end{bmatrix} \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\},$$

where \mathcal{B} denotes the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with

$$\Delta_M = \begin{bmatrix} 0 & \Delta_J - \Delta_R & \Delta_B \\ (\Delta_J - \Delta_R)^H & 0 & 0 \\ (\Delta_B)^H & 0 & 0 \end{bmatrix}, \quad \Delta_N = 0,$$

and $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$, $\Delta_B \in \mathbb{C}^{n,m}$, while \mathcal{S} denotes the corresponding set of pencils that satisfy in addition $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R \in \text{Herm}(n)$. If the perturbations are restricted to be real then the above backward errors are denoted by $\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, B, \lambda, x)$ and $\eta^{\mathcal{S}_{\mathbb{R}}}(J, R, B, \lambda, x)$, respectively.

REMARK 5.1. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in \mathbb{C}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then for any $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$, and corresponding $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$\begin{aligned} (\Delta_J - \Delta_R)x_2 + \Delta_B x_3 &= (J - R + \lambda E)x_2 + Bx_3, \\ (\Delta_J - \Delta_R)^H x_1 &= (-J - R - \lambda E)x_1, \\ (\Delta_B)^H x_1 &= B^H x_1 + Sx_3, \end{aligned}$$

if and only if

$$(5.1) \quad \begin{bmatrix} \Delta_J - \Delta_R & \Delta_B \end{bmatrix} \underbrace{\begin{bmatrix} x_2 \\ x_3 \end{bmatrix}}_{=u} = \underbrace{(J - R + \lambda E)x_2 + Bx_3}_{=r},$$

$$(5.2) \quad \begin{bmatrix} \Delta_J - \Delta_R & \Delta_B \end{bmatrix}^H \underbrace{x_1}_{=w} = \underbrace{\begin{bmatrix} -(J + R + \lambda E)x_1 \\ B^H x_1 + Sx_3 \end{bmatrix}}_{=s}.$$

LEMMA 5.2. Let $L(z)$ be a pencil defined by (1.3), $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and let u, w, r and s be as defined in (5.1) and (5.2). Then the following statements are equivalent.

- 1) There exist $\Delta_J, \Delta_R \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$ satisfying (5.1) and (5.2).
- 2) There exist $\Delta \in \mathbb{C}^{n,n+m}$ such that $\Delta u = r$ and $\Delta^H w = s$.
- 3) There exist $\Delta_J \in \text{SHerm}(n)$, $\Delta_R \in \text{Herm}(n)$ and $\Delta_B \in \mathbb{C}^{n,m}$ satisfying (5.1) and (5.2).
- 4) x satisfies $x_3 = 0$.

Moreover, we have

$$\begin{aligned} & \inf \left\{ \left\| \begin{bmatrix} \Delta_J & \Delta_R & \Delta_B \end{bmatrix} \right\|_F^2 \mid \Delta_J, \Delta_R \in \mathbb{C}^{n,n}, \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (5.1) and (5.2)} \right\} \\ &= \inf \left\{ \frac{\|\Delta_1\|_F^2}{2} + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}, \end{aligned}$$

and

$$\begin{aligned} & \inf \left\{ \left\| \begin{bmatrix} \Delta_J & \Delta_R & \Delta_B \end{bmatrix} \right\|_F^2 \mid \Delta_J \in \text{SHerm}(n), \Delta_R \in \text{Herm}(n), \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (5.1) and (5.2)} \right\} \\ &= \inf \left\{ \|\Delta_1\|_F^2 + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}. \end{aligned}$$

Proof. As seen in the proof of Lemma 4.16, any $\Delta \in \mathbb{C}^{n,n+m}$ can be written as $\Delta = [\Delta_1 \ \Delta_2]$ where $\Delta_1 \in \mathbb{C}^{n,n}$ and $\Delta_2 \in \mathbb{C}^{n,m}$ such that $\|\Delta\|_F = \left\| \begin{bmatrix} \Delta_1 & \Delta_2 \end{bmatrix} \right\|_F = \sqrt{\|\Delta_1\|_F^2 + \|\Delta_2\|_F^2}$. With this key observation the proof is obtained by following exactly the same arguments as in the proof of Lemma 4.13. \square

THEOREM 5.3. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and define $\hat{u} = [\sqrt{2}x_2^T \ x_3^T]^T$, $w = x_1$,

$$r = (J - R + \lambda E)x_2 + Bx_3 \quad \text{and} \quad \hat{s} = \left[-\frac{1}{\sqrt{2}}((J + R + \lambda E)x_1)^T \ (B^H x_1 + Sx_3)^T \right]^T.$$

Then the following statements hold:

- 1) $\eta^{\mathcal{B}}(J, R, B, \lambda, x)$ is finite if and only if $x_3 = 0$. In that case, we have

$$\eta^{\mathcal{B}}(J, R, B, \lambda, x) = \sqrt{\|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2},$$

and

$$\eta^{\mathcal{B}}(J, R, B, \lambda) = \min \left\{ \sigma_{\min} \left(\begin{bmatrix} \frac{(J-R+\lambda E)}{\sqrt{2}} & B \end{bmatrix}^H \right), \frac{\sigma_{\min}(J-R+\lambda E)}{\sqrt{2}} \right\},$$

where $\hat{\Delta}_1$ and $\hat{\Delta}_2$ are given by

$$[\hat{\Delta}_1 \ \hat{\Delta}_2] = \begin{cases} \frac{r\hat{u}^H}{\|\hat{u}\|^2} & \text{if } x_1 = 0, \\ \frac{w\hat{s}^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{r\hat{u}^H}{\|\hat{u}\|^2} + \frac{w\hat{s}^H}{\|w\|^2} \left(I_{n+m} - \frac{\hat{u}\hat{u}^H}{\|\hat{u}\|^2} \right) & \text{otherwise.} \end{cases}$$

- 2) If $L(z)$ is real, and $\text{rank}([x_1 \ \bar{x}_1]) = \text{rank}([x_2 \ \bar{x}_2]) = 2$, then $\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, B, \lambda, x)$ is finite if and only if $x_3 = 0$ and $\lambda x_2^T E x_1 = 0$. If the latter conditions are satisfied, then

$$\eta^{\mathcal{B}_{\mathbb{R}}}(J, R, B, \lambda, x) = \sqrt{\|\tilde{\Delta}_1\|_F^2 + \|\tilde{\Delta}_2\|_F^2},$$

where $\tilde{\Delta}_1 \in \mathbb{R}^{n,n}$ and $\tilde{\Delta}_2 \in \mathbb{R}^{n,m}$ are given by

$$[\tilde{\Delta}_1 \ \tilde{\Delta}_2] = [r \ \bar{r}][\hat{u} \ \bar{\hat{u}}]^\dagger + ([\hat{s} \ \bar{\hat{s}}][w \ \bar{w}]^\dagger)^H - ([\hat{s} \ \bar{\hat{s}}][w \ \bar{w}]^\dagger)^H ([\hat{u} \ \bar{\hat{u}}][\hat{u} \ \bar{\hat{u}}]^\dagger).$$

Proof. Observe that if $u = [x_2^T \ x_3^T]^T$ and $s = [-((J + R + \lambda E)x_1)^T \ (B^H x_1 + Sx_3)^T]^T$, then

$$\begin{aligned} & \inf \left\{ \frac{\|\Delta_1\|_F^2}{2} + \|\Delta_2\|_F^2 \mid \Delta_1, \Delta_2 \in \mathbb{C}^{n,n}, [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\} \\ &= \inf \left\{ \|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2 \mid \hat{\Delta}_1, \hat{\Delta}_2 \in \mathbb{C}^{n,n}, [\hat{\Delta}_1 \ \hat{\Delta}_2]\hat{u} = r, [\hat{\Delta}_1 \ \hat{\Delta}_2]^H w = \hat{s} \right\}. \end{aligned}$$

Therefore, the proof is analogous to that of Theorem 4.3 by using first Lemma 5.2 and then Theorem 2.2 for 1) and Theorem 2.3 for 2). \square

The following theorem presents the value of $\eta^S(J, R, B, \lambda, x)$ and its real counterpart if the original pencil is real. It also gives $\eta^S(J, R, B, \lambda) := \inf_{x \in \mathbb{C}^{2n+m} \setminus \{0\}} \eta^S(J, R, B, \lambda, x)$.

THEOREM 5.4. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and define $u = [x_2^T \ x_3^T]^T$, $w = x_1$,*

$$r = (J - R + \lambda E)x_2 + Bx_3 \quad \text{and} \quad s = [-((J + R + \lambda E)x_1)^T \ (B^H x_1 + Sx_3)^T]^T.$$

Then the following statements hold.

- 1) $\eta^S(J, R, B, \lambda, x)$ is finite if and only if $x_3 = 0$. In such a case the following holds.

$$\eta^S(J, R, B, \lambda, x) = \sqrt{\|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2},$$

and

$$\eta^S(J, R, B, \lambda) = \min \left\{ \sigma_{\min} \left(\begin{bmatrix} J - R + \lambda E & B \end{bmatrix}^H \right), \sigma_{\min}(J - R + \lambda E) \right\},$$

where $\hat{\Delta}_1 \in \mathbb{C}^{n,n}$ and $\hat{\Delta}_2 \in \mathbb{C}^{n,m}$ are given by

$$[\hat{\Delta}_1 \ \hat{\Delta}_2] = \begin{cases} \frac{ru^H}{\|u\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} \left(I_{n+m} - \frac{uu^H}{\|u\|^2} \right) & \text{otherwise.} \end{cases}$$

- 2) If $L(z)$ is real, and $\text{rank}([x_1 \ \bar{x}_1]) = \text{rank}([x_2 \ \bar{x}_2]) = 2$ then $\eta^{S\mathbb{R}}(J, R, B, \lambda, x)$ is finite if and only if $x_3 = 0$ and $\lambda x_2^T E x_1 = 0$. If the latter conditions are satisfied, then

$$\eta^{S\mathbb{R}}(J, R, B, \lambda, x) = \sqrt{\|\tilde{\Delta}_1\|_F^2 + \|\tilde{\Delta}_2\|_F^2},$$

where $\tilde{\Delta}_1 \in \mathbb{R}^{n,n}$ and $\tilde{\Delta}_2 \in \mathbb{R}^{n,m}$ are given by

$$[\tilde{\Delta}_1 \ \tilde{\Delta}_2] = [r \ \bar{r}][u \ \bar{u}]^\dagger + ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H - ([s \ \bar{s}][w \ \bar{w}]^\dagger)^H ([u \ \bar{u}][u \ \bar{u}]^\dagger).$$

Proof. The proof is similar to that of Theorem 4.3 by using first Lemma 5.2, and then Theorem 2.2 for 1) and Theorem 2.3 for 2). \square

5.2. Perturbations to R , E and B , or J , E and B . This section is devoted to the block- and symmetry-structure-preserving eigenpair and eigenvalue backward errors when only the blocks R , E and B of a pencil $L(z)$ as in (1.3) are subject to perturbations. Let $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$, then in view of Section 3, we have the definitions

$$\eta^{\mathcal{B}}(R, E, B, \lambda, x) = \inf \left\{ \left\| [\Delta_R \ \Delta_E \ \Delta_B] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\},$$

$$\eta^{\mathcal{S}}(R, E, B, \lambda, x) = \inf \left\{ \left\| [\Delta_R \ \Delta_E \ \Delta_B] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\},$$

respectively, where \mathcal{B} is the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with

$$\Delta_M = \begin{bmatrix} 0 & -\Delta_R & \Delta_B \\ -\Delta_R^H & 0 & 0 \\ \Delta_B^H & 0 & 0 \end{bmatrix} \quad \text{and} \quad \Delta_N = \begin{bmatrix} 0 & \Delta_E & 0 \\ -\Delta_E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

and $\Delta_R, \Delta_E \in \mathbb{C}^{n,n}$, $\Delta_B \in \mathbb{C}^{n,m}$, and \mathcal{S} is the corresponding set of all such pencils that in addition satisfy $\Delta_R, \Delta_E \in \text{Herm}(n)$.

REMARK 5.5. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ be such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$. Then for any $\Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$, and corresponding $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$\begin{aligned} (-\Delta_R + \lambda\Delta_E)x_2 + \Delta_Bx_3 &= (J - R + \lambda E)x_2 + Bx_3, \\ (-\Delta_R + \lambda\Delta_E)^Hx_1 &= (-J - R - \lambda E)x_1, \\ \Delta_B^Hx_1 &= B^Hx_1 + Sx_3, \end{aligned}$$

which, in turn, is equivalent to

$$(5.3) \quad \begin{bmatrix} -\Delta_R + \lambda\Delta_E & \Delta_B \end{bmatrix} \underbrace{\begin{bmatrix} x_2 \\ x_3 \end{bmatrix}}_{=u} = \underbrace{(J - R + \lambda E)x_2 + Bx_3}_{=r},$$

$$(5.4) \quad \begin{bmatrix} -\Delta_R + \lambda\Delta_E & \Delta_B \end{bmatrix}^H \underbrace{x_1}_{=w} = \underbrace{\begin{bmatrix} -(J + R + \lambda E)x_1 \\ B^Hx_1 + Sx_3 \end{bmatrix}}_{=s}.$$

LEMMA 5.6. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and let u, w, r and s be defined as in (5.3) and (5.4). Then the following statements are equivalent.

- 1) There exist $\Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$ satisfying (5.3) and (5.4).
- 2) There exists $\Delta \in \mathbb{C}^{n,n+m}$ such that $\Delta u = r$ and $\Delta^H w = s$.
- 3) There exist $\Delta_R, \Delta_E \in \text{Herm}(n)$ and $\Delta_B \in \mathbb{C}^{n,m}$ satisfying (5.3) and (5.4).
- 4) x satisfies $x_3 = 0$.

Moreover,

$$\begin{aligned} & \inf \left\{ \left\| [\Delta_R \ \Delta_E \ \Delta_B] \right\|_F^2 \mid \Delta_R, \Delta_E \in \mathbb{C}^{n,n}, \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (5.3) and (5.4)} \right\} \\ &= \inf \left\{ \frac{\|\Delta_1\|_F^2}{1 + |\lambda|^2} + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}, \end{aligned}$$

and

$$\begin{aligned} & \inf \left\{ \|\Delta_R \ \Delta_E \ \Delta_B\|_F^2 \mid \Delta_R, \Delta_E \in \text{Herm}(n), \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (5.3) and (5.4)} \right\} \\ &= \inf \left\{ \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, \right. \\ & \quad \left. [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}. \end{aligned}$$

Proof. Again, by using the fact that any $\Delta \in \mathbb{C}^{n,n+m}$ can be written as $\Delta = [\Delta_1 \ \Delta_2]$ where $\Delta_1 \in \mathbb{C}^{n,n}$ and $\Delta_2 \in \mathbb{C}^{n,m}$ such that $\|\Delta\|_F = \|[\Delta_1 \ \Delta_2]\|_F = \sqrt{\|\Delta_1\|_F^2 + \|\Delta_2\|_F^2}$, the proof is obtained by arguments similar to those in the proof Lemma 4.2 and Lemma 4.9. \square

THEOREM 5.7. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ so that $x_1, x_2 \in \mathbb{C}^n$, and $x_3 \in \mathbb{C}^m$, and define $w = x_1$, $u = [x_2^T \ x_3^T]^T$, $\hat{u} = [(1 + |\lambda|^2)^{1/2} x_2^T \ x_3^T]^T$, $r = (J - R + \lambda E)x_2 + Bx_3$, $s = [-(J + R + \lambda E)x_1]^T (B^H x_1 + Sx_3)^T$, and $\hat{s} = [-(1 + |\lambda|^2)^{-1/2} (J + R + \lambda E)x_1]^T (B^H x_1 + Sx_3)^T$. Then $\eta^B(R, E, B, \lambda, x)$ and $\eta^S(R, E, B, \lambda, x)$ are finite if and only if $x_3 = 0$. Furthermore, the following statements hold.*

1) If $x_3 = 0$, then

$$(5.5) \quad \eta^B(R, E, B, \lambda, x) = \sqrt{\|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2},$$

and

$$(5.6) \quad \eta^B(R, E, B, \lambda) = \min \left\{ \sigma_{\min} \left(\begin{bmatrix} \frac{J-R+\lambda E}{\sqrt{1+|\lambda|^2}} & B \end{bmatrix}^H \right), \frac{\sigma_{\min}(J - R + \lambda E)}{\sqrt{1+|\lambda|^2}} \right\},$$

where $\hat{\Delta}_1$ and $\hat{\Delta}_2$ are given by

$$[\hat{\Delta}_1 \ \hat{\Delta}_2] = \begin{cases} \frac{r\hat{u}^H}{\|\hat{u}\|^2} & \text{if } x_1 = 0, \\ \frac{w\hat{s}^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{r\hat{u}^H}{\|\hat{u}\|^2} + \frac{w\hat{s}^H}{\|w\|^2} \left(I_{n+m} - \frac{\hat{u}\hat{u}^H}{\|\hat{u}\|^2} \right) & \text{otherwise.} \end{cases}$$

2) If $x_3 = 0$, then

$$(5.7) \quad \sqrt{\|\tilde{\Delta}_1\|_F^2 + \|\tilde{\Delta}_2\|_F^2} \leq \eta^S(R, E, B, \lambda, x) \leq \sqrt{\left\| \frac{\tilde{\Delta}_1 + \tilde{\Delta}_1^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\tilde{\Delta}_1 - \tilde{\Delta}_1^H}{2} \right\|_F^2 + \|\tilde{\Delta}_2\|_F^2},$$

when $|\lambda| \leq 1$, and

$$(5.8) \quad \sqrt{\frac{\|\tilde{\Delta}_1\|_F^2}{|\lambda|^2} + \|\tilde{\Delta}_2\|_F^2} \leq \eta^S(R, E, B, \lambda, x) \leq \sqrt{\left\| \frac{\tilde{\Delta}_1 + \tilde{\Delta}_1^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\tilde{\Delta}_1 - \tilde{\Delta}_1^H}{2} \right\|_F^2 + \|\tilde{\Delta}_2\|_F^2},$$

when $|\lambda| \geq 1$, where $\tilde{\Delta}_1$ and $\tilde{\Delta}_2$ are given by

$$[\tilde{\Delta}_1 \ \tilde{\Delta}_2] = \begin{cases} \frac{ru^H}{\|u\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} \left(I_{n+m} - \frac{uu^H}{\|u\|^2} \right) & \text{otherwise.} \end{cases}$$

Proof. In view of (5.3) and (5.4), we have

$$\begin{aligned} (\eta^{\mathcal{B}}(R, E, B, \lambda, x))^2 &= \inf \left\{ \left\| [\Delta_R \ \Delta_E \ \Delta_B] \right\|_F^2 \mid \Delta_R, \Delta_E \in \mathbb{C}^{n,n}, \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (5.3) and (5.4)} \right\} \\ &= \inf \left\{ \frac{\|\Delta_1\|_F^2}{1+|\lambda|^2} + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}, \end{aligned}$$

where the last equality follows from Lemma 5.6. Observe that if we set $\hat{\Delta}_2 = \Delta_2$ and $\hat{\Delta}_1 = \frac{\Delta_1}{\sqrt{1+|\lambda|^2}}$, then we obtain

$$(\eta^{\mathcal{B}}(R, E, B, \lambda, x))^2 = \inf \left\{ \|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2 \mid \hat{\Delta}_1 \in \mathbb{C}^{n,n}, \hat{\Delta}_2 \in \mathbb{C}^{n,m}, [\hat{\Delta}_1 \ \hat{\Delta}_2]\hat{u} = r, [\hat{\Delta}_1 \ \hat{\Delta}_2]^H w = \hat{s} \right\}.$$

Thus (5.5) follows from Theorem 2.2, and arguments similar to those in the proof of Theorem 4.3 give (5.6).

Similarly, by using Lemma 5.6 in the definition of $\eta^{\mathcal{S}}(R, E, B, \lambda, x)$, we can write

$$\begin{aligned} (\eta^{\mathcal{S}}(R, E, B, \lambda, x))^2 &= \inf \left\{ \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2 \mid \Delta_1, \Delta_2 \in \mathbb{C}^{n,n}, \right. \\ &\quad \left. [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}. \end{aligned}$$

For any $\Delta_1 \in \mathbb{C}^{n,n}$ we have $\|\Delta_1\|_F^2 = \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2$. This implies

$$(5.9) \quad \|\Delta_1\|_F^2 + \|\Delta_2\|_F^2 \leq \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2 \quad \text{if } |\lambda| \leq 1$$

and

$$(5.10) \quad \frac{\|\Delta_1\|_F^2}{|\lambda|^2} + \|\Delta_2\|_F^2 \leq \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \frac{1}{|\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2 \quad \text{if } |\lambda| \geq 1$$

for all $\Delta_1 \in \mathbb{C}^{n,n}$ and $\Delta_2 \in \mathbb{C}^{n,m}$. Taking the infimum over all $\Delta_1 \in \mathbb{C}^{n,n}$, $\Delta_2 \in \mathbb{C}^{n,m}$ satisfying $[\Delta_1 \ \Delta_2]u = r$ and $[\Delta_1 \ \Delta_2]^H w = s$ in (5.9) and (5.10) followed by applying Theorem 2.2 yields (5.7) and (5.8). \square

REMARK 5.8. We mention that a result similar to Theorem 5.7 can also be obtained for the block-structure-preserving eigenpair and eigenvalue backward errors $\eta^{\mathcal{B}}(J, E, B, \lambda, x)$ and $\eta^{\mathcal{B}}(J, E, B, \lambda)$, respectively, when perturbations are restricted to affect only the blocks J , E and B of a pencil $L(z)$ as in (1.3). In fact, for $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m}$, using arguments analogous to those in this section, we obtain that

$$\eta^{\mathcal{B}}(J, E, B, \lambda, x) = \eta^{\mathcal{B}}(R, E, B, \lambda, x) \quad \text{and} \quad \eta^{\mathcal{B}}(J, E, B, \lambda) = \eta^{\mathcal{B}}(R, E, B, \lambda).$$

5.3. Perturbation to J , R and E . Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. In this section, we allow perturbations in the blocks J , R and E of $L(z)$. The block- and symmetry-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(J, R, E, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, E, \lambda, x)$ are defined by

$$\begin{aligned} \eta^{\mathcal{B}}(J, R, E, \lambda, x) &= \inf \left\{ \left\| [\Delta_J \ \Delta_R \ \Delta_E] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\}, \\ \eta^{\mathcal{S}}(J, R, E, \lambda, x) &= \inf \left\{ \left\| [\Delta_J \ \Delta_R \ \Delta_E] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\}, \end{aligned}$$

respectively, where \mathcal{B} is the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with

$$\Delta_M = \begin{bmatrix} 0 & \Delta_J - \Delta_R & 0 \\ (\Delta_J - \Delta_R)^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad \Delta_N = \begin{bmatrix} 0 & \Delta_E & 0 \\ -\Delta_E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

and \mathcal{S} is the corresponding set of pencils from \mathcal{B} that satisfy in addition $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R, \Delta_E \in \text{Herm}(n)$.

REMARK 5.9. If $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ are such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, then for any $\Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ and corresponding $\Delta L(z) \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$(5.11) \quad (\Delta_J - \Delta_R + \lambda\Delta_E) \underbrace{x_2}_{=u} = \underbrace{(J - R + \lambda E)x_2 + Bx_3}_{=r},$$

$$(5.12) \quad (\Delta_J - \Delta_R + \lambda\Delta_E)^H \underbrace{x_1}_{=w} = \underbrace{(-J - R - \lambda E)x_1}_{=s},$$

$$(5.13) \quad 0 = B^H x_1 + Sx_3.$$

LEMMA 5.10. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and let u, w, r and s be defined as in (5.11) and (5.12). Then the following statements are equivalent.

- 1) There exist $\Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ satisfying (5.11) and (5.12).
- 2) There exists $\Delta \in \mathbb{C}^{n,n}$ such that $\Delta u = r$ and $\Delta^H w = s$.
- 3) There exist $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R, \Delta_E \in \text{Herm}(n)$ satisfying (5.11) and (5.12).
- 4) x satisfies $x_3^H B^H x_1 = 0$.

Moreover, we have

$$(5.14) \quad \inf \left\{ \left\| \begin{bmatrix} \Delta_J & \Delta_R & \Delta_E \end{bmatrix} \right\|_F^2 \mid \Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n} \text{ satisfy (5.11) and (5.12)} \right\} \\ = \inf \left\{ \left\| \frac{\Delta}{2 + |\lambda|^2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta u = r, \Delta^H w = s \right\},$$

and

$$(5.15) \quad \inf \left\{ \left\| \begin{bmatrix} \Delta_J & \Delta_R & \Delta_E \end{bmatrix} \right\|_F^2 \mid \Delta_J \in \text{SHerm}(n), \Delta_E, \Delta_R \in \text{Herm}(n) \text{ satisfying (5.11) and (5.12)} \right\} \\ = \inf \left\{ \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \mid \Delta \in \mathbb{C}^{n,n}, \Delta u = r, \Delta^H w = s \right\}.$$

Proof. “1) \Rightarrow 2)”: Let $\Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ be such that they satisfy (5.11) and (5.12). By setting $\Delta = \Delta_J - \Delta_R + \lambda\Delta_E$ we get $\Delta u = r$ and $\Delta^H w = s$. Also, we obtain

$$(5.16) \quad \|\Delta\|_F^2 \leq (\|\Delta_J\|_F + \|\Delta_R\|_F + |\lambda|\|\Delta_E\|_F)^2 \leq (2 + |\lambda|^2)(\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2),$$

where the latter inequality follows from the Cauchy-Schwarz inequality (in \mathbb{R}^3). Then “ \geq ” in (5.14) can be shown similarly as “1) \Rightarrow 2)” in the proof of Lemma 4.2.

“2) \Rightarrow 1)”: Conversely, let $\Delta \in \mathbb{C}^{n,n}$ such that $\Delta u = r$ and $\Delta^H w = s$. Define

$$\Delta_J = \frac{\Delta}{2 + |\lambda|^2}, \quad \Delta_R = -\frac{\Delta}{2 + |\lambda|^2}, \quad \text{and} \quad \Delta_E = \frac{\bar{\lambda}\Delta}{2 + |\lambda|^2}.$$

553 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

Then Δ_J , Δ_R and Δ_E satisfy $\Delta_J - \Delta_R + \lambda\Delta_E = \Delta$ and hence (5.11) and (5.12). Furthermore, we have

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 = \frac{\|\Delta\|_F^2}{2 + |\lambda|^2}.$$

Thus, we get “ \leq ” in (5.14) by following arguments similar to those of “ $2) \Rightarrow 1)$ ” in the proof of Lemma 4.2.

“ $2) \Rightarrow 3)$ ”: To show this, let $\Delta \in \mathbb{C}^{n,n}$ be such that $\Delta u = r$ and $\Delta^H w = s$. Then by setting

$$\Delta_R = -\frac{\Delta + \Delta^H}{2}, \quad \Delta_J = \frac{\Delta - \Delta^H}{2(1 + |\lambda|^2)}, \quad \text{and} \quad \Delta_E = \frac{\bar{\lambda}(\Delta - \Delta^H)}{2(1 + |\lambda|^2)},$$

we have $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R, \Delta_E \in \text{Herm}(n)$ (using $\lambda \in i\mathbb{R}$), and furthermore we obtain

$$\Delta_J - \Delta_R + \lambda\Delta_E = \frac{\Delta - \Delta^H}{2(1 + |\lambda|^2)} + \frac{\Delta + \Delta^H}{2} + \frac{|\lambda|^2(\Delta - \Delta^H)}{2(1 + |\lambda|^2)} = \frac{\Delta + \Delta^H}{2} + \frac{\Delta - \Delta^H}{2} = \Delta.$$

Thus, Δ_J , Δ_R , and Δ_E satisfy (5.11) and (5.12), and also

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 = \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 + \frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2.$$

Now “ \leq ” in (5.15) can be shown by arguments similar to those of “ $2) \Rightarrow 1)$ ” in the proof of Lemma 4.9.

“ $3) \Rightarrow 2)$ ”: Suppose that $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R, \Delta_E \in \text{Herm}(n)$ satisfy (5.11) and (5.12). Define $\Delta = \Delta_J - \Delta_R + \lambda\Delta_E$, then $\Delta u = r$ and $\Delta^H w = s$. Note that $\Delta_J + \lambda\Delta_E$ is skew-Hermitian since $\lambda \in i\mathbb{R}$, and therefore, $\Delta_J + \lambda\Delta_E$ and $-\Delta_R$ are respectively the unique skew-Hermitian and Hermitian parts of Δ , i.e.,

$$\Delta_R = -\frac{\Delta + \Delta^H}{2} \quad \text{and} \quad \Delta_J + \lambda\Delta_E = \frac{\Delta - \Delta^H}{2}.$$

This implies

$$\left\| \frac{\Delta - \Delta^H}{2} \right\|_F = \|\Delta_J + \lambda\Delta_E\|_F \leq \|\Delta_J\|_F + |\lambda| \cdot \|\Delta_E\|_F$$

and

$$\frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 \leq \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2,$$

where the last inequality is obtained with the help of the Cauchy-Schwarz inequality (in \mathbb{R}^2). Furthermore, we have

$$(5.17) \quad \frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta - \Delta^H}{2} \right\|_F^2 + \left\| \frac{\Delta + \Delta^H}{2} \right\|_F^2 \leq \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 + \|\Delta_R\|_F^2.$$

Thus, arguments similar to those in “ $1) \Rightarrow 2)$ ” in the proof of Lemma 4.2 give “ \geq ” in (5.15).

“ $2) \Leftrightarrow 4)$ ”: This follows immediately from Theorem 2.2. □

THEOREM 5.11. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and define $r = (J - R + \lambda E)x_2 + Bx_3$ and $s = -(J + R + \lambda E)x_1$. Then $\eta^B(J, R, E, \lambda, x)$ and $\eta^S(J, R, E, \lambda, x)$ are finite if and only if $x_3 = 0$ and $B^H x_1 = 0$. If the latter conditions are satisfied, then*

$$(5.18) \quad \eta^{\mathcal{B}}(J, R, E, \lambda, x) = \frac{\|\hat{\Delta}\|_F}{\sqrt{2 + |\lambda|^2}}, \quad \eta^{\mathcal{B}}(J, R, E, \lambda) = \frac{\sigma_{\min}(J - R + \lambda E)}{\sqrt{2 + |\lambda|^2}}$$

and

$$(5.19) \quad \frac{\|\hat{\Delta}\|_F}{\sqrt{1 + |\lambda|^2}} \leq \eta^{\mathcal{S}}(J, R, E, \lambda, x) \leq \sqrt{\left\| \frac{\hat{\Delta} + \hat{\Delta}^H}{2} \right\|_F^2 + \frac{1}{1 + |\lambda|^2} \left\| \frac{\hat{\Delta} - \hat{\Delta}^H}{2} \right\|_F^2},$$

where $\hat{\Delta}$ is given by

$$\hat{\Delta} = \begin{cases} \frac{ru^H}{\|u\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} \left(I_n - \frac{uu^H}{\|u\|^2} \right) & \text{otherwise.} \end{cases}$$

Proof. In view of Lemma 5.10 and Theorem 2.2, the proofs of (5.18) and (5.19) are based on similar arguments as those in the proofs of Theorem 4.3 and Theorem 4.10, respectively. \square

6. Perturbations in J , R , E and B . Finally, in this section, we allow all four blocks J , R , E , and B of a pencil $L(z)$ as in (1.3) to be perturbed. Let $\lambda \in \mathbb{C}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$, then by the terminology of Section 3 the block- and symmetry-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(J, R, E, B, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, E, B, \lambda, x)$ are respectively defined by

$$\eta^{\mathcal{B}}(J, R, E, B, \lambda, x) = \inf \left\{ \left\| [\Delta_J \ \Delta_R \ \Delta_E \ \Delta_B] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{B} \right\},$$

$$\eta^{\mathcal{S}}(J, R, E, B, \lambda, x) = \inf \left\{ \left\| [\Delta_J \ \Delta_R \ \Delta_E \ \Delta_B] \right\|_F \mid ((M - \Delta_M) + \lambda(N - \Delta_N))x = 0, \Delta_M + z\Delta_N \in \mathcal{S} \right\},$$

where \mathcal{B} denotes the set of all pencils of the form $\Delta L(z) = \Delta_M + z\Delta_N$ with

$$\Delta_M = \begin{bmatrix} 0 & \Delta_J - \Delta_R & \Delta_B \\ (\Delta_J - \Delta_R)^H & 0 & 0 \\ \Delta_B^H & 0 & 0 \end{bmatrix} \quad \text{and} \quad \Delta_N = \begin{bmatrix} 0 & \Delta_E & 0 \\ -\Delta_E^H & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

and \mathcal{S} is the set of corresponding pencils where in addition we have that $\Delta_J \in \text{SHerm}(n)$ and $\Delta_R, \Delta_E \in \text{Herm}(n)$.

REMARK 6.1. If $\lambda \in i\mathbb{R}$ and $x = [x_1^T \ x_2^T \ x_3^T]^T$ are such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$, then for any $\Delta_B \in \mathbb{C}^{n,m}$, $\Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}$, and corresponding $\Delta L(z) = \Delta_M + z\Delta_N \in \mathcal{B}$, we have $(L(\lambda) - \Delta L(\lambda))x = 0$ if and only if

$$\begin{aligned} (\Delta_J - \Delta_R + \lambda\Delta_E)x_2 + \Delta_B x_3 &= (J - R + \lambda E)x_2 + Bx_3, \\ (\Delta_J - \Delta_R + \lambda\Delta_E)^H x_1 &= (-J - R - \lambda E)x_1, \\ \Delta_B^H x_1 &= B^H x_1 + Sx_3, \end{aligned}$$

555 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

which in turn is equivalent to

$$(6.1) \quad \begin{bmatrix} \Delta_J - \Delta_R + \lambda \Delta_E & \Delta_B \end{bmatrix} \underbrace{\begin{bmatrix} x_2 \\ x_3 \end{bmatrix}}_{=u} = \underbrace{(J - R + \lambda E)x_2 + Bx_3}_{=r},$$

$$(6.2) \quad \begin{bmatrix} \Delta_J - \Delta_R + \lambda \Delta_E & \Delta_B \end{bmatrix}^H \underbrace{x_1}_{=w} = \underbrace{\begin{bmatrix} -(J + R + \lambda E)x_1 \\ B^H x_1 + Sx_3 \end{bmatrix}}_{=s}.$$

LEMMA 6.2. Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ such that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and let u, w, r and s be defined as in (6.1) and (6.2). Then the following statements are equivalent.

- 1) There exist $\Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$ satisfying (6.1) and (6.2).
- 2) There exists $\Delta \in \mathbb{C}^{n,n+m}$ such that $\Delta u = r$ and $\Delta^H w = s$.
- 3) There exist $\Delta_B \in \mathbb{C}^{n,m}$, $\Delta_J \in \text{SHerm}(n)$, $\Delta_R, \Delta_E \in \text{Herm}(n)$ satisfying (6.1) and (6.2).
- 4) x satisfies $x_3 = 0$.

Moreover, we have

$$(6.3) \quad \inf \left\{ \|\Delta_J \ \Delta_R \ \Delta_E \ \Delta_B\|_F^2 \mid \Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}, \Delta_B \in \mathbb{C}^{n,m} \text{ satisfy (6.1) and (6.2)} \right\} \\ = \inf \left\{ \frac{\|\Delta_1\|_F^2}{2 + |\lambda|^2} + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\},$$

and

$$(6.4) \quad \inf \left\{ \|\Delta_J \ \Delta_R \ \Delta_E \ \Delta_B\|_F^2 \mid \Delta_J \in \text{SHerm}(n), \Delta_R, \Delta_E \in \text{Herm}(n), \Delta_B \in \mathbb{C}^{n,m} \right. \\ \left. \text{satisfy (6.1) and (6.2)} \right\} \\ = \inf \left\{ \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2 \mid \Delta_1 \in \mathbb{C}^{n,n}, \Delta_2 \in \mathbb{C}^{n,m}, \right. \\ \left. [\Delta_1 \ \Delta_2]u = r, [\Delta_1 \ \Delta_2]^H w = s \right\}.$$

Proof. “1) \Rightarrow 2)”: Let $\Delta_J, \Delta_R, \Delta_E \in \mathbb{C}^{n,n}$ and $\Delta_B \in \mathbb{C}^{n,m}$ be such that they satisfy (6.1) and (6.2). By setting $\Delta_1 = \Delta_J - \Delta_R + \lambda \Delta_E$, $\Delta_2 = \Delta_B$ and $\Delta = [\Delta_1 \ \Delta_2]$ we get $\Delta \in \mathbb{C}^{n,n+m}$ with $\Delta u = r$ and $\Delta^H w = s$. Also, observe that by (5.16) we have

$$(6.5) \quad \frac{\|\Delta_1\|_F^2}{2 + |\lambda|^2} \leq \|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2$$

which implies

$$\frac{\|\Delta_1\|_F^2}{2 + |\lambda|^2} + \|\Delta_2\|_F^2 \leq \|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 + \|\Delta_B\|_F^2.$$

Now “ \geq ” in (6.3) can be shown by arguments similar to those in the proof of “1) \Rightarrow 2)” in Lemma 4.2.

“2) \Rightarrow 1)”: Conversely, let $\Delta \in \mathbb{C}^{n,n+m}$ such that $\Delta u = r$ and $\Delta^H w = s$ and suppose that $\Delta = [\Delta_1 \ \Delta_2]$ where $\Delta_1 \in \mathbb{C}^{n,n}$ and $\Delta_2 \in \mathbb{C}^{n,m}$. Define

$$\Delta_J = \frac{\Delta_1}{2 + |\lambda|^2}, \quad \Delta_R = -\frac{\Delta_1}{2 + |\lambda|^2}, \quad \Delta_E = \frac{\bar{\lambda}\Delta_1}{2 + |\lambda|^2}, \quad \text{and} \quad \Delta_B = \Delta_2,$$

then $\Delta_J, \Delta_R, \Delta_E$ and Δ_B satisfy $[\Delta_J - \Delta_R + \lambda\Delta_E \ \Delta_B] = \Delta$ and hence (6.1) and (6.2). Furthermore, we have

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 + \|\Delta_B\|_F^2 = \frac{\|\Delta_1\|_F^2}{2 + |\lambda|^2} + \|\Delta_2\|_F^2.$$

Therefore, we get “ \leq ” in (6.3) by following arguments similar to those in the proof “2) \Rightarrow 1)” in Lemma 4.2.

“2) \Rightarrow 3)”: To this end, let $\Delta \in \mathbb{C}^{n,n+m}$ be such that $\Delta u = r$ and $\Delta^H w = s$, and suppose that $\Delta = [\Delta_1 \ \Delta_2]$ where $\Delta_1 \in \mathbb{C}^{n,n}$ and $\Delta_2 \in \mathbb{C}^{n,m}$. Setting

$$\Delta_R = -\frac{\Delta_1 + \Delta_1^H}{2}, \quad \Delta_J = \frac{\Delta_1 - \Delta_1^H}{2(1 + |\lambda|^2)}, \quad \Delta_E = \frac{\bar{\lambda}(\Delta_1 - \Delta_1^H)}{2(1 + |\lambda|^2)}, \quad \text{and} \quad \Delta_B = \Delta_2,$$

we have $\Delta_J \in \text{SHerm}(n)$ and, because of $\lambda \in i\mathbb{R}$, also $\Delta_R, \Delta_E \in \text{Herm}(n)$. Furthermore, we obtain

$$[\Delta_J - \Delta_R + \lambda\Delta_E \ \Delta_B] = [\Delta_1 \ \Delta_2] = \Delta.$$

Thus, $\Delta_J, \Delta_R, \Delta_E$, and Δ_B satisfy (6.1) and (6.2), and we also have

$$\|\Delta_J\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_E\|_F^2 + \|\Delta_B\|_F^2 = \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2.$$

Therefore, “ \leq ” in (6.4) can be shown by arguments similar to those in the proof of “2) \Rightarrow 1)” in Lemma 4.9.

“3) \Rightarrow 2)”: Let $\Delta_R, \Delta_E \in \text{Herm}(n)$, $\Delta_J \in \text{SHerm}(n)$ and $\Delta_B \in \mathbb{C}^{n,m}$ be such that they satisfy (6.1) and (6.2). Define $\Delta_1 = \Delta_J - \Delta_R + \lambda\Delta_E$, $\Delta_2 = \Delta_B$ and $\Delta = [\Delta_1 \ \Delta_2]$ then $\Delta \in \mathbb{C}^{n,n+m}$ with $\Delta u = r$ and $\Delta^H w = s$. Again, observe that by (5.17) we have that

$$(6.6) \quad \frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 \leq \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 + \|\Delta_R\|_F^2.$$

This implies

$$\frac{1}{1 + |\lambda|^2} \left\| \frac{\Delta_1 - \Delta_1^H}{2} \right\|_F^2 + \left\| \frac{\Delta_1 + \Delta_1^H}{2} \right\|_F^2 + \|\Delta_2\|_F^2 \leq \|\Delta_J\|_F^2 + \|\Delta_E\|_F^2 + \|\Delta_R\|_F^2 + \|\Delta_B\|_F^2,$$

and thus, “ \geq ” in (6.4) can be shown by arguments similar to those in the proof of “1) \Rightarrow 2)” in Lemma 4.9.

“2) \Leftrightarrow 4)”: This follows immediately from Theorem 2.2. \square

THEOREM 6.3. *Let $L(z)$ be a pencil as in (1.3), and let $\lambda \in i\mathbb{R}$ and $x \in \mathbb{C}^{2n+m} \setminus \{0\}$. Partition $x = [x_1^T \ x_2^T \ x_3^T]^T$ so that $x_1, x_2 \in \mathbb{C}^n$ and $x_3 \in \mathbb{C}^m$ and define $w = x_1$, $u = [x_2^T \ x_3^T]^T$, $\hat{u} = [(2 + |\lambda|^2)^{1/2} x_2^T \ x_3^T]^T$, $r = (J - R + \lambda E)x_2 + Bx_3$, $s = [-(J + R + \lambda E)x_1]^T (B^H x_1 + Sx_3)^T$, and $\hat{s} = [-(2 + |\lambda|^2)^{-1/2} (J + R + \lambda E)x_1]^T (B^H x_1 + Sx_3)^T$. Then $\eta^B(J, R, E, B, \lambda, x)$ and $\eta^S(J, R, E, B, \lambda, x)$ are finite if and only if $x_3 = 0$. Furthermore, the following statements hold.*

1) If $x_3 = 0$ then

$$\eta^B(J, R, E, B, \lambda, x) = \sqrt{\|\hat{\Delta}_1\|_F^2 + \|\hat{\Delta}_2\|_F^2}$$

and

$$\eta^B(J, R, E, B, \lambda) = \min \left\{ \sigma_{\min} \left(\begin{bmatrix} \frac{J-R+\lambda E}{\sqrt{2+|\lambda|^2}} & B \end{bmatrix}^H \right), \frac{\sigma_{\min}(J-R+\lambda E)}{\sqrt{2+|\lambda|^2}} \right\}$$

where $\hat{\Delta}_1$ and $\hat{\Delta}_2$ are given by

$$[\hat{\Delta}_1 \ \hat{\Delta}_2] = \begin{cases} \frac{r\hat{u}^H}{\|\hat{u}\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{r\hat{u}^H}{\|\hat{u}\|^2} + \frac{ws^H}{\|w\|^2} \left(I_{n+m} - \frac{\hat{u}\hat{u}^H}{\|\hat{u}\|^2} \right) & \text{otherwise.} \end{cases}$$

2) If $x_3 = 0$ then

$$\sqrt{\frac{\|\tilde{\Delta}_1\|_F^2}{1+|\lambda|^2} + \|\tilde{\Delta}_2\|_F^2} \leq \eta^S(J, R, E, B, \lambda, x) \leq \sqrt{\left\| \frac{\tilde{\Delta}_1 + \tilde{\Delta}_1^H}{2} \right\|_F^2 + \frac{1}{1+|\lambda|^2} \left\| \frac{\tilde{\Delta}_1 - \tilde{\Delta}_1^H}{2} \right\|_F^2 + \|\tilde{\Delta}_2\|_F^2},$$

where $\tilde{\Delta}_1$ and $\tilde{\Delta}_2$ are given by

$$[\tilde{\Delta}_1 \ \tilde{\Delta}_2] = \begin{cases} \frac{ru^H}{\|u\|^2} & \text{if } x_1 = 0, \\ \frac{ws^H}{\|w\|^2} & \text{if } x_2 = 0, \\ \frac{ru^H}{\|u\|^2} + \frac{ws^H}{\|w\|^2} \left(I_{n+m} - \frac{uu^H}{\|u\|^2} \right) & \text{otherwise.} \end{cases}$$

Proof. The proof is analogous to that of Theorem 5.7 by using Lemma 6.2 instead of Lemma 5.6. \square

7. Numerical experiments. In this section, we illustrate our results with the help of numerical experiments. In particular, we show that the backward eigenpair errors computed in the previous sections can sometimes be significantly larger than the backward errors that correspond to perturbations that ignore the block structure of the pencil.

In the following, we compare the backward errors $\eta(L, \lambda, x)$ and $\eta^{\text{even}}(L, \lambda, x)$ from (1.4) and (1.5) with the block structured and symmetry structured eigenpair backward errors obtained in the Sections 4–6. We consider random pencils $L(z)$ in the form (1.3) and random pairs $(\lambda, x) \in i\mathbb{R} \times (\mathbb{C}^{2n+m} \setminus \{0\})$. To make this a fair comparison it is necessary to multiply the block structured and symmetry structured eigenpair backward errors with a factor of $\sqrt{2}$, because each of the perturbed blocks J , R , E , or B occurs twice in the pencil $L(z)$. We used Matlab Version No. 7.8.0 (R2009a) to compute the eigenpair backward errors in all cases.

EXAMPLE 7.1. We take a random asymptotically stable system with $J, R, Q \in \mathbb{C}^{4,4}$, $B \in \mathbb{C}^{4,3}$, $S \in \mathbb{C}^{3,3}$ and $P = 0$ such that $J^H = -J$, $R^H = R$, $Q^H = Q > 0$ and $S^H = S > 0$. For a particular choice of these matrices, the corresponding pencil $L(z)$ in the form (1.3) turned out to have the eigenvalues $\pm 54.518 - 63.914i$, $\pm 46.8738 - 16.2214i$, $\pm 6.8221 - 3.2867i$, $\pm 4.7381 + 11.4052i$ and ∞ , where ∞ is a semisimple eigenvalue of multiplicity 3. Thus, the system is strictly passive. We fix a vector $x = [x_1^T \ x_2^T \ x_3^T]^T \in \mathbb{C}^{11} \setminus \{0\}$, where

$x_1, x_2 \in \mathbb{C}^4$, $0 = x_3 \in \mathbb{C}^3$ and randomly select vectors x_1 from the intersection of the kernels of B^H and R , and x_2 from the kernel of R . Thus, x satisfies $x_3 = 0$, $B^H x_1 = 0$, $Rx_1 = 0$ and $Rx_2 = 0$, and hence x fulfils the finiteness criteria for all block- and symmetry-structure-preserving eigenpair backward errors from Sections 4–7.

TABLE 7.1

Comparison of various block-structure-preserving eigenpair backward errors for the pencil $L(z)$ of Example 7.1.

λ	$\eta(L)$	$\eta^{\text{even}}(L)$	$\sqrt{2}\eta^{\mathcal{B}}(J, E)$ $= \sqrt{2}\eta^{\mathcal{B}}(R, E)$	$\sqrt{2}\eta^{\mathcal{B}}(E, B)$	$\sqrt{2}\eta^{\mathcal{B}}(J, B)$ $= \sqrt{2}\eta^{\mathcal{B}}(R, B)$	$\sqrt{2}\eta^{\mathcal{B}}(J, E, B)$ $= \sqrt{2}\eta^{\mathcal{B}}(R, E, B)$
.138i	3.687	4.752	6.501	47.560	6.563	6.501
-.510i	3.364	4.353	5.927	13.046	6.653	5.927
-.895i	2.849	3.698	5.021	7.529	6.739	5.021
1.048i	2.553	3.280	4.522	6.249	6.552	4.522
-1.321i	2.346	3.056	4.139	5.190	6.859	4.139
1.908i	1.734	2.230	3.095	3.494	6.668	3.095
2.508i	1.405	1.810	2.524	2.717	6.817	2.524

In Table 7.1, we compare $\eta(L, \lambda, x)$ and $\eta^{\text{even}}(L, \lambda, x)$ with various block-structure-preserving eigenpair backward errors of $L(z)$ for pairs (λ, x) , where x is chosen as above and random values for λ on the imaginary axis were chosen. For the sake of saving space, we omit λ and x from the notation of backward errors in Table 7.1 and also in the following Table 7.2.

TABLE 7.2

Comparison of various symmetry-structure-pres. eigenpair backward errors for the pencil $L(z)$ of Example 7.1.

λ	$\eta(L)$	$\eta^{\text{even}}(L)$	$\sqrt{2}\eta^{\mathcal{S}}(J, E)$	lower bound of $\sqrt{2}\eta^{\mathcal{S}}(R, E)$	upper bound of $\sqrt{2}\eta^{\mathcal{S}}(R, E)$	lower bound of $\sqrt{2}\eta^{\mathcal{S}}(J, R, E)$	upper bound of $\sqrt{2}\eta^{\mathcal{S}}(J, R, E)$
.138i	3.687	4.752	8.462	6.563	38.625	6.501	6.523
-.510i	3.364	4.353	7.647	6.653	11.330	5.927	6.178
-.895i	2.849	3.698	6.444	6.739	7.282	5.021	5.635
1.048i	2.553	3.280	5.954	6.249	6.362	4.522	5.357
-1.321i	2.346	3.056	5.283	5.190	5.767	4.139	5.152
1.908i	1.734	2.230	4.111	3.494	4.954	3.095	4.787
2.508i	1.405	1.810	3.369	2.717	4.760	2.524	4.694

In Table 7.2, we record various symmetry-structure-preserving eigenpair backward errors for the same choice of pairs (λ, x) as in Table 7.1. We sometimes observe large differences between various of these symmetry-structure-preserving eigenpair backward errors. The tightness of the lower and upper bounds for $\eta^{\mathcal{S}}(R, E, \lambda, x)$ and $\eta^{\mathcal{S}}(J, R, E, \lambda, x)$ depends on the values of λ , which is clear by Theorem 4.10 and Theorem 5.11. Also the corresponding block-structure-preserving eigenpair backward errors $\eta^{\mathcal{B}}(J, E, \lambda, x)$ and $\eta^{\mathcal{B}}(R, E, \lambda, x)$ are sometimes significantly smaller than their symmetry-structure-preserving counterparts, i.e., $\eta^{\mathcal{S}}(J, E, \lambda, x)$ and $\eta^{\mathcal{S}}(R, E, \lambda, x)$, respectively.

8. Conclusions. We have obtained eigenpair and eigenvalue backward errors of a pencil $L(z)$ of the form (1.3) with respect to perturbations that respect the given block structure of $L(z)$ and also those that in addition respect the symmetry structure of $L(z)$. We have shown that these backward errors may be significantly larger than those that ignore the special block structure of the pencil. The following table gives

559 Structured Eigenvalue/Eigenvector Backward Errors of Matrix Pencils Arising in Optimal Control

an overview of the existence of formulas (or bounds) for these backward errors, when only specific blocks in the pencil are perturbed. In the second and third column, a check mark “✓” means that an explicit formula for a block- or symmetry-structure-preserving eigenpair backward error is available for perturbations that are restricted to blocks from the first column. In some cases, the real eigenpair backward error is complementary. Furthermore, in all cases block-structure-preserving eigenvalue backward errors can also be obtained while symmetry-structure-preserving eigenvalue backward errors are obtained only for perturbations restricted to any two of the three blocks J , R and B .

perturbed blocks	block-str.-pres. backward error	symm.-str.-pres. backward error
J and E	✓ Theorem 4.3	✓ Theorem 4.6
R and E	✓ Theorem 4.7	bounds in Theorem 4.10
J and R	✓ Theorem 4.14 (also real)	✓ Theorem 4.14 (also real)
J and B	✓ Theorem 4.17 (also real)	–
R and B	✓ Remark 4.18 (also real)	–
E and B	✓ Theorem 4.19 (also real)	–
J, R and B	✓ Theorem 5.3 (also real)	✓ Theorem 5.4 (also real)
R, E and B	✓ Theorem 5.7	bounds in Theorem 5.7
J, E and B	✓ Remark 5.8	–
J, R and E	✓ Theorem 5.11	bounds in Theorem 5.11
J, R, E and B	✓ Theorem 6.3	bounds in Theorem 6.3

REFERENCES

- [1] B. Adhikari. *Backward Perturbation and Sensitivity Analysis of Structured Polynomial Eigenvalue Problem*. PhD Thesis, Department of Mathematics, IIT Guwahati, Assam, India, 2008.
- [2] B. Adhikari and R. Alam. Structured backward errors and pseudospectra of structured matrix pencils. *SIAM J. Matrix Anal. Appl.*, 31(2):331–359, 2009.
- [3] Sk.S. Ahmad and R. Alam. Pseudospectra, critical points and multiple eigenvalues of matrix polynomials. *Linear Algebra Appl.*, 430:1171–1195, 2009.
- [4] R. Alam, S. Bora, M. Karow, V. Mehrmann, and J. Moro. Perturbation theory for Hamiltonian matrices and the distance to bounded-realness. *SIAM J. Matrix Anal. Appl.*, 32:484–514, 2011.
- [5] C. Beattie, V. Mehrmann, H. Xu, and H. Zwart. Port-Hamiltonian descriptor systems. *Math. Control, Signals, Systems*, 30:Article 17, <https://doi.org/10.1007/s00498-018-0223-3>, 2018.
- [6] P. Benner, R. Byers, V. Mehrmann, and H. Xu. A robust numerical method for the γ -iteration in \mathcal{H}_∞ control. *Linear Algebra Appl.*, 425(2/3):548–570, 2007.
- [7] P. Benner, P. Losse, V. Mehrmann, and M. Voigt. Numerical linear algebra methods for linear differential-algebraic equations. In A. Ilchmann and T. Reis (editors), *Surveys in Differential-Algebraic Equations III*, Differ.-Algebr. Equ. Forum, Springer-Verlag, Cham, Switzerland, Chapter 3, 117–175, 2015.
- [8] S. Bora, M. Karow, C. Mehl, and P. Sharma. Structured eigenvalue backward errors of matrix pencils and polynomials with Hermitian and related structures. *SIAM J. Matrix Anal. Appl.*, 35(2):453–475, 2014.
- [9] S. Bora, M. Karow, C. Mehl, and P. Sharma. Structured eigenvalue backward errors of matrix pencils and polynomials with palindromic structures. *SIAM J. Matrix Anal. Appl.*, 36(2):393–416, 2015.
- [10] C. Desoer and E. Kuh. *Basic Circuit Theory*. McGraw-Hill, 1969.
- [11] G. Freiling, V. Mehrmann, and H. Xu. Existence, uniqueness and parametrization of Lagrangian invariant subspaces. *SIAM J. Matrix Anal. Appl.*, 23:1045–1069, 2002.
- [12] Y. Genin, Y. Hachez, Yu. Nesterov, R. Stefan, P. Van Dooren, and S. Xu. Positivity and linear matrix inequalities. *European Journal of Control*, 8(3):275 – 298, 2002.

- [13] N. Gillis, V. Mehrmann, and P. Sharma. Computing nearest stable matrix pairs. *Numer. Linear Algebra Appl.*, 25(5):e2153, <https://doi.org/10.1002/nla.2153>, 2018.
- [14] N. Gillis and P. Sharma. Finding the nearest positive-real system. *SIAM J. Numer. Anal.*, 56(2), 1022-1047, 2018.
- [15] G.H. Golub and C.F. Van Loan. *Matrix Computations*, third edition. Johns Hopkins University Press, Baltimore, 1996.
- [16] D.J. Higham and N.J. Higham. Structured backward error and condition of generalized eigenvalue problems. *SIAM J. Matrix Anal. Appl.*, 20(2):493-512, 1998.
- [17] W. Kahan, B.N. Parlett, and E. Jiang. Residual bounds on approximate eigensystems of nonnormal matrices. *SIAM J. Numer. Anal.*, 19:470-484, 1982.
- [18] M. Karow, D. Kressner, and F. Tisseur. Structured eigenvalue condition numbers. *SIAM J. Matrix Anal. Appl.*, 28(4):1052-1068, 2006.
- [19] P. Kunkel and V. Mehrmann. *Differential-Algebraic Equations — Analysis and Numerical Solution*. EMS Publishing House, Zürich, Switzerland, 2006.
- [20] P. Kunkel and V. Mehrmann. Optimal control for unstructured nonlinear differential-algebraic equations of arbitrary index. *Math. Control Signals Systems*, 20(3):227-269, 2008.
- [21] D.S. Mackey, N. Mackey, C. Mehl, and V. Mehrmann. Structured polynomial eigenvalue problems: Good vibrations from good linearizations. *SIAM J. Matrix Anal. Appl.*, 28(4):1029-1051, 2006.
- [22] C. Mehl, V. Mehrmann, and P. Sharma. Stability radii for real linear Hamiltonian systems with perturbed dissipation. *BIT*, 57(3):811-843, 2017.
- [23] V. Mehrmann. *The Autonomous Linear Quadratic Control Problem, Theory and Numerical Solution*. *Lecture Notes in Control and Inform. Sci.*, Vol. 163, Springer-Verlag, Heidelberg, 1991.
- [24] M. Overton and P. Van Dooren. On computing the complex passivity radius. In *Proceedings of CDC-ECC 2005*, 7960-7964, 2005.
- [25] F. Tisseur. A chart of backward errors for singly and doubly structured eigenvalue problems. *SIAM J. Matrix Anal. Appl.*, 24(3):877-897, 2003.
- [26] F. Tröltzsch. On the Lagrange-Newton-SQP method for the optimal control of semilinear parabolic equations. *SIAM J. Control Optim.*, 38(1):294-312, 1999.
- [27] A.J. Van der Schaft. Port-Hamiltonian differential-algebraic systems. In: A. Ilchmann and T. Reis (editors), *Surveys in Differential-Algebraic Equations I*, Springer, 173-226, 2013.